

A COMPUTER SIMULATION FOR THE
EVALUATION OF FLEET AIR DEFENSE EMPLOYING
MONOSTATIC AND BISTATIC SEARCH RADARS

Richard John Leonhardt

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THESIS

A COMPUTER SIMULATION FOR THE
EVALUATION OF FLEET AIR DEFENSE EMPLOYING
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by

Richard John Leonhardt

and

Charles Robert Schlegelmilch

March 1975

Thesis Advisor:

A. F. Andrus

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A Computer Simulation for the
Evaluation of Fleet Air Defense Employing
Monostatic and Bistatic Search Radars

by

Richard John Leonhardt
Lieutenant Commander, United States Navy
B.S., University of Notre Dame, 1965

and

Charles Robert Schlegelmilch
Lieutenant Commander, United States Navy
B.S., Marquette University, 1961

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I. INTRODUCTION

The purpose of this thesis is to develop a computer simulation model for use in analysing the Navy's Fleet Air Defense problem, and to demonstrate the usefulness of the model with a hypothetical air defense scenario. The model is unique in that it provides for employment of bistatic as well as monostatic search radars. A bistatic radar is simply a radar system in which the radar transmitter and the radar receiver are not collocated. This capability was provided to allow for the investigation of the possible advantages of the use of a bistatic radar receiver in view of the extensive capability for passive detection of active radars.

The model, acronym FADS, for Fleet Air Defense Simulation, is programmed in FORTRAN IV level G, and is designed to run on an IBM 360/65 computer meeting the core requirement of 350 kilobytes.

FADS is structured along the lines of FLOATS IIB, a model currently maintained at the Johns Hopkins University Applied Physics Laboratory [Ref. 6]. The significant differences from FLOATS IIB which have been incorporated in FADS are: bistatic search radar systems, provision for engagement of bombers by surface-to-air missiles (SAM), the addition of a surface-to-surface missile (SSM) capability for the defensive forces, a control logic which requires the defensive forces to hold fire until fired on, the inclusion of a dispersed defensive force disposition, and the

means for constructing up to six distinct target lists for the attacking units.

FADS is suitable for analysing both large scale problems and one-on-one situations in a clear or jamming environment. In general, the model provides for the description of up to 90 enemy raiders of 10 different classes, 40 defensive units of 10 different classes, 15 classes of radars, 10 classes of SAMs, 35 time delay distribution functions, and 18 logic switches are included which vary the defensive play of the simulation. During the computer debugging phase of the model construction, FADS was exercised in all of its various modes. Included among these were clear and jamming environment, single and multi threats, area and point defense, and monostatic and bistatic search radar systems.

The particular problem used to demonstrate the usefulness of the model is an investigation of the relative effectiveness of 100 nautical mile and 50 nautical mile non-fire control dedicated SAM systems deployed on picket type surface units with bistatic search radar capability. This type of SAM system employs active or passive homing throughout its entire flight. The measure of effectiveness for the respective SAM systems is the rate at which enemy air-to-surface and surface-to-surface missiles (ASM/SSM) arrive at their target area during the ASM/SSM impact phase. This is an indication of the level of the enemy attack surviving the picket defenses and will demonstrate the diminishing of the intensity of the air battle which will be

waged in the vicinity of the main force. The primary concern is to determine what effect the different missile ranges will have on breaking up this focus of an enemy ASM/SSM attack.

The analysis was conducted with hypothetical or illustrative values for all systems. Specific performance characteristics for the bistatic radar system and the missile system do not exist. Care was taken to ensure that the hypothetical values were within the range of existing systems and that the proposed systems' parameters were comparable to present system capabilities when appropriate.

Section II of the thesis contains a general description of the flow of events in FADS and a discussion of the principle assumptions in the model. The specific inputs and results of the demonstration problem together with an analysis of the results are contained in Section III. Sections IV and V provide a detailed listing of the inputs required and the outputs received from FADS. Conclusions are given in Section VI. The appendixes contain background information on bistatic radar systems, a verbal description of the simulation program, glossaries, and a FORTRAN IV computer program listing.

II. BACKGROUND AND DISCUSSION

A. GENERAL DESCRIPTION OF THE SIMULATION MODEL

FADS is a large scale store-event simulation of a Task Force size surface missile engagement with an enemy air attack. The model is capable of representing a threat consisting of a coordinated missile attack launched from aircraft, surface units or submarines. Although the model provides for defensive engagement of the enemy missiles and launch platforms with either SAM or SSM, there is no determination of defensive interceptor attrition of enemy systems during the engagement. If interceptors are to be employed, they must be played against the launch platforms prior to the start of the game and the enemy forces reduced to the appropriate level. The Air Battle Analyzer developed by the Applied Physics Laboratory of Johns Hopkins University is a suitable tool to determine these interceptor attritions [Ref. 11].

The simulation determines friendly force equipment availabilities at the start of each iteration. These availabilities are based on a comparison between user inputs of the probability that a given equipment is operational and the value of a uniform (0,1) random number which is drawn by the computer. The next step in the simulation's iterative process is to determine detections and firing events for the friendly forces against the enemy launch platforms. These

SAM/SSM fire events are stored in an events list in a time sequence. The enemy ASM/SSM launch sequence and targeting is computed next. Detections and resultant fire events against the enemy ASM/SSM's are then determined and entered in the appropriate sequence in the events list. Friendly SAM/SSM intercepts and target hits are evaluated followed by enemy ASM/SSM hits and ship kill determinations. The kill and damage events are time interactive so that offensive and defensive force capabilities are decremented as hits occur. The simulation then prints statistics for the iteration and starts the next iteration by re-entering the flow at the point where equipment availabilities are determined. The program stops upon completion of the specified number of iterations and cumulative statistics are provided.

B. ASSUMPTIONS

1. Bistatic Radar System

In the bistatic detection portion of the simulation, the principle assumptions made regarding bistatic radar systems are: a) the target's bistatic radar cross section is equal to its monostatic cross section; b) the target is not located along the transmitter-receiver base line; and c) the radar propagation losses are the same as those experienced in monostatic systems.

a. Radar Cross Section

The approximation for the bistatic radar cross section is made on the basis that, in the limit, the bistatic cross section is equal to the monostatic cross

section except for the case where the scattering angle is equal to 180° [Ref. 10, p. 590]. The scattering angle is the angle between the path from the transmitter to the target and the path from the target to the receiver. It is equal to 180° when the target is on the base line between the transmitter and the receiver. The fact that the monostatic and bistatic cross sections are the same in the limit does not imply that they are everywhere equal. It does imply that the range of the values will be equal and thus on the average allow usage of the monostatic cross section to provide representative values for detection ranges during the iterative process of the computer simulation.

b. Target Location

The assumption concerning the target not being on the base line between the transmitter and the receiver is necessary since range ambiguities result when the scattering angle is equal to 180° . This assumption is not unreasonable since the typical track may cross the base line, but will not originate on it and remain on the base line. A situation in which this could occur would be the case when a raider while on the base line launches a missile at a target which is either the transmitter or the receiver platform.

c. Propagation Losses

The assumption concerning the propagation losses is appropriate in that similar assumptions are routinely made in arriving at detection ranges for monostatic radars. A representative propagation loss for the nominal detection

range is used in conjunction with the signal to noise ratio required for a specified probability of detection to arrive at a minimum reflected power level which must be received in order for target detection to occur.

An additional assumption concerning the bistatic radar system in the simulation model is that the bistatic transmitter is always in an operative status. It is not destroyed by enemy missiles during the attack phase nor is it evaluated as being down or degraded during the equipment status evaluation which is conducted at the start of each iteration. Individual bistatic receivers have an assigned probability of being operational which should also reflect the reliability of their associated transmitter.

2. Jamming

Some major assumptions were made in simulating the jamming environment in order to keep the problem tractable and to remain within reasonable time limits for the computer program. The jamming assumptions will tend to drive the solution to conservative estimates for the defensive forces. The first assumption made is that the jammer and detecting radar have a single gain for their main beam. Thus targets not in the main beam are considered to be in a unique side-lobe which is a specified number of db below the main beam. To determine the level of the jamming power arriving at the detecting radar, it was necessary to approximate the position of the jammer relative to the detecting radar. This was done by determining the jammer's position at the time a

given target was at the midpoint of its track through the radar's detection envelope. In the case of monostatic radar this point was the target's closest point of approach. For bistatic radar the midpoint in the first detection envelope was utilized. The jamming power arriving at the detecting radar, given the geometry of this midpoint position, was then used to calculate the detection range for the target. Additionally, in the computation of bomber detections and "shoot" events, no provision is made for jammers which may have been shot down prior to the time of detection. This assumption is not required in the case of missile detections where detection events for missiles take into consideration reduction in jamming levels caused by previous destruction of jammers.

The model is limited to four frequency bands for frequency separation of individual radars in the jamming environment.

3. Target Tracks

The principle target track assumptions are concerned with minor anomalies from the real world situations. These assumptions do not detract excessively from the simulation results, but do ease computation and simplify programming. A fixed altitude for the raider and missiles, and the lack of course changes on the part of raiders are such simplifying assumptions. In the case where a raider or missile track does not change more than 0.1 nautical mile (nm) in either the x or y direction, the target is assumed to fly

parallel to the non-changing axis. If the target does not move more than 0.1 nm in both the x and y directions, the target is assumed to be stationary. Additionally, raiders who have completed their missile launches continue on their preset course rather than exiting the battle area. Although these targets will be engaged by the defensive forces if higher priority targets are not present, the resulting target hits can be readily "backed out" of the simulation results by the user if desired. On the other hand, this assumption does allow raiders that are providing standoff jamming protection for the missiles to continue to close the defensive forces and thereby increase the effectiveness of their jamming.

Other less general assumptions are covered as they occur in the details of the subroutine descriptions in Appendix B.

III. DEMONSTRATION PROBLEM

This section presents a demonstration of the use of FADS in analysing a hypothetical problem involving bistatic radar systems and surface-to-air missiles (SAM). The problem is to select the maximum range required for the SAM system to be employed by a small surface combatant (SSC). The proposed SAM system is to protect the major units of a naval task force involved in an engagement with enemy missile systems. The SSC will have a bistatic search radar and the SAMs will be active homing missiles requiring no fire control director. As such, the SSC will emit no radiation. The SAM characteristics and performance capabilities have been specified with the exception of the maximum range. Two range capabilities will be considered, a 100 nautical mile missile and a 50 nautical mile missile. The problem thus becomes that of determining the relative effectiveness of the SSC when equipped with the different range missiles. As discussed in the introduction, the measure of effectiveness used to evaluate the missiles is the number of enemy missiles penetrating to the force center per unit of time. That is, the number of missiles arriving at the force center per minute during the time period in which missiles are impacting at the force center.

A. THE SCENARIO

The BLUE force consists of one High Value Target (HVT) and eight small escorts. The BLUE force is maneuvering within range of enemy air forces. The HVT is located at force center and the pickets are equally spaced on a circle one hundred miles from the HVT. The picket force is silent except for one early warning aircraft which carries the transmitter for the bistatic radars. For purposes of this analysis, the aircraft is assumed to be at force center and at 20,000 feet.

The RED force has detected the radar transmissions of the aircraft and the HVT and have launched an attack of twenty-one aircraft accompanied by three jammers. The RED aircraft will attack simultaneously in three sections, separated by forty degrees of bearing. The RED air force has practiced this maneuver to the point that the maximum deviation from simultaneous launch will be fifteen minutes. Each aircraft will take a maximum of three minutes to launch its missiles. The three sections will approach their target from 320, 000, and 040 degrees true. The jammers will carry equipment to cover all radar bands used by the BLUE force. Each section will consist of one heavy and six light attack aircraft.

The RED air force will attempt to penetrate the BLUE defense and sink the HVT. The HVT is considered to be unarmed. In order to target a BLUE unit in this dispersed formation, a RED unit will have to have positive identification of the

unit as hostile. An ECM fix, or visual ID will be adequate. As the BLUE pickets are not radiating, no ECM fix may be obtained. As the pickets are assumed to be smaller than a destroyer escort, and the RED aircraft will fly at a minimum altitude of 33,000 feet, no positive visual identification will be allowed.

The radio and radar silence of the pickets leaves them without the ability to coordinate their defense. No BLUE intercept will be allowed if the intercept point is within two miles of another BLUE unit's assigned position. The BLUE units will use a shoot-look-shoot doctrine.

B. THE INPUTS

1. The Units

a. The BLUE Units

The BLUE units consist of the HVT, eight pickets, and one early warning aircraft. Positions are as indicated in the scenario.

(1) HVT. For the purpose of this analysis the HVT is assumed to be unarmed.

(2) Pickets. The pickets will employ a type 4, bistatic, band 4 radar with an antenna height of 50 feet. They will carry thirty missiles in canisters. The probability of a correct target identification will be .95.

(3) Early Warning Aircraft. The BLUE early warning aircraft will be unarmed. It will carry a type 4 radar and serve as the transmitter for the pickets' bistatic receiver.

b. The RED Units

The three classes of RED units are heavy attack, light attack and jammers.

(1) Heavy Attack. The RED heavy attack aircraft will carry a type 5 radar and have the following characteristics.

WEAPONS: 1 type I ASM
4 type II ASM
SPEED: 415 Knots
JAMMERS: none
RADAR CROSS SECTION: 40 square meters
ALTITUDE: 35,000 feet

(2) Light Attack. The RED light attack aircraft will carry a type 5 radar and have the following characteristics.

WEAPONS: 2 type II ASM
SPEED: 420 Knots
JAMMERS: none
RADAR CROSS SECTION: 13 square meters
ALTITUDE: 33,000 feet

(3) Jammers. The RED jammer will carry no radar. It will have the following characteristics.

WEAPONS: none
SPEED: 417 Knots
JAMMERS: bands 1-4
250 watts/MHZ/band
359° beam width
-20 db side-lobe ratio
jamming target, HVT

RADAR CROSS SECTION: 32 square meters

ALTITUDE: 40,000 feet

2. The Radars

The two radars which the simulation will use to play the simulation are the class 4 and class 5 radars. Class 4 radars are found on all pickets and class 5 on all raiders.

a. Class 4 Radar

TYPE: Bistatic

β : 120 nm/m ^{$\frac{1}{2}$}

α : 30 nm/m ^{$\frac{1}{2}$}

SIDE LOBE RATIO: -20 db

MAXIMUM INSTRUMENTED RANGE: 200 miles

RADAR FREQUENCY BAND: 4

BEAM WIDTH: 10 degrees

TRANSMITTER UNIT: aircraft overhead HVT

TRANSMITTER ANTENNA HEIGHT: 20,000 feet

b. Class 5 Radar

TYPE: Monostatic

β : 100 nm/m ^{$\frac{1}{2}$}

α : 50 nm/m ^{$\frac{1}{2}$}

SIDE LOBE RATIO: -20 db

MAXIMUM INSTRUMENTED RANGE: 200 miles

RADAR FREQUENCY BAND: 3

BEAM WIDTH: 3 degrees

3. The Reaction Time Distributions

The reaction time distributions for target processing by the picket are displayed below.

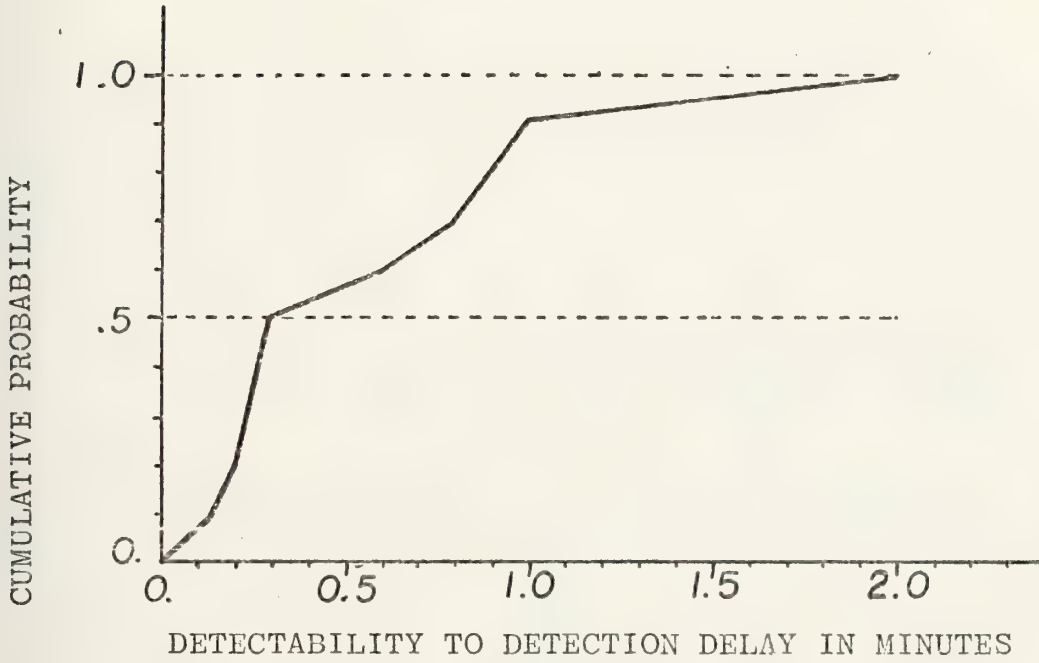


Figure 1

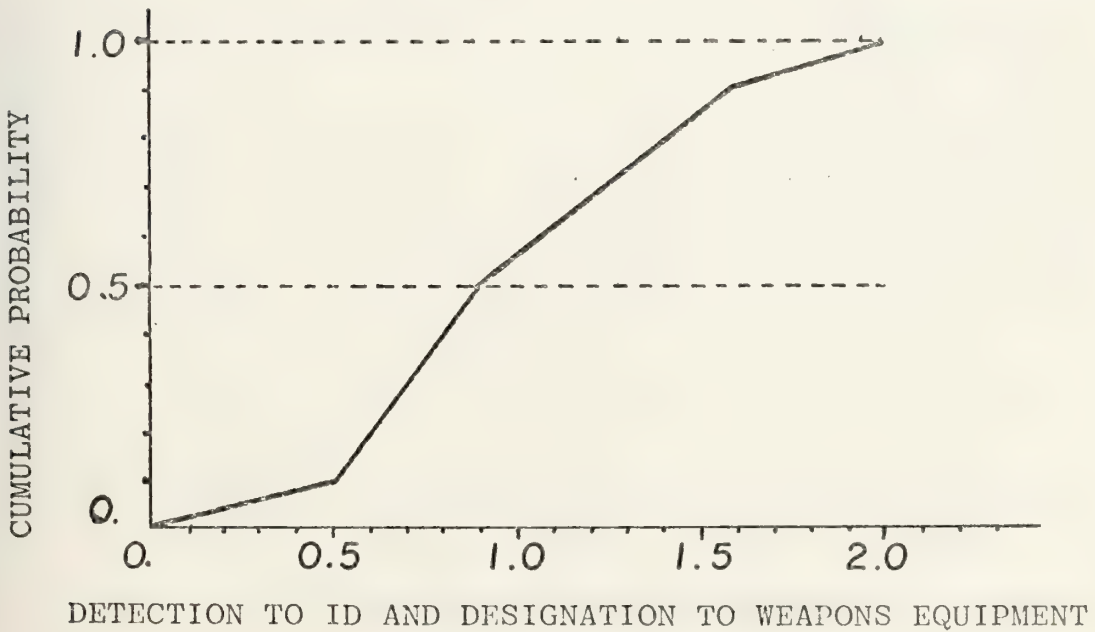
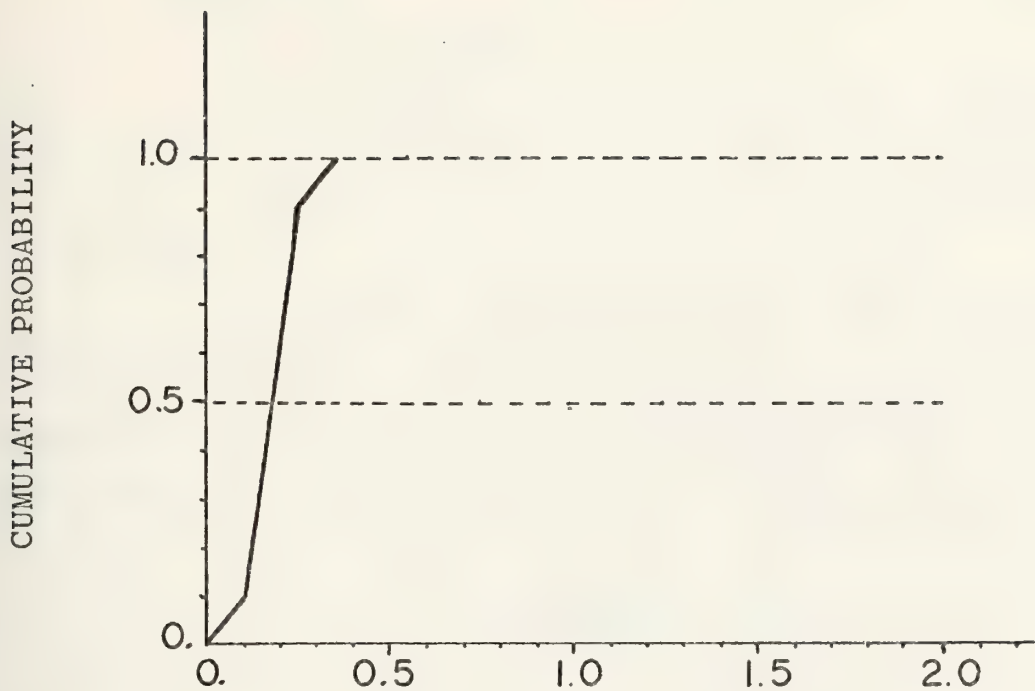
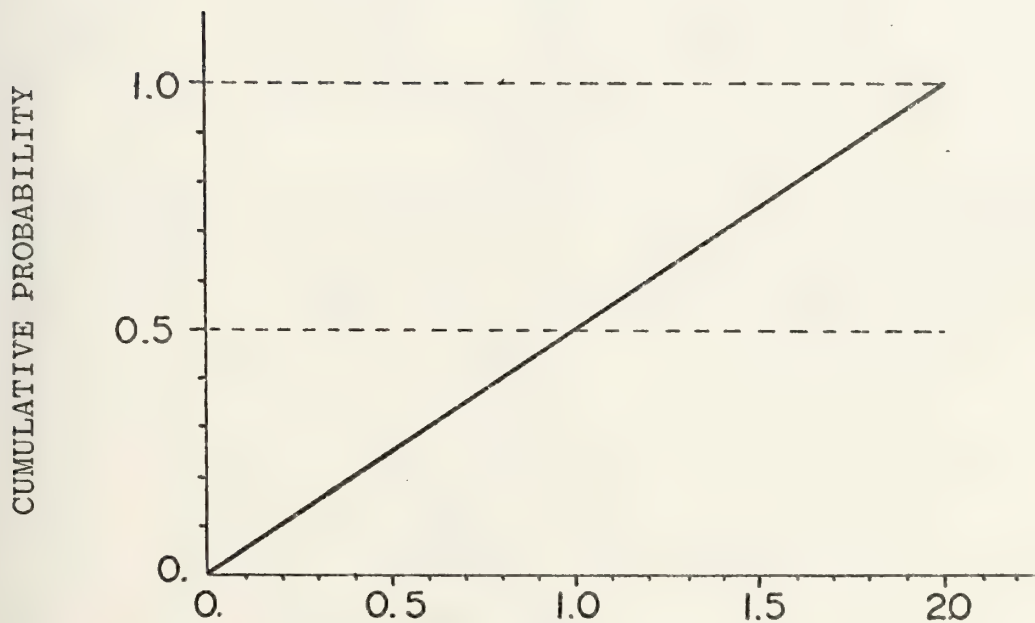


Figure 2



ASSIGNMENT TO FIRING CONSOLE IN MINUTES

Figure 3



FIRING DELAY IN MINUTES

Figure 4

4. The Weapons

a. The BLUE Weapons

There are two types of BLUE weapons. Both are SAMs and are denoted as SAM LR (long range) and SAM SR (short range).

(1) SAM LR. This will be the 100 mile version of the BLUE missile. It will have two sets of intercept parameters. The first is for a large, slow, high flying target. The second is for a small, fast, medium altitude target.

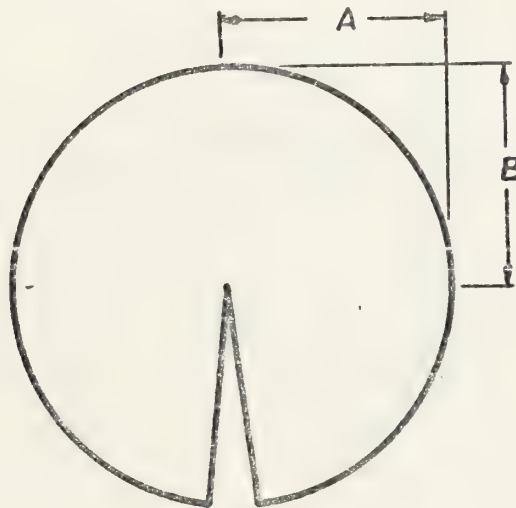


Figure 5

SAM Intercept Contour for High Altitude Engagement

The input value for the SAM LR class are:

$$A = 100$$

$$B = 100$$

$$N = 2.0$$

$$\text{SLOPE} = -20$$

$$\text{SEEK} = -5$$

$$\text{SPEED} = 1400 \text{ Knots}$$

PROBABILITY KILL FOR SINGLE SHOT (PKSS)
= .88

PKSS (CROSSING) = .79

SYSTEM RELIABILITY = .95

LAUNCH RELIABILITY = .99

MAXIMUM ALTITUDE = 59,000 feet

MINIMUM RANGE = 0.5 miles

The intercept parameters A, B, N, SLOPE, and SEEK are defined in the description of subroutine TIMMY in Appendix B.

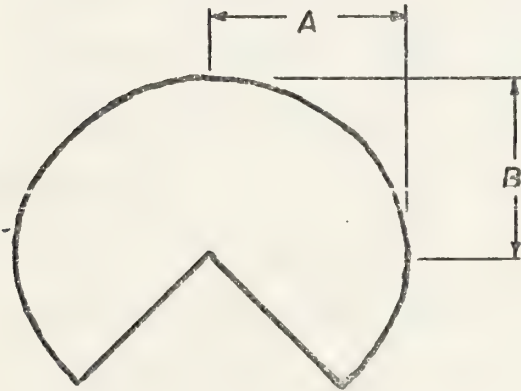


Figure 6

SAM Intercept Contour for the Medium Altitude Engagement

A = 100

B = 90

N = 2.8

SLOPE = -1

All other parameters are the same as high altitude engagement

(2) SAM SR. This will be the 50 mile version of the BLUE missile. The intercept contours will be the same as those for the SAM LR except the down range and cross range values are half the SAM LR values.

b. The RED Weapons

The RED aircraft carry two types of ASMs.

(1) ASM Type I.

SPEED: 750 Knots

ALTITUDE: 20,000 feet

LAUNCH RANGE: 120 miles

LAUNCH RELIABILITY: 0.85

INFLIGHT RELIABILITY: 0.80

RADAR CROSS SECTION: 1.79 square meters

(2) ASM Type II.

SPEED: 900 Knots

ALTITUDE: 15,000 feet

LAUNCH RANGE: 110 miles

LAUNCH RELIABILITY: 0.85

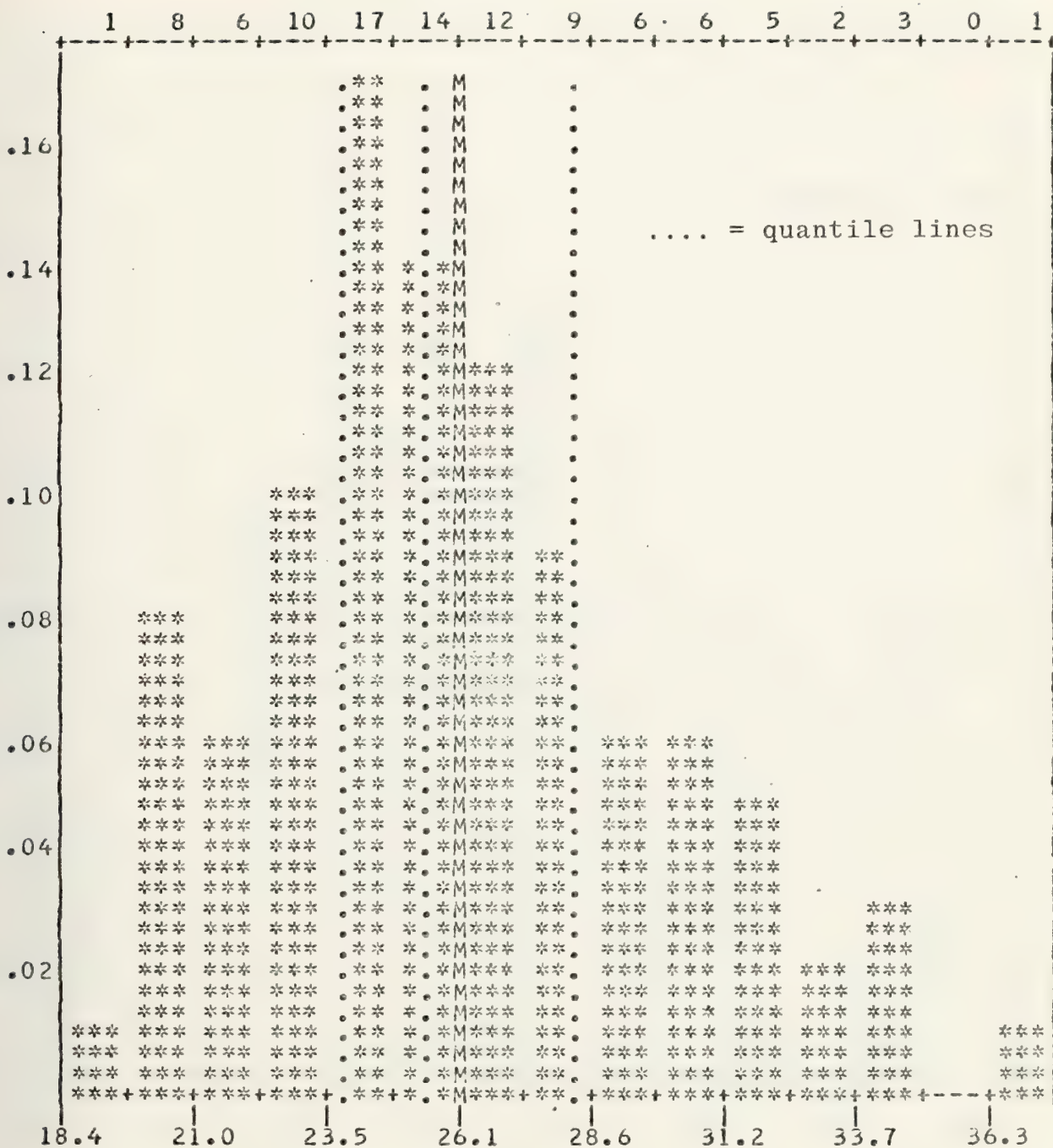
INFLIGHT RELIABILITY: 0.9

RADAR CROSS SECTION: 1.01 square meters

C. RESULTS

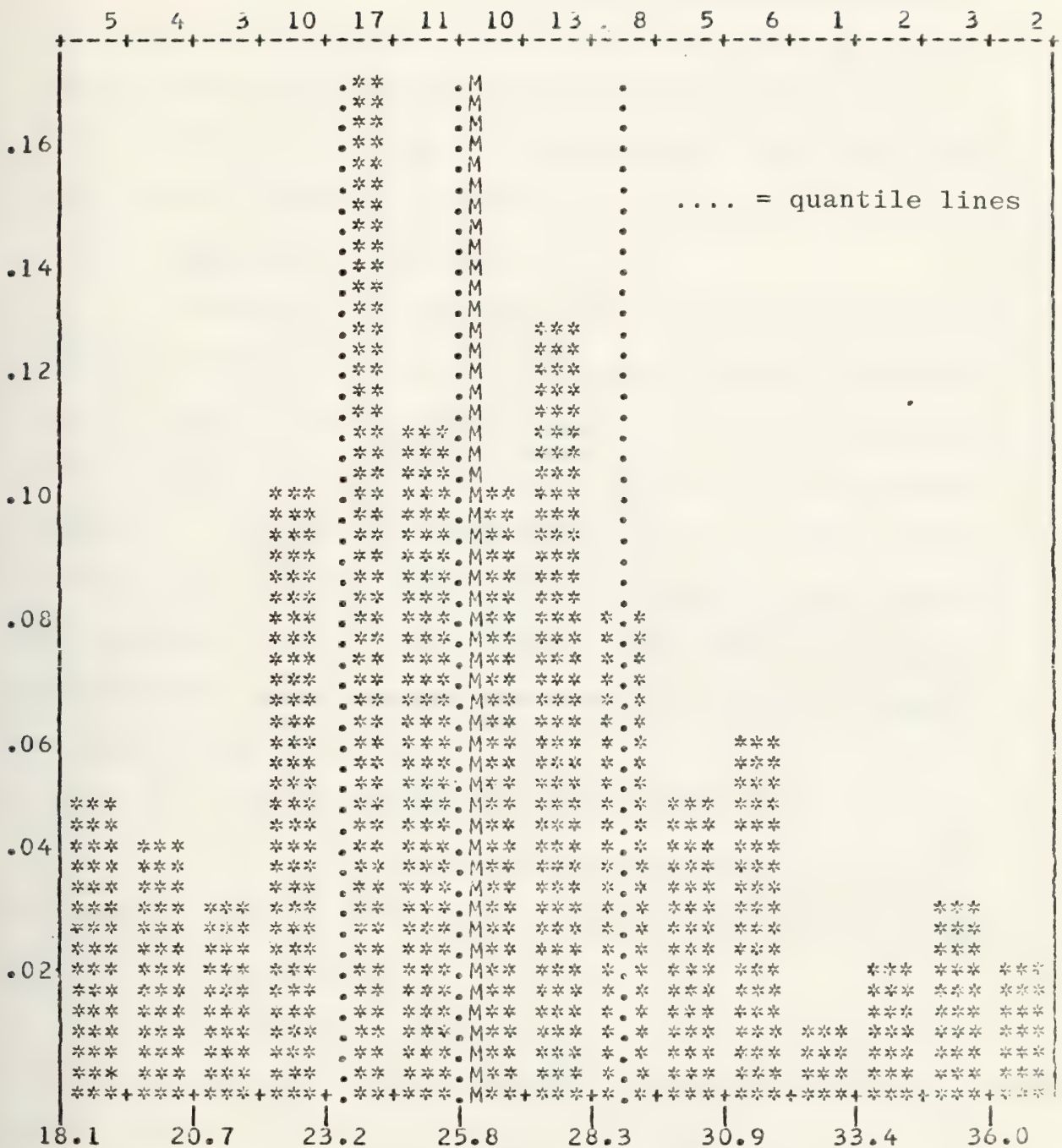
A summary of the results for 100 iterations is presented below.

1. ASM Results.	SAM SR	SAM LR
Available	5100	5100
Destroyed with launch platform	172 (3.4%)	246 (4.8%)
Launched	<u>4928 (96.6%)</u>	<u>4854 (95.2%)</u>
Failed at launch	724 (14.7%)	750 (15.4%)
Failed in flight	429 (8.7%)	418 (8.6%)
Destroyed by SAMs	0	0
Impact on HVT	3775 (76.6%)	3686 (75.9%)
2. SAM Results.		
Available	24000	24000
Launched	<u>3401</u>	<u>6440</u>
Kills	2116 (62.2%)	2398 (37.2%)
ASM	0	0
Raiders	2116	2398
Overkills	605 (17.8%)	2694 (41.8%)
Failures	680 (20.0%)	1348 (20.9%)
3. ASM Impact Intervals (minutes).		
Mean	1.468	1.432
Variance	0.033	0.037
Skewness	-0.060	0.070
Kurtosis	-0.620	-0.532
Minimum	1.091	0.966
Maximum	1.849	1.862
4. ASM Impacts per Minute.		
Mean	26.101	26.192
Variance	14.651	17.541
Skewness	-0.584	0.453
Kurtosis	-0.006	-0.136
Minimum	18.422	18.129
Maximum	37.567	37.246
5. Histograms of the ASM impacts per minute are shown in Figures 7 and 8.		



Histogram of the ASM Impacts per Minute, SAM SR

Figure 7



Histogram of the ASM Impacts per Minute, SAM LR

Figure 8

D. ANALYSIS

The analysis of the results consists of three parts. The first part contains a parametric evaluation of the ASM impacts per minute for the two SAM systems. The second part provides a nonparametric evaluation. Part three provides general comments concerning anomalies in the results.

1. Parametric Evaluation

The purpose of the parametric evaluation is to test whether the mean ASM impacts per minute against the SAM SR (u_{50}) is significantly greater than the mean ASM impacts per minute against the SAM LR (u_{100}). With its shorter range capability, the SAM SR system should attain a lower number of kills than the SAM LR system. Consequently the number of ASM impacts on the HVT that occur during the defense by the SAM SR system should be greater than the number of impacts during the SAM LR defense.

a. Null Hypothesis

$H_0: u_{50} \leq u_{100}$; SAM SR effectiveness is equal to or greater than the SAM LR system's as indicated by the mean ASM impacts per minute.

b. Alternative Hypothesis

$H_1: u_{50} > u_{100}$; SAM SR is less effective than SAM LR and therefore has a higher mean ASM impacts per minute.

c. Significance Level

A significance level of 0.05 was used in testing H_0 .

d. Statistical Test

The null hypothesis was tested against the alternative hypothesis using a t test. The t statistic for testing equal means is:

$$t = \frac{\bar{x}_{50} - \bar{x}_{100}}{\left[\frac{n_{50} + n_{100}}{n_{50} n_{100}} \right]^{\frac{1}{2}} \left[\frac{n_{50} S_{50}^2 + n_{100} S_{100}^2}{n_{50} + n_{100} - 2} \right]^{\frac{1}{2}}}$$

where:

$$\bar{x}_{50} = \text{sample mean for SAM SR. (26.10)}$$

$$\bar{x}_{100} = \text{sample mean for SAM LR. (26.19)}$$

$$s_{50}^2 = \text{sample variance for SAM SR. (14.651)}$$

$$s_{100}^2 = \text{sample variance for SAM LR. (17.541)}$$

$$n_{50} = n_{100} = \text{number of samples for SAM SR and SAM LR. (100)}$$

The null hypothesis will be rejected if the computed test statistic t is greater than or equal to the table value for the 0.95 point of t distribution with 198 degrees of freedom.

The table value is:

$$t_{.95, 198} = 1.96$$

e. Decision

The computed test statistic is $t = -0.1578$.

Since the computed t ratio is less than the tabulated value, the null hypothesis cannot be rejected at the 0.05 level.

f. Conclusion

The effectiveness of the SAM SR system was equal to or greater than the effectiveness of the SAM LR system at the 0.05 level of significance.

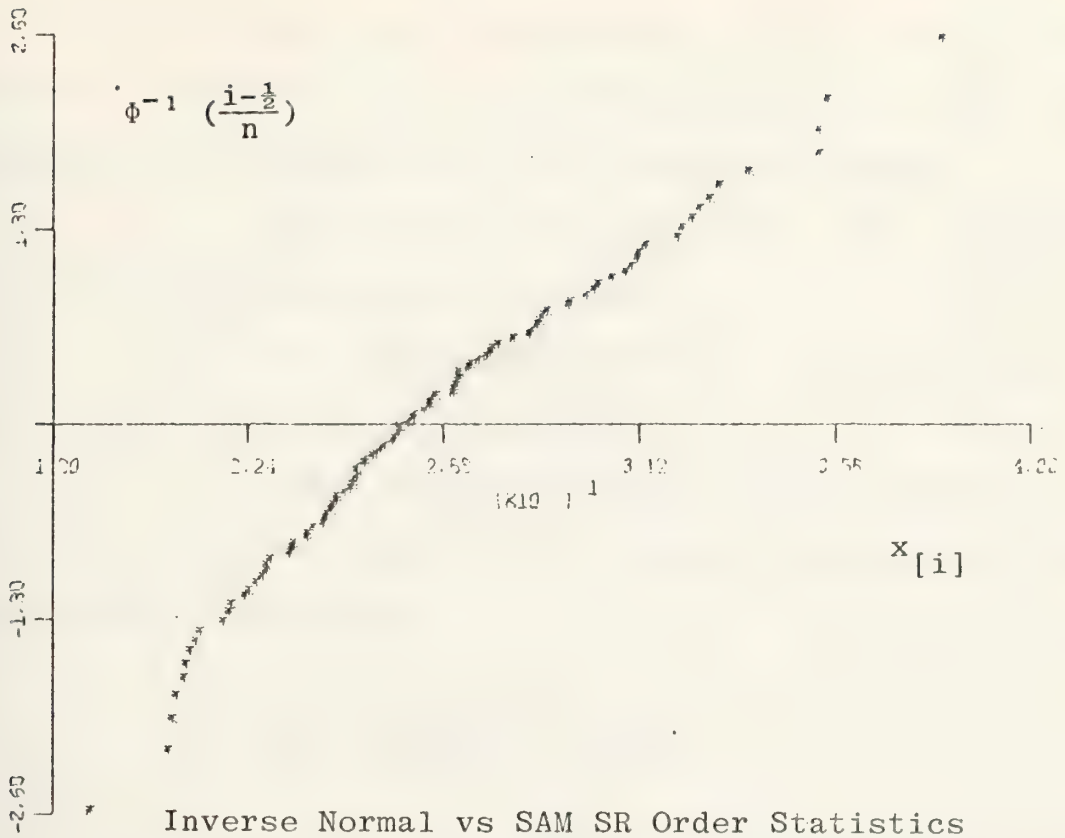
g. Justification for Use of the t Test

In order to use the t test for difference in means, three basic conditions had to be met. These were: i) the sample means were independent; ii) the underlying distributions from which the samples were drawn was normal; and iii) the underlying distributions had equal variances.

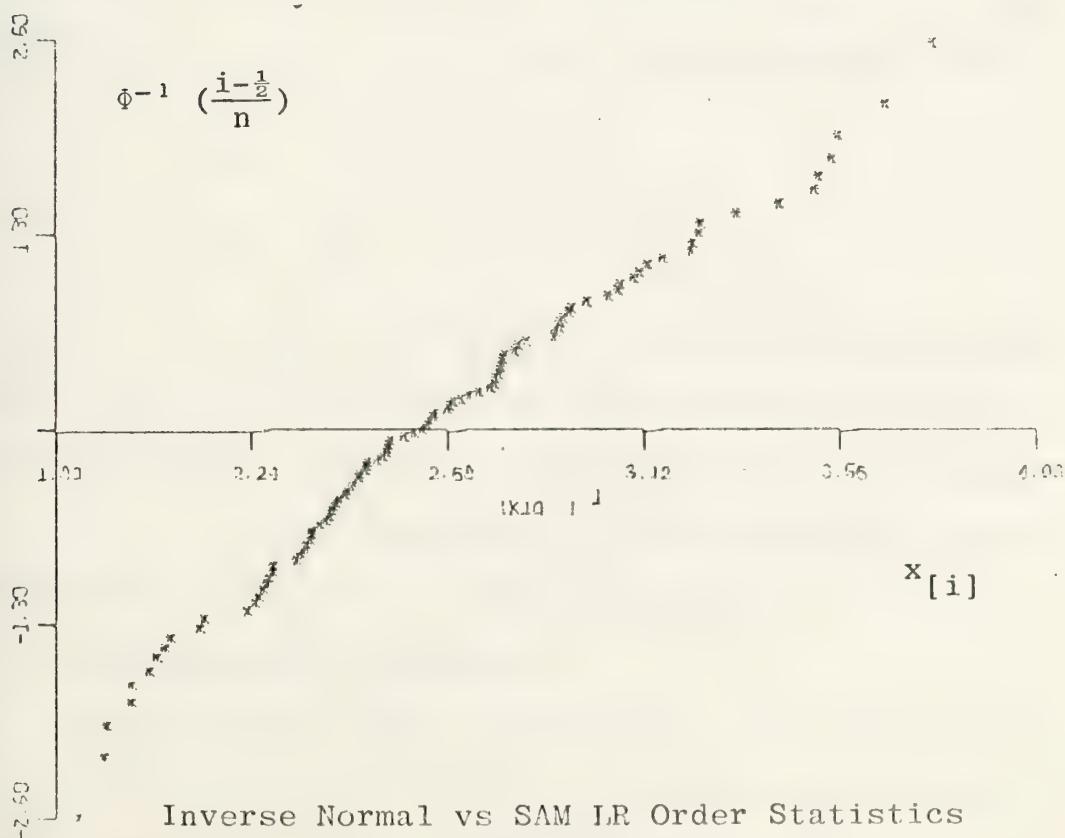
(1) Independence. The independence of the sample means was a reasonable assumption since the individual samples were obtained from different simulation runs using different random number streams.

(2) Normality. The normality of the sample mean values could be asserted on the basis of the sample size (100) and the central limit theorem or by demonstrating that the means were computed from samples which came from a normal distribution. The underlying normal distribution can be shown on the basis that both samples were unimodal and symmetric, and that the plots of their order statistics against the inverse normal probability scale was linear. The unimodality of the samples is seen in the histograms in figures 7 and 8. Symmetry is evident in both histograms and supported by the fact that the kurtosis of the sample values is close to zero. The order statistic plots, which are clearly linear, are shown in figures 9 and 10.

(3) Equal Variance. The relationship between the variance of the population from which the samples were drawn is tested using the F ratio. This test is applicable since the populations are normally distributed.



Inverse Normal vs SAM SR Order Statistics
Figure 9



Inverse Normal vs SAM LR Order Statistics
Figure 10

(a) Null Hypothesis. $H_0: \sigma_{50}^2 = \sigma_{100}^2$; the population variance (σ_{50}^2) of the SAM SR system is equal to the population variance (σ_{100}^2) of the SAM LR system.

(b) Alternative Hypothesis. $H_1: \sigma_{50}^2 \neq \sigma_{100}^2$; the population variances are not equal.

(c) Significance Level. A significance level of 0.05 was used in testing H_0 .

(d) Statistical Test. H_0 was tested against H_1 using the ratio of the unbiased estimators of the two population variances.

$$F = \frac{s_{100}^2}{s_{50}^2} = \frac{17.541}{14.651} = 1.1973$$

The null hypothesis will be rejected if the computed ratio F is greater than the tabulated value of $F_{(1-\alpha/2; 99, 99)}$ or less than $F_{(\alpha/2; 99, 99)}$. The tabulated values are:

$$F_{(.975, 99, 99)} = 1.451$$

$$F_{(.025, 99, 99)} = 0.684$$

(e) Decision. Since the computed ratio F is not greater than or less than the tabulated values for the F distribution, the null hypothesis cannot be rejected.

(f) Conclusion. The samples were drawn from populations which had equal variances.

2. Nonparametric Evaluation

The purpose of the nonparametric evaluation is to test whether the sample values for the SAM SR system and the SAM LR system are from the same population.

a. Null Hypothesis

H_0 : There is no difference in the number of ASM impacts per minute when defending with the SAM LR system or with the SAM SR system.

b. Alternative Hypothesis

H_1 : There is a difference.

c. Significance Level

A significance level of 0.05 was used in testing H_0 .

d. Statistical Test

The Kolmogorov-Smirnov (K-S) two-sample test was used to test the null hypothesis. The K-S test requires the use of independent samples. Independence was shown in D.1.g.(1) above. The K-S test is conducted using the statistic

$$K = \max |F_n(X) - G_m(Y)|$$

where $F_n(X)$ is the empirical cumulative distribution function for the first set of sample values and $G_m(Y)$ is the empirical cumulative distribution function for the second.

The null hypothesis will be rejected if there is a large enough deviation between the two sample cumulative distributions. The critical values of D for the level of significance of 0.05 and 100 observations in each sample is 0.19233.

e. Decision

The computed value of K was determined to be 0.0800. Since the computed value of K is less than the tabulated critical value, the null hypothesis cannot be rejected at the 0.05 level. A plot of the empirical cumulative distribution functions for the two sets of sample values is provided in figure 11. This plot clearly shows the close relationship between the two underlying populations.

f. Conclusion

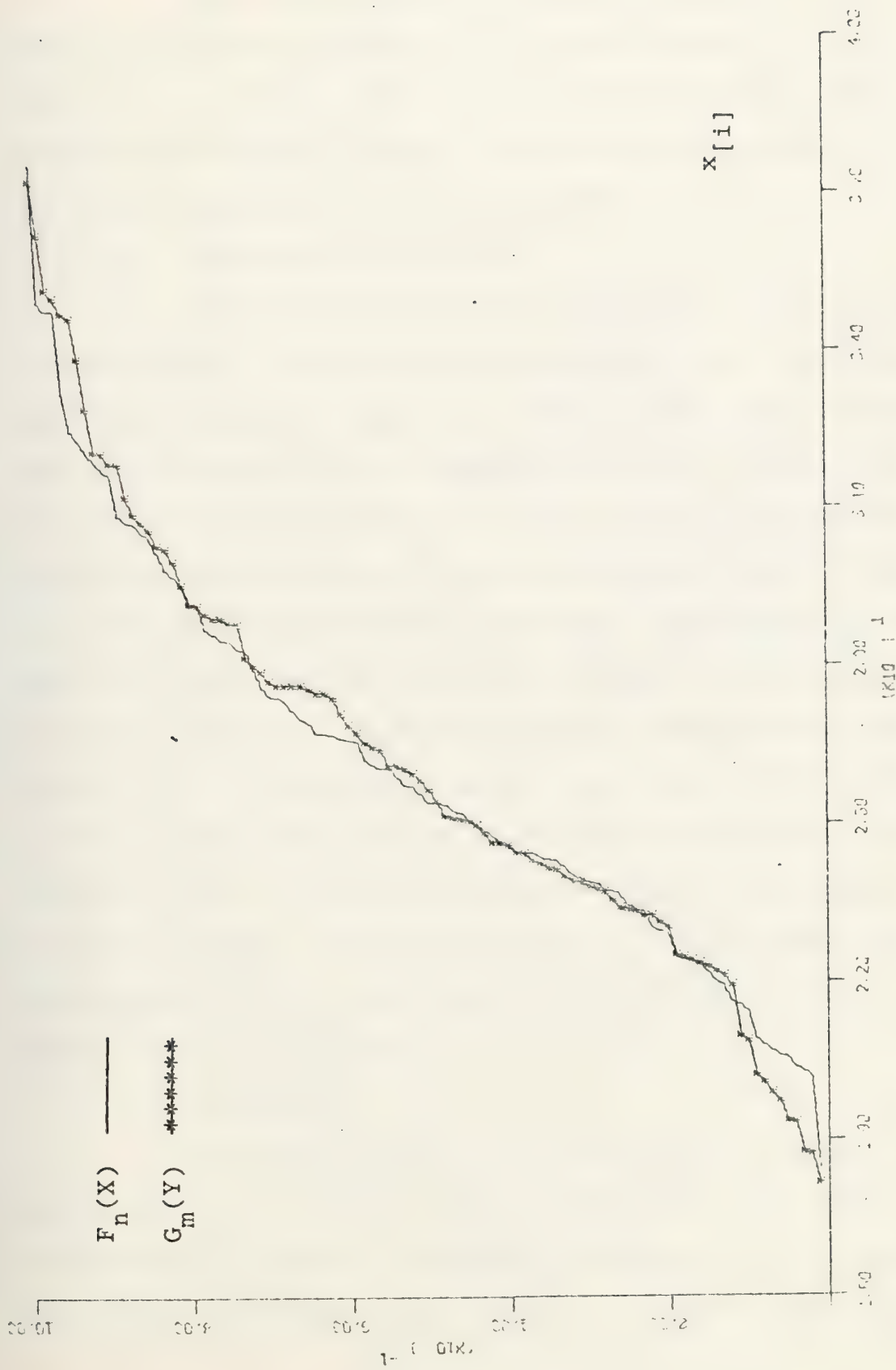
There was no difference in the defensive capabilities of systems in the environment in which they were examined.

3. General Comments

The principal anomalies present in the data include the following:

- a) a lack of difference in the SAM LR and SAM SR effectiveness;
- b) no SAM kills of ASMs;
- c) a greater number of overkills for the SAM LR;
- d) the number of SAM failures; and
- e) the short ASM impact interval.

These anomalies do not significantly detract from the conclusions presented in the parametric and nonparametric evaluations.



Plot of Empirical Cumulative Distribution Function for Both SAMs.

Figure 11

a. Lack of Difference in Effectiveness

The most probable reason for the lack of difference in the effectiveness of the two SAM systems was the jamming environment. The reduced detection ranges experienced in jamming will tend to preclude the use of SAMs at the longer ranges available to the SAM LR system.

b. No SAM Kills of ASMs

The lack of SAM kills of ASMs was primarily due to the geometry of the ASM launch positions and the program logic concerning SAM targeting. The program logic requires that the closest target be considered as most threatening and therefore engaged first. In the problem, the ASM launch positions were less than 10 miles from their point of closest approach to the SAM ship positions. Consequently, the ASMs with their greater speed were closer than the raiders to the SAM ships for only the first 30 seconds after their launch. After that period, their speed caused them to be at a greater range from the SAM ship. Thus the SAM ships had a 30 second period in which to detect, acquire, and designate an ASM as the most threatening target. The reaction time distributions for the SAM ships precluded such a short reaction time in most cases.

c. Overkills

The higher number of overkills for the 100 mile SAM was due to the longer flight time of the SAM. This coupled with a lack of coordination resulted in a greater opportunity for another unit to obtain a kill on the target

while a second SAM was in flight. Targets that had been destroyed prior to the scheduled SAM launch time were not engaged.

d. SAM Failures

The number of SAM failures includes SAMs which were fired on the ASMs that impacted on the HVT while the SAM was in flight. These attempted engagements occurred since the SAM units were not given the capability to determine the ASM impact point.

e. Short ASM Impact Interval

The tightness of the ASM impact interval may appear to be pessimistic in relation to a real world threat. However, this should not detract from the comparison of the two SAM systems.

IV. MODEL INPUTS

The inputs required to use FADS fall into three groups. These are the X vector, the target list assignments, and the target lists themselves. The amount of actual input required depends upon the size of the problem to be analyzed.

A. THE X-VECTOR

All X vector inputs are real values and are read into the X vector in the following way. Each input card must contain six numbers. The first number is the integer address in the X vector. This integer should be placed in columns 1-10, right justified. The remaining five numbers are the values to be inserted in the five X vector positions beginning with the position indicated in columns 1-10 of the input card. The format for each card with X vector data is (I10,5F10.3). If there are no data to be read into a position, no input is required, unless the position falls within the scope of another input card. The end of the X vector inputs is signaled by the inclusion of a zero card. This card contains a zero in column 10 and zeros in the five data positions. A brief overview of the organization of the input array is provided below. Details concerning the individual sub-sections are provided at the beginning of each sub-section. Specifics dealing with the input values are discussed in the description of the particular input value and as footnotes to the individual sections.

The following is the organization of the input X vector:

X(1) to X(100), Control switches and program constants

X(101) to X(500), Ship Classes

X(501) to X(900), SAM Classes

X(901) to X(1200), Radar Classes

X(1201) to X(1400), Ship Positions

X(1401) to X(1800), Delay Functions

X(1801) to X(2000), Raid Classes

X(2001) to X(2200), Raid Weapon Classes

X(2201) to X(2740), Initial Raider Positions.

1. Control Switches

These inputs include logic switches for varying the general play of the game. They also provide the means for controlling the output in the form of debug and array printout switches. Several of the control switches are related to inputs for specific systems which appear in later sections and must be consistent with later usage. Other portions of this input section are used to store values for generating statistics and for internal use by the model. These portions should not have inputs since their value will be set as required by the model.

<u>X()</u>	<u>Inputs</u>
1	Case number
2	Blue force equipment availability switch: 0 = 100% availability 1 = use input availabilities

X()

Inputs

- 3 Blue force radar detection range printout in Event 2:
0 = no print
1 = print
- 4 Fleet coordination of Blue forces:
0 = none
1 = coordinated defense
- 5 Blue ship out of action after N hits:
0 = yes
1 = no
(N is a ship class input)
- 6 Number of iterations. (Must be at least 1. If X(85) used, must be at least 10 and less than 101.)
- 7 Horizon/Sector Scan for Blue fire control radar system enabled:
0 = no
1 = yes if equipment capable
- 8 Blue SAM Sector enable:
0 = don't use sectors
1 = sectors used
- 9 Print control:
0 = none
1 = selected output tables and intermediate debug printouts. Set to 0 by the model after first iteration.
- 10 Detectability to detection delay:
0 = use input distribution function
0.XX = a fraction; time for Raider or ASM to move this portion of calculated detection range.
- 11 ISEED value. Initial seed value used in generation of random numbers. Can be up to a seven digit number.
- 12 X-array print out switch:
0 = no print
1 = print out X-array as read in, target lists, and target list assignments.
- 13 Random number counter. Set to 0 by model. Maintains running count of random numbers drawn.

<u>X()</u>	<u>Inputs</u>
14	Total number of random numbers used. Computed by model.
15	Converted X-array print out switch: 0 = no print 1 = print out X-array as converted by model.
16	Blue first shoot control: 0 = Blue may fire as soon as Red detected. 1 = Blue may only fire after first Red missile launch.
17	Number of jamming raiders: 0 = no jammers 1 = one jammer 2 = two jammers, etc.
18-19	Spares
20	Altitude in feet above which a raider will be considered as being at "high altitude" for purposes of obtaining a visual identification of a non-radiating picket.
21	Probability of "high altitude," from X(20), raider launching ASM at a non-radiating picket.
22	Probability of "low altitude," below X(20) input, raider launching ASM at non-radiating picket.
23	Maximum range (nautical miles) at which a raider is able to obtain a visual identification of a Blue surface unit.
24	Geographical plots: 0 = no plots required 1 = print plot of Blue positions 2 = print plot of raider tracks 3 = print both plots
25-50	Spares
(51-60)	(Debug switches - cleared at end of first iteration a printout will occur if input value is 1.)
51	Ship table.
52	Raid table.
53	SAM table.

<u>X()</u>	<u>Inputs</u>
54	Random numbers used.
55	Subroutine login/logout.
56	SAM/ASM engagement, ASM impact, and SAM kill.
57	ASM detection data.
58	Closest point of approach and IBAT data.
59	SAM-ASM Intercept data (angles).
60	Store and Get Event Log.
(61-70)	(Statistics generated by the model, ignore for input.)
61	Total ASM's fired for all iterations.
62	Total ASM's failed at launch.
63	Total ASM's killed by SAM's.
64	Total ASM's failed in flight.
65	Total ASM's destroyed with launch platform.
66	Total SAM launches.
67	Total SAM failures.
68	Total SAM overkills.
69	Total ASM successfully launched.
70	Total ASM hits.
71-74	Spares
75	Number of SAM rounds remaining in Fleet. Internal use by the model.
76	Hazard zone radius, nm. If predicted intercept of target is within this range of another ship, then the firing ship must hold fire until the predicted intercept point has moved beyond this range.
77	Breakpoint altitude, ft, used to select proper SAM velocities, ranges, and intercept contours, for "high" or "low" SAM contours.

<u>X()</u>	<u>Inputs</u>
78	Ship position inputs coordinate system: 0 = Polar (000 True is Y axis). 1 = Cartesian (X = ; Y =).
79-80	Spares
81	Radar horizon factor (default value 1.23).
82	End of game time (default value 120 min).
83	Launch interval for one raid, min.
84	Launch interval for all raids, min.
85	Number of ship for which the display of hit frequency and hit interval is desired. Enter 0 if analysis is not desired or if the number of iterations is less than 10 or greater than 100, in which case the histogram can not be generated by the model.
86	Interval for initial launch of Red SSM's, min.
87	Recognition delay, in minutes, for stationary Red raiders. For use when X(10) is not zero.
88	Number of ships.
89	Number of raiders (including Red aircraft which are only jammers, those without weapons, and Red surface/subsurface units).
90-100	Spares

2. Ship Class Inputs

The different types of BLUE ships in the simulation are specified by the ship class inputs. Included under one listing are all of the ships of a particular class (e.g. DDG, CG, FFG) which possess similar weapons and detection capabilities. A maximum of 10 different classes may be used. Ship class 1 is input into X(101) to X(140); ship class 2 into X(141) to X(180); etc.

<u>X()</u>	<u>Inputs</u>
101	SAM/SSM battery #1 class ¹
102	Sam/SSM battery #2 class
103	SAM/SSM battery #3 class
104	SAM/SSM battery #4 class
105	Search radar #1 class number ²
106	Search radar #2 class number
107	Search radar #3 class number
108	Search radar #1 antenna height (ft)
109	Search radar #2 antenna height (ft)
110	Search radar #3 antenna height (ft)
111	Fire control radar #1 antenna height (ft)
112	Fire control radar #2 antenna height (ft)
113	Fire control radar #3 antenna height (ft)
114	Fire control radar #4 antenna height (ft)
115	Coordination capability for this ship class: 0 = none (override) 1 = coordination X(14) if fleet coordination is in use.
116	Probability of correct identification and designation to Weapon Direction Equipment (WDE).
117	Class of RTDF #2 (detection to ID and designation to WDE).

¹ Enter 1 if the battery has SAM/SSM's where class inputs are listed in X(501) to X(540); enter 2 if SAM/SSM inputs are in X(541) to X(580); etc.

² Enter 1 if the search radar class inputs for the respective search radar are contained in X(901) to X(920); enter 2 if the search radar class inputs are in X(921) to X(940); etc. Note that the Fire Control Radar class is listed with its associated SAM class inputs.

<u>X()</u>	<u>Inputs</u>
118	Class of RTDF #3 (designation to assign FCS).
119	Class of RTDF #5 (firing delay).
120	Class of RTDF #7 (decisional delay for horizon/ sector scan mode -- used with X(7)).
121	Number of hits required to put ship out of action.
122	Left SAM battery #1 launcher train angle limits (deg. true).
123	Right SAM battery #1 launcher train angle limits (deg. true).
124	Left SAM battery #2 launcher train angle limits (deg. true).
125	Right SAM battery #2 launcher train angle limits (deg. true).
126	Left SAM battery #3 launcher train angle limits (deg. true).
127	Right SAM battery #3 launcher train angle limits (deg. true).
128	Left SAM battery #4 launcher train angle limits (deg. true).
129	Right SAM battery #4 launcher train angle limits (deg. true).
130	Ability to determine target at which an ASM has been fired: 0 = No 1 = Yes
131	Designation for non-radiating picket units using bistatic radar: 0 = No; unit will be targeted using only the normal target list algorithm. 1 = Yes; unit will be targeted using both the normal target list algorithm and the additional algorithm for non-radiating pickets. If some bistatic units are to be used in the main force, a separate ship class must be en- tered for them.
132-140	Spares

<u>X()</u>	<u>Inputs</u>
141-180	Ship class 2
181-220	Ship class 3
221-260	Ship class 4
261-300	Ship class 5
301-340	Ship class 6
341-380	Ship class 7
381-420	Ship class 8
421-460	Ship class 9
461-500	Ship class 10

3. SAM/SSM Class Inputs

These inputs specify the BLUE SAM/SSM system capabilities in terms of missile flight characteristics, fire control radar class, salvo firing doctrine, missile reliabilities and kill probabilities. A maximum of 10 different SAM/SSM classes may be input. SAM/SSM class 1 is input into X(501) to X(540); SAM/SSM class 2 into X(541) to X(580); etc.

<u>X()</u>	<u>Inputs</u>
501	Max range, nm, against "high" altitude target.
502	Average speed, knots, for expected intercept range against "high" altitude target (converted by the model to nm/min).

<u>X()</u>	<u>Inputs</u>
530	A, nm, "high" altitude target ³
504	B, nm, "high" target ³
505	N, for "high" target ³
506	SLOPE against "high" target ³
507	SEEK, nm, for "high" target ³
508	Max range, nm against "low" altitude target
509	Average speed, knots, against "low" altitude target (converted by the model to nm/min).
510	A, nm, against a "low" target
511	B, nm, against a "low" target
512	N, for "low" target
513	SLOPE for "low" target
514	SEEK, nm, for "low" target
515	Minimum range, nm
516	Maximum altitude, ft
517	Number of Fire Control Radar (FCR) channels for FCR Type 1. (0=missile not requiring a dedicated fire control system.)
518	Class of FCR - Type 1
519	Number of FCR channels for FCR Type 2
520	Class of FCR - Type 2
521	Number of FCR channels for FCR Type 3
522	Class of FCR - Type 3

³ The definitions of A, B, N, SLOPE, and SEEK are contained in the description of subroutine TIMMY in Appendix B.

<u>X()</u>	<u>Inputs</u>
523	Horizon sector scan capability for fire control radars: 0 = No (used when X(7) set) 1 = Yes input as XXX = unit digit FCR Type 1 ten digit FCR Type 2 hundred digit FCR Type 3
524	Number of SAM's per salvo
525	Launch cycle time, min
526	Probability that launcher is available (used only when X(2) is set to 1).
527	Magazine size
528	Spare
529	Probability of single-shot kill
530	System reliability
531	Reliability (launch, guidance, and fuse)
532	Terminal guidance time, min (if HAW set to 0).
533	Kill assessment time, min
534-535	Spares
536	Flag for Blue surface to surface missiles: 0 = SAM 1 = SSM
537	Single shot kill probability for a crossing target
538-540	Spares
541-580	SAM Class 2
581-620	Sam Class 3
.	.
.	.
.	.
861-900	SAM Class 10

4. Radar Class Inputs

Search and fire control radars for both BLUE and RED units are specified in this section of the inputs. Search radars classes are related to the ship class and raid class inputs. The fire control radars are used with the appropriate SAM/SSM class inputs although their antenna heights are contained in the ship class inputs. The radars are specified on the basis of their detection capabilities, beam widths, side-lobes, radar frequency, and delay functions. In the case of a bistatic radar, the location and antenna height of the transmitter must also be specified. A maximum of 15 radar classes may be included. Radar class 1 is input into X(901) to X(920); radar class 2 in X(921) to X(940); etc.

<u>X()</u>	<u>Inputs</u>
901	Radar Type: 0 = Bistatic 1 = Monostatic
902	β , detection range in clear environment, $\text{nm}/\text{m}^{\frac{1}{2}}$ (see Appendix C).
903	α , detection range with standoff jamming of $1\text{w}/\text{mhz}$, $\text{nm}/\text{m}^{\frac{1}{2}}$ (see Appendix C).
904	Side-lobe ratio. Number of db that average side-lobe is below main beam. Enter as a nega- tive number. Converted by model to side-lobe coefficient for use in obtaining jamming effects.
905	Maximum instrumented range, nm.
906	Class of reaction time distribution function: Detectability-to-detection for search radars. FCS assigned to acquisition for fire control radars.

<u>X()</u>	<u>Inputs</u>
907	Radar frequency band index. 1, 2, 3, or 4. Used with jamming to provide for frequency differences in various radars.
908	Class of reaction time distribution function for fire control radars: Detectability to detection delay in horizon/sector scan mode. Blank for search radars.
909	Max Director assignment range for FCR, nm.
910	Spare
911	Radar beam width in degrees. (Converted to one-half beam width in radians by the model.)
912	Spare
913	Probability radar is fully operable. (Used when X(2) set.)
914-916	Spares
917	Ship number of bistatic transmitter. Used only with bistatic radars. If transmitter is not located on a ship, a dummy ship must be input at the appropriate geographical location of the transmitter.
918	Bistatic transmitter antenna height in feet. Used only with bistatic radars.
919-920	Spares
921-940	Radar Class 2
·	·
·	·
·	·
1181-1200	Radar Class 15

5. Ship Position Inputs

BLUE ship positions are input by specifying the class of a ship that is at a given location. The position may be entered as the range and bearing from force center or as X and Y coordinates in nautical miles. The form must be

the same for all ships and is dependent on the value of X(78). The left and right firing bearing for the ships must also be specified if firing sectors are used. If a mix of some ships with firing sectors and others without is used, X(8) should be set to 1 and appropriate bearings entered for all ships. Ships which are not limited should be assigned a left bearing of 000 and a right bearing of 359.99. A maximum of 40 ships may be used. Ship 1 is input into X(1201) to X(1205); ship 2 in X(1206) to X(1210); etc.

<u>X()</u>	<u>Inputs</u>
1201	Ship class number.
1202	If X(78) = 0, circle in nautical miles = 1, X coordinate in nm
1203	If X(78) = 0, bearing from forces center in degrees true = 1, Y coordinate in nm
1204	Left sector limit, degrees true, use if X(8) = 1.
1205	Right sector limit, degrees true, use if X(8)= 1. In assigning sector limits to ships with no limitations, put 000 in X(1204) and 359.99 in X(1205).
1206-1210	Ship number 2
.	.
.	.
.	.
1396-1400	Ship number 40

6. Reaction Time Distribution Function Inputs

These inputs provide appropriate delays, in minutes, for processing events during the simulation. A detailed description of the functions together with an example is contained in Appendix B under subroutine REACT. There are

seven events which may be specified by up to five different classes of delay functions for each event. The reaction functions 2, 3, 5, and 7 are related to ship class inputs. Functions 1, 4, and 6 are used with radar class inputs.

#1: Detactability to Detection (5 classes)

<u>X()</u>	<u>Inputs</u>
1401	Delay in minutes for 0.1 cumulative probability.
1402	Delay in minutes for 0.2 cumulative probability.
1403	Delay in minutes for 0.3 cumulative probability.
1404	Delay in minutes for 0.4 cumulative probability.
1405	Delay in minutes for 0.5 cumulative probability.
1406	Delay in minutes for 0.6 cumulative probability.
1407	Delay in minutes for 0.7 cumulative probability.
1408	Delay in minutes for 0.8 cumulative probability.
1409	Delay in minutes for 0.9 cumulative probability.
1410	Delay in minutes for 1.0 cumulative probability.
1411-1420	Class 2 of RTDF1
·	·
·	·
·	·
1441-1450	Class 5 of RTDF1

#2: Detection to ID and Designation to Weapons Direction Equipment (5 classes)

1451-1460	Class 1 of RTDF2
·	·
·	·
·	·
1491-1500	Class 5 of RTDF2

<u>X()</u>	<u>Inputs</u>
#3:	ID and Designation to Fire Control System (FCS) Assignment (5 classes)
1501-1510	Class 1 of RTDF3
.	.
.	.
.	.
1541-1550	Class 5 of RTDF3
#4:	FCS Assigned to Acquisition (5 classes)
1551-1560	Class 1 of RTDF4
.	.
.	.
.	.
1591-1600	Class 5 of RTDF4
#5:	FCS Acquire to Fire (5 classes)
1601-1610	Class 1 of RTDF5
.	.
.	.
.	.
1641-1650	Class 5 of RTDF5
#6:	Detectability to Detection for Fire Control Radar in Horizon/Sector Scan Mode (5 classes)
1651-1660	Class 1 of RTDF6
.	.
.	.
.	.
1691-1700	Class 5 of RTDF6
#7	Decisional Delay for Horizon/Sector Scan Mode (5 classes)
1701-1710	Class 1 of RTDF7
.	.
.	.
.	.
1741-1750	Class 5 of RTDF7
1751-1800	Spares

7. Raid Class Inputs

Raid classes are used to specify the launch platforms for the RED ASM/SSM and standoff jammers. The launch platforms can be aircraft or surface units. Submarines are required to be on the surface for launch and are input as a surface unit. The raid classes contain the offensive capability of the RED units in terms of weapons carried, radar class, jamming ability, and speed. The inputs also specify the radar cross section of the raider and the number of hits to put it out of action. A maximum of 10 classes may be input. Raid class 1 is contained in X(1801) to X(1820); raid class 2 in X(1821) to X(1840); etc.

<u>X()</u>	<u>Inputs</u>
1801	Spare
1802	Number of hits to put out of action, always 1 for aircraft. Must be whole number.
1803	Number of first type weapons carried.
1804	Class of first type weapon.
1805	Number of second type weapons carried.
1806	Class of second type of weapon.
1807	Radar class number.
1808	Salvo switch (surface and subsurface only) 0 = 1 missile per salvo 1 = 2 missiles per salvo
1809	Launch cycle time for salvo, minutes for surface/subunits only.
1810	Jamming power, w/MHz on band 1.
1811	Jamming power, w/MHz on band 2.
1812	Jamming power, w/MHz on band 3.

<u>X()</u>	<u>Inputs</u>
1813	Jamming power, w/MHz on band 4.
1814	Raid speed, knots (converted by the model to nm/min).
1815	Raid radar cross section, meters squared.
1816	Fourth root of raid radar cross section (computed by the model).
1817	Jammer beam width in degrees. (Converted to one-half beam width in radians by the model.)
1818	Jammer side-lobe ratio. Number of db that average side-lobe is below main beam. Enter as negative number. (Converted by model to side-lobe coefficient for use in obtaining jamming effects.)
1819-1820	Spares
1821-1840	Raid Class 2
.	.
.	.
.	.
1981-2000	Raid Class 10

8. Raid Weapon Class Inputs

The raid weapon classes specify the types of ASM/SSM by their flight characteristics, reliabilities, and radar cross section. A total of 20 different classes may be used. Weapon class 1 is input in X(2001) to X(2010); weapon class 2 in X(2011) to X(2020); etc.

<u>X()</u>	<u>Inputs</u>
2001	ASM/SSM speed, knots (converted by the model to nm/min).
2002	ASM/SSM flight altitude, ft.

<u>X()</u>	<u>Inputs</u>
2003	Launch range ⁴
2004	Reliability (launch and initial guidance).
2005	Inflight reliability (including homing and fusing).
2006	Radar cross-section, meters squared.
2007-2008	Spares
2009	Weapon horizon, nm (computed by model).
2010	Fourth root of radar cross section (computed by model).
2011-2020	Weapon Class 2
.	.
.	.
.	.
2192-2200	Weapon Class 20

9. Raid Position Inputs

These inputs contain the location, course, and altitude of an individual launch platform. If the raider has a jammer, the jammer target is also specified. A maximum of 90 raiders is permitted. Raid 1 is input in X(2201) to X(2206); raid 2 in X(2207) to X(2212); etc.

<u>X()</u>	<u>Inputs</u>
2201	Raid class number (1, 2, etc.)
2202	Range, nm (from (0,0)).
2203	Bearing, degrees true (from (0,0)).

⁴ Launch Range is measured from the position (0,0). The user must consider this fact when dealing with dispersed formations and multiple target list. The distance of the intended launch point from force center is the proper input, not the range of the launch point from the primary target.

<u>X()</u>	<u>Inputs</u>
2204	Altitude, feet (less than 50 feet for surface/ subsurface units).
2205	Course, degrees true.
2206	Jammer's jamming target: 0 = no jam capability N = ship number of jamming target 999 = force center (0,0)
2207-2212	Raid number 2
.	.
.	.
.	.
2734-2740	Raid number 90

B. THE TARGET LIST ASSIGNMENTS

The target list assignments are read in immediately following the zero card indicating the end of the X vector inputs. Each RED raider must be assigned a target list, even if the raider carries no weapons. If the raider carries no weapons the target list information is not used, but the input logic requires that some number be entered. There must be a total of three cards which are to be dimensioned 30I2. The first thirty raiders are entered with card one, the second thirty raiders on two, etc. For example, if the simulation has four RED aircraft, column 2 card 1 would contain the number of the target list for raider number 1; column 4 card 1 that for aircraft number 2; etc. Columns 9 through 60 on the first card, and 1 through 60 on the next two cards could contain any integers desired, usually 00.

C. THE TARGET LISTS

The cards that input the target lists follow immediately after the three cards described above. The values to be read in are stored in the array PLIST. This is a (40,6) array in which the columns are the target lists. The array allows for up to 40 individual targets and six separate listings of targets. The target list is identified by its column number, and it is this number that was entered in NRTGT. The PLIST cards follow immediately after the three input cards for NRTGT mentioned above. The format for the PLIST cards is 10F8.4. The column entries are the total probability of targetting all ships up to and including the target ship in the given row. As an example, in the case of three target lists and five BLUE ships the PLIST array could appear as follows:

	1	2	3	4	5	6
1	.12	0.0	.25	0	0	0
2	.42	.25	.50	0	0	0
3	.62	.50	.50	0	0	0
4	.82	.75	1.0	0	0	0
5	1.0	1.0	1.0	0	0	0
6	0	0	0	0	0	0

The raiders that have been assigned target list 1 would have a probability of .12 of firing a missile at ship 1 each time it fires. It would have a probability of .3 of firing at ship 2, and .20 of firing at ship 3. A raider firing a missile with target list 2 would have a probability of 0.0 of firing at ship 1 and .25 of firing at any of the other four. A raider with list 3 would have a .25 probability of

firing at ship 1, a .25 probability of firing at ship 2, and a .50 probability of firing at ship 4.

The input cards for the PLIST array would be structured as follows. Card one would contain .12 in columns 1-8, .42 in 9-16, .62 in 17-24, .82 in 25-32, 1.0 in 33-40, and zeros throughout the remainder. Cards two, three, and four would contain zeros. Since card five starts list two, it is filled out in the same manner as card one, with, in this case, cards 6, 7, and 8 containing zeros. Since there are only five ships and three lists, the last card required for this run would be card 9. If the full 40 ships and six target lists were being used, a total of twenty-four cards would be required to input the target lists.

V. MODEL OUTPUT

The model produces three types of output. The types are standard, special displays, and debugging. For debugging, there are a number of switches in the control section of the inputs which may be set to provide intermediary values during the iteration. The special displays provide one time outputs of geographical plots, histograms, and selected tables. The standard output occurs at the end of each iteration and contains an abbreviated battle history along with statistical data concerning the engagement.

A. STANDARD OUTPUT

The standard output consists of the ASM table, the SAM-ASM-RAID table, and statistics regarding hits, detections, and opportunities to engage. The contents of the tables are given below. The actual format of this output is provided in the tables of representative output at the end of this section.

1. The ASM Table

Column 1 ASM/SSM number. This number identifies the ASM/SSM by target number. The order in which the missiles were launched or destroyed can be determined by subtracting 90 from the target number.

Column 2 Status code. This code indicates the disposition of the missile. The code is as follows:

0 missile failed on launch.

1 missile was in flight.

- 2 missile was destroyed by SAM. The SAM-ASM-RAID table will indicate which missile ship was responsible.
 - 3 missile failed in flight.
 - 4 missile flight successful, missile impacted on target ship.
 - 5 missile destroyed when raider destroyed.
- Column 3 Time of impact. This will be the time the missile impacted, or would have impacted, unless it was lost when raider was destroyed. In this case it will be 0.0.
- Column 4 Launch raid.
- Column 5 Target ship. Target ship number unless the missile was lost with raider destruction.
- Column 6 Launch time. The time of missile launch unless lost when raider destroyed. In this case it is the time of loss.
- Column 7 Weapon class. If lost with raid, 0.0.
- Column 8 X coordinate at launch.
- Column 9 Y coordinate at launch.

2. The SAM-ASM-RAID Table

- Column 1 Target number. Targets 1 through 90 are raiders, 91 through 190 are missiles.
- Column 2 Launcher. The launcher code AAB, where AA is the ship number and B is the launcher.
- Column 3 Channel. The director-channel code AB where A is the director number and B is the channel number.
- Column 4 Time of Launch. Time of BLUE missile launch.
- Column 5 Kill code. The code is as follows: a negative number, an overkill, the number indicating the number of missiles in the salvo; a zero, a missile failure or system support failure; a positive number, a kill, the value indicating the number of missiles in the salvo.

Column 6 Time channel free. The game time that this launcher-channel combination will be available for re-engagement or reassignment.

3. Statistical Output

The output form of the statistics for each iteration are underlined. The definitions of the terms used follow each form.

The ships took "H" hits: The total number of hits (H) sustained by the BLUE force.

Of "X" ASMs fired, "Y" ("Z" percent) failed at launch.

X: total number of ASM/SSM that survived to launch.

Y: of X, the number that failed on launch.

Z: Y/X .

Of launched ASM, "W" ("P" percent) were killed by SAMs, "Q" ("R" percent) failed in flight.

Launched ASM; from above, X-Y.

W: the number of RED SSM/ASM shot down.

P: $W/\text{Launched ASM}$.

Q: the number of RED SSM/ASM that failed in flight.

R: $Q/\text{Launched ASM}$.

Of total ASMs available "I" ("J" percent) were destroyed when mother killed by SAMs.

Total ASMs: All SSM/ASM carried by engageable raiders or raiders that reach a launch position.

I: The number of RED ASM/SSM lost when raider destroyed.

J: $I/\text{Total available}$.

"D" SAMs were launched of which "E" ("F" percent) failed and "G" ("H" percent) were overkills.

D: Total BLUE SSM/SAM launched.

E: Number of SAM/SSM evaluated as failure at intercept or system support.

F: E/D.

G: Overkills. Overkill occurs when the target does not survive to the SAM intercept point due to being shot down. If the target is a missile and the RED missile reaches its target prior to intercept, this intercept is scored as a failure and not an overkill.

H: G/D.

The ship statistics for each iteration are printed in a table labeled SHIP STATS. The format is as follows:

Column 1 Ship number.

Column 2 Chances to engage. The number of RED targets that will enter this ship's missile envelope.

Column 3 Number of engagements. The number of actual missile intercept evaluations.

Column 4 Number of targets killed.

Column 5 Bombers detectable. Of those targets that will enter the ship's missile envelope, the number that are raiders.

Column 6 Bombers detected. Of the raiders detectable, those detected.

Column 7 ASM's detectable. Those ASM/SSM that will enter the ship's missile envelope.

Column 8 ASM's detected.

The following additional statistics are provided with the SHIP STATS table:

Average detection range: The average detection range of each ship on those targets that entered its missile envelope.

"X" ASMs were fired on by the fleet. X is the number of ASM/SSM that were engaged by one or more BLUE units.

"X" Bombers were fired on by the fleet. X is the number of RED raiders that were engaged by one or more BLUE units.

ASMs fired at. The number of ASM/SSM that were first engaged by each ship.

Bombers fired at. The number of RED raiders that were first engaged by each ship.

A table of the frequency of hits received by ships is printed at the end of the run. This table displays a distribution of the hit frequency over all ships for all runs. It constitutes a histogram of hit frequencies for all BLUE units.

B. SPECIAL DISPLAY SWITCHES

The below listed switches will provide the indicated output if set to one or the specified value. Setting X(2) to 1 will provide the equipment availability status for each iteration. The remaining switches provide a one-time output for a run.

X(2) Indicates equipment availability check desired. Prints out each ship number and equipment status.

X(24) Plot of BLUE unit positions using DISPL if set to 1.

Plot of raider tracks and launch points using RAIDIS if set to 2.

Both plots are provided if set to 3.

X(51) Prints the SHIP table at the end of the first iteration. The table is structured as follows: (see Table IV)

Column 1 Ship number.

Column 2 Ship class number.

Column 3 Ship's X coordinate.

Column 4 Ship's Y coordinate.

Column 5 Hits to sink. The number of RED SSM/ASM missile hits to put out of action.

Column 6 Class address. The ship class starting index in the X array.

Column 7 Up/down. 0 = sunk
1 = operating normally.

X(52) Prints the RAID table at the end of the first iteration in the following form: (see Table IV)

Column 1 RAIDER The raid number, 1-90.

Column 2 CLASS The class starting index in the X array.

Column 3 TIMER (R) The time the raider was at the position indicated in columns 4 and 5.

Column 4 XR The raider's X position at the time specified in column 3.

Column 5 YR The raider's Y position at the time specified in column 3.

Column 6 XEOG The X position of the raider at the time specified as the end of the game.

Column 7 YEOG The Y position at the end of the game.

Column 8 XL The raider X position at its first launch time. If the raider has no missiles, or cannot reach a launch position, the end of game position will also be indicated here.

Column 9 YL The raider Y position at first launch.

Column 10	ALT	The raider altitude in feet. If 50 feet or below, the raider is considered a surface or subsurface unit.
Column 11	HORZ	The raider radar horizon in miles.
Column 12	WEP-CLASS	The class number of the raider's longest range ASM/SSM.
Column 13	WEPS	The total number of weapons carried by the raider.
Column 14	UP/DOWN	The status of the raider at the end of the game. 0 = shot down or sunk 1 = operating normally.

X(53) Prints the SAM table at the end of the first iteration. The table is organized as follows: (see Table V)

Column 1	SAM	The salvo number.
Column 2	SAM CLASS INDEX	The SAM type class number for the SAM/SSM in this BLUE miss-le salvo.
Column 3	SHIP NUMBER	The firing ship.
Column 4	SAM LEFT	The number of SAM/SSM remaining in the battery's magazine after this salvo was fired.
Column 5	CH1 FREE	This is the time that channel 1 for the fire control radar used in this intercept will be free for re-engagement or reassignment. If the missile requires director illumination throughout missile flight, or the missile is totally independent of the director, this is an indication of system availability.

Columns 6-10

Channel availability times for systems employing a time sharing system of homing.

Column 11 SALVO

The number of missiles in the salvo.

X(85) If the number of iterations is between 10 and 100, prints a histogram of hit frequency and ASM/SSM arrival interval for the BLUE ship who's number has been entered.

C. THE DEBUGGING SWITCHES

The debugging switches, X-3,9,12,15,54,55,56,57,58,59, 60, are set by assigning a value of 1 to the specified location in the X-array. These switches are subroutine related and will provide the indicated output whenever the program cycles through the appropriate portion of the subroutine. Reference should be made to the description of the subroutines in Appendix B when using the debugging switches.

In the below format, the debug switch which must be set to 1 is listed and is followed by the subroutine name with its associated output. The output is in the form as it appears in the computer printout. The parenthesis indicate the location of the intermediary values.

X-3

SUBE1 Detection range by ship () on raider () with radar () in clear, jamming, and horizon limited environments.

Reaction time delays for raid () by ship ().

Bistatic radar gain and lose contact times on raider () by ship ().

SUBE2 ASM/SSM failed on launch.

Detection range by ship () on ASM/SSM () with search radar () in clear, jamming, and horizon limited environments.

No detection due to reaction time delay.

Detection range on ASM/SSM by ship () on missile () with system () fire control radar () in clear, jamming, and horizon limited cases. Jamming range of 999. indicates no jamming.

Earliest search radar detection time and earliest fire control radar detection time () ().

When missile launch time will exceed the launch interval set by the user, the launch does not take place. Output is: bomber () could not fire as launch time was () and all ASM's had to be launched by ().

X-9

SUBE3 EV 3 Ship () target () reason ().

EV 3 SAM () battery () channel ().

PRIOR PRIOR debug data input channel () output channel () battery number () input target () output target ().

TIMMY Intercept data: target, firing ship, firing ship position, intercept position, number of firing zones, left and right bearings of the firing zones, launch bearing of SAM.

Target, firing ship, indicator flag, reason.

X-12

MAIN Original X array as read into the computer.

The target lists as read into the computer.

The target list assignments as read into the computer.

X-15

MAIN The X-array as converted by the program.

X-54

MAIN Prints out all random numbers used in the first iteration, in the order they were used.

X-55 Provides the computer time that the program enters and leaves the specified subroutine.

EFFECT Login, logout

JULIE Login, logout

EVENT Login, logout

GETEV Login, logout

STOREV Login, logout

REMOVE Login, logout

TMDASM Login, logout

TMDBOM Login, logout

SUBE1 Login, logout

SUBE2 Login, logout

SUBE3 Login, logout

SUBE4 Login, logout

SUBE5 Login, logout

SUBE6 Login, logout

LOCTIM Login, logout

PRIOR Login, logout

TIMMY Login, logout

RCHECK Login, logout

JAMM Login, logout

BIDET Login, logout

X-56

SUBE4 EV 4 ASM () ship () ASM status () hits on ship () time ().

SUBE5 EV 5 target number () firing ship () launcher () salvo number () time ().

X-57

SUBE1 Detection ranges by ship () on raider () with system () fire control radar () in clear, jamming, and horizon limited cases.

Raider () surface or submarine unit, ship () has no SSM.

Detection ranges on raider () by ship () in horizon search mode.

SUBE2 Reaction time delays.

Detection ranges in horizon search mode of ASM/SSM () by ship () in clear, jamming, and horizon limited cases.

TMDASM No engagement possible, raid () target ship () battery () missile ship () ASM/SSM ().

No engagement possible; raider () ship ().

Engagement data - time entering and time leaving a given range from ship ().

X-58

JULIE Number of SAM/SSM in each battery.

SUBE2 Prints the NONO table after each raider's launch cycle.

NONO table codes are contained in the description of SUBE2 in Appendix B.

SUBE5 For salvo () results ().

X-59

TIMMY Crossing target data: target, firing ship, angle between target flight path and line of sight at launch, angle between SAM/SSM flight path and target flight path, angle between SAM/SSM flight path and line of sight at launch, target position at launch, GSINE, range to target at launch.

X-60

JULIE The events list at start of the iteration.

EVENT The event retrieved.

STOREV The event stored.

The event lost.

THE NUMBER OF SAMs LEFT AT THE END OF ITERATION 1 WAS 126

ASM TABLE
ITERATION 1

ASM NUMBER	STATUS CODE	TIME OF IMPACT	LAUNCH RAID	TARGET SHIP	LAUNCH TIME	WEAPON CLASS	X LAUNCH	Y LAUNCH
91	5.	0.0	2.	0.	15.36	0.	0.0	0.0
92	5.	0.0	2.	0.	15.36	0.	0.0	0.0
93	5.	0.0	2.	0.	15.36	0.	0.0	0.0
94	5.	0.0	2.	0.	15.36	0.	0.0	0.0
95	5.	0.0	1.	0.	16.37	0.	0.0	0.0
96	5.	0.0	1.	0.	16.37	0.	0.0	0.0
97	5.	0.0	1.	0.	16.37	0.	0.0	0.0
98	5.	0.0	1.	0.	16.37	0.	0.0	0.0
99	5.	0.0	5.	0.	17.13	0.	0.0	0.0
100	5.	0.0	5.	0.	17.13	0.	0.0	0.0
101	5.	0.0	5.	0.	17.13	0.	0.0	0.0
102	5.	0.0	5.	0.	17.13	0.	0.0	0.0
103	2.	26.694	3.	1.	20.46	1.	11.58	-99.33
104	0.	27.542	3.	1.	21.86	1.	- 2.59	-91.15
105	2.	27.706	3.	1.	22.11	1.	- 5.11	-89.69
106	2.	28.392	3.	1.	23.07	1.	-14.91	-84.04

THE ORIGINAL ATTACK CONSISTED OF 5 RAIDERS. 1 WERE LEFT AFTER THE ATTACK.

TABLE I
REPRESENTATIVE OUTPUT FOR ASM TABLE

SAM-ASM-RAID TABLE

TGT NO.	LAUNCHER	CHANNEL	TIME OF LAUNCH	KILL CODE	TIME CHANNEL FREE
2.	21.	17.	10.61	1.	15.36
1.	21.	17.	12.15	1.	16.37
5.	31.	17.	12.37	1.	17.13
3.	51.	17.	13.90	0.	18.15
3.	41.	17.	18.15	0.	21.61
103.	41.	17.	21.09	1.	22.85
3.	41.	17.	21.61	1.	23.92
105.	41.	17.	22.76	1.	24.69
106.	41.	17.	23.18	0.	25.49
106.	21.	17.	25.49	1.	27.03

STATISTICS FOR ITERATION NO. 1

THE SHIPS TOOK 0 HITS.
 OF 4 ASMS FIRED, 1 (25.00 PERCENT) FAILED AT LAUNCH,
 OF LAUNCHED ASM, 3 (100.00 PERCENT) WERE KILLED BY SAMS,
 OF THE TOTAL ASMS AVAIL, 0 (0.0 PERCENT) FAILED IN FLIGHT.
 10 SAMS WERE LAUNCHED OF WHICH 3 (30.00 PERCENT) WERE DESTROYED WHEN
 MOTHER KILLED BY SAMS.
 334 RANDOM NUMBERS WERE DRAWN. 0 (0.0 PERCENT) WERE OVERKILLS.

SUMMARY FOR 1 ITERATIONS

OF 4 ASMS FIRED, 1 (25.00 PERCENT) FAILED AT LAUNCH,
 OF LAUNCHED ASM, 3 (100.00 PERCENT) WERE KILLED BY SAMS,
 OF THE TOTAL ASMS AVAIL, 0 (0.0 PERCENT) FAILED IN FLIGHT.
 AVERAGE NUMBER OF HITS ON FLEET FOR 1 ITERATIONS IS 0.0
 10 SAMS WERE LAUNCHED OF WHICH 3 (30.00 PERCENT) FAILED AND
 0 (0.0 PERCENT) WERE OVERKILLS.

TABLE II

REPRESENTATIVE OUTPUT FOR SAM-ASM-RAID TABLE AND THE STATISTICS

334 RANDOM NUMBERS WERE DRAWN.

SHIP STATS FOR ITERATION 1

SHIP NO.	CHANCES TO ENGAGE	NUMBER OF ENGAGEMENTS	TARGETS KILLED	BOMBERS DETECTABLE	BOMBERS DETECTED	ASMS DETECTABLE	ASMS DETECTED
1	4	0	0	1	1	3	3
2	6	3	3	3	3	3	3
3	8	1	1	5	5	3	3
4	7	5	3	4	4	3	3
5	7	1	0	4	4	3	3

SHIP	AVE DET RANGE BOMBERS	AVE DET RANGE ASMS
1	142.96	69.38
2	86.26	61.68
3	63.20	23.85
4	77.66	49.21
5	67.44	16.02

3 ASMS WERE FIRED ON BY THE FLEET

4 BOMBERS WERE FIRED ON BY THE FLEET

SHIP	ASMS FIRED AT	BOMBERS FIRED AT
1	0	0
2	0	2
3	0	1
4	3	0
5	0	1

HITS ON SHIP "I"

1	0
2	0
3	0
4	0
5	0

TABLE III

REPRESENTATIVE OUTPUT FOR SHIP STATS TABLE

SHIP TABLE

SHIP	CALSS	X	Y	HITS TO SINK	CLA-ADR	UP/DOWN
1	1.	0.0	0.0	5.	101.	1.
2	2.	25.00	25.00	1.	141.	1.
3	2.	-25.00	25.00	1.	141.	1.
4	2.	-25.00	-25.00	1.	141.	1.
5	2.	25.00	-25.00	1.	141.	1.

RAID TABLE

RAIDER	CLASS	TIMER(R)	XR	YR	XEOG	YEOG
1	1801.	15.34	15.7	120.9	122.5	-1100.6
2	1801.	14.86	71.3	118.3	-950.0	- 570.6
3	1801.	21.61	32.0	- 67.2	-998.4	483.8
4	1801.	26.17	-51.5	122.1	498.2	1074.2
5	1801.	16.33	-99.3	104.0	774.5	- 739.8

XL	YL	ALT	HORZ	WEP-CLASS	WEPS	UP/DOWN
17.6	98.4	10000.0	174.	1.	4.	0.
34.9	93.7	25306.0	196.	1.	4.	0.
11.6	-99.3	35000.0	230.	1.	4.	0.
498.2	1074.2	10000.0	123.	1.	4.	1.
-67.7	73.6	27000.0	202.	1.	4.	0.

TABLE IV
REPRESENTATIVE OUTPUT FOR SHIP AND RAID TABLES

SAM TABLE

SAM	SAM CLASS INDEX	SHIP NUMBER	SAM LEFT	CH1 FREE
1	1.	2.	29.	15.36
2	1.	2.	28.	16.37
3	1.	3.	29.	17.13
4	1.	5.	29.	18.15
5	1.	4.	29.	21.61
6	1.	4.	28.	22.85
7	1.	4.	27.	23.92
8	1.	4.	26.	24.69
9	1.	4.	25.	25.49
10	1.	2.	27.	27.03

CH2 FR	CH3 FR	CH4 FR	CH5 FR	CH6 FR	SALVO
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.
0.0	0.0	0.0	0.0	0.0	1.

TABLE V

REPRESENTATIVE OUTPUT FOR SAM TABLE

VI. CONCLUSIONS

The use of bistatic search radars is not a new concept. FADS provides a method of evaluating their potential usefulness to the Navy. As demonstrated in the sample problem, FADS also has many applications in weapons systems analysis and the analysis of tactics.

The model was structured along the lines of the FLOATS model in use at the Johns Hopkins University Applied Physics Laboratory. The additional capabilities introduced by FADS should provide a basis for a more realistic view of the present day and future tactical environments. The employment of decoys, dispersed formations, and passive missile traps are but a few of the ways in which FADS might be utilized.

Lastly, the model is ideal for use in an advanced war gaming course. The model is complex, but the simulation was written with ease of reading in mind. With rewriting the core requirements might be reduced, but, in its present form, FADS is easily read and understood, and it could be dissected by the interested student with ease.

APPENDIX A

BISTATIC RADAR SYSTEMS

Although the bistatic radar system was described in the introduction as a radar system in which the transmitter and the receiver are not collocated it is necessary to point out that the separation between the transmitter and the receiver should be comparable to the target distance, that is, on the order of several nautical miles as opposed to several feet. The assumed bistatic system is to provide detection and location information similar to that obtained with current search radar systems. It should in essence provide the user with what would be on a plan position indicator (PPI) scope. No provision is assumed for height finding capability. The basic difference between the target geometry for monostatic and the bistatic radar systems is shown in figure A1.

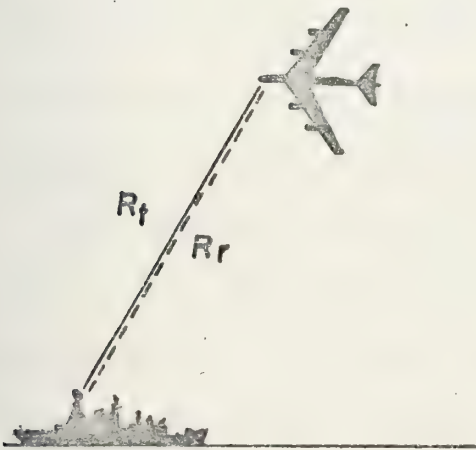


Figure A1a

Monostatic Radar Principle

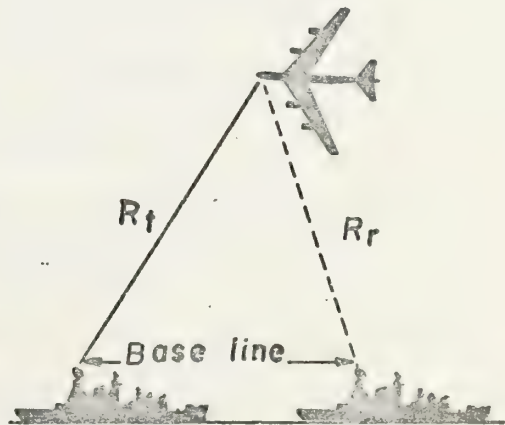


Figure A1b

Bistatic Radar Principle

The bistatic radar concept is not a recent development, although the technology required to bring the system up to the capabilities described above is. The bistatic concept predates the monostatic radar in that the development of the radar duplexer was required in order to convert the original bistatic radar to a monostatic system. Sholnik [Ref. 10, p. 585] states:

Its (the bistatic radar) principle was known and demonstrated many years before the development of practical monostatic radar. ...the first "radar" observations in both the United States and in Great Britain were made with separated CW transmitters and receivers. These early radars were known as wave-interference equipment but were the same as what would now be called bistatic radar. Taylor and Young of the Naval Research Laboratory first demonstrated bistatic radar for the detection of ships in 1922. Their work was disclosed in a patent issued in 1934. The early experiments with wave-interference (bistatic) radar led to the development of monostatic radar in the late 1930s in both this country and abroad. Further development was put aside after the demonstration of the more versatile monostatic-radar principle. Bistatic radar lay dormant for about fifteen years until it was "reinvented" in the early 1950s and received new interest.

Current interest is conceivably motivated by considerations of electromagnetic counter-measures, defense against anti-radiation missiles, and deception roles.

One method for target location with a bistatic system requires knowledge of the distance from the transmitter to the target, (R_x), and to the receiver (R_r), the horizontal angle between the base line (a line from the receiver to the transmitter) and the target bearing, and the elevation angle from the receiver to the target. However, in the simulation problem it is not necessary to determine a target's

location since the target's position at any time is a function of the input parameters. It is only necessary to determine if the target is detectable and, given that it is, determine where along the target's track an individual radar is able to detect the target.

Detection occurs when the reflected power at the receiver is greater than the detection threshold of the receiver for a given probability of detection. The radar range equation for the bistatic radar is identical to the well known monostatic range equation except that the power received varies inversely with the product of $R_x^2 R_r^2$. Additionally the two-way propagation losses differ since the path of the reflected signal is not the same as that of the transmitted signal. The range equation can be readily written in terms of the constants for the radar system, the variables R_x , R_r and the target's radar cross section.

For comparison purposes both the monostatic and the bistatic detection range equations are given below:

$$\text{Monostatic } P_r = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 L_p^2 L_s R^4}$$

$$\text{Bistatic } P_r = \frac{P_t G_t G_r \lambda^2 \sigma}{(4\pi)^3 L_p(t) L_p(r) L_s R_s^2 R_x^2}$$

where:

- R = range to target (monostatic)
- R_x = range from transmitter to target (bistatic)
- R_r = range from receiver to target (bistatic)

- P_t = power of transmitter
 P_r = power received at the receiver
 G = gain of monostatic antenna
 G_t = gain of bistatic transmitter antenna
 G_r = gain of bistatic receiver antenna
 λ = radar wavelength
 σ = target's radar cross section (see below for discussion of bistatic and monostatic approximation)
 L_p = one way propagation losses for monostatic
 $L_p(t)$ = propagation losses from transmitter to target (bistatic)
 $L_p(r)$ = propagation losses from target to receiver (bistatic)
 L_s = system losses

By defining P_r as the minimum power required by the receiver in order to obtain a given probability of detection with typical propagation and system losses and by grouping constants of the radar system, the above equations can be simplified to read: $R = \beta \sigma^{\frac{1}{4}}$ and $R_x^2 R_r^2 = \beta^4 \sigma$ where β is the range at which a particular radar system can detect a one square meter target in a non-jamming environment. Values of β for current U.S. Navy radars are listed in Ref. 9.

When standoff electronic noise jamming is present, the range equations are defined in a similar manner:

$$\text{Monostatic: } R_{bt}^4 = \frac{P_t G \sigma}{4\pi B_r (S/J) \Sigma J P}$$

$$\text{Bistatic: } R_{bt}^2 R_x^2 = \frac{P_t G_t^{\frac{1}{2}} G_r^{\frac{1}{2}} \sigma}{4\pi B_r (S/J) \Sigma J P}$$

where:

R_{bt} = burn through range monostatic

B_r = receiver band width

S/J = signal-to-jamming ratio (includes propagation losses)

ΣJP = sum of jamming power arriving at the receiver

The jamming level from an individual jammer is obtained by multiplying the power of the jammer by the appropriate coefficient for the geometry of the radar and jammer main to side-lobe ratios and dividing by the square of the distances between the jammer and the radar. The individual jamming levels are then added to obtain the sum of the jamming power arriving at the radar.

As in the case with the non-jamming environment, the above equations can be simplified by defining a term α which contains the constants of the radar system and which is equal to the range at which a one square meter target can be detected in the presence of one watt of jamming power per megahertz. The monostatic range equation in jamming is:

$$R_{bt} = \alpha^{\frac{1}{2}} (\sigma / \Sigma JP)^{\frac{1}{4}}$$

and the bistatic equation is

$$R_x R_r = \alpha (\sigma / \Sigma JP)^{\frac{1}{2}} .$$

In solving the bistatic detection problem in the simulation algorithm, R_x and R_r have only the target's position in common. It is therefore necessary to state the product $R_x R_r$ as a function of the target's position and solve the

detection equation in terms of the time at which the target can be detected. If a constant CHAR is defined to be the product of β^4 times σ for a clear environment and α^2 times σ divided by the sum of the jamming power for the jamming situation, the detection equation then becomes $R_x^2 R_r^2 = \text{CHAR}$. The radar is able to detect a target whenever the range product squared is less than or equal to the constant CHAR. By expressing R_x and R_r in terms of time, the solution of the bistatic equation $R_x^2(t)R_r^2(t) - \text{CHAR} = 0$ provides the times at which detection can occur and then be lost as the target moves along its track relative to the transmitter and the receiver. The below figure is a layout of the track and detection points that is illustrative of the detection equation:

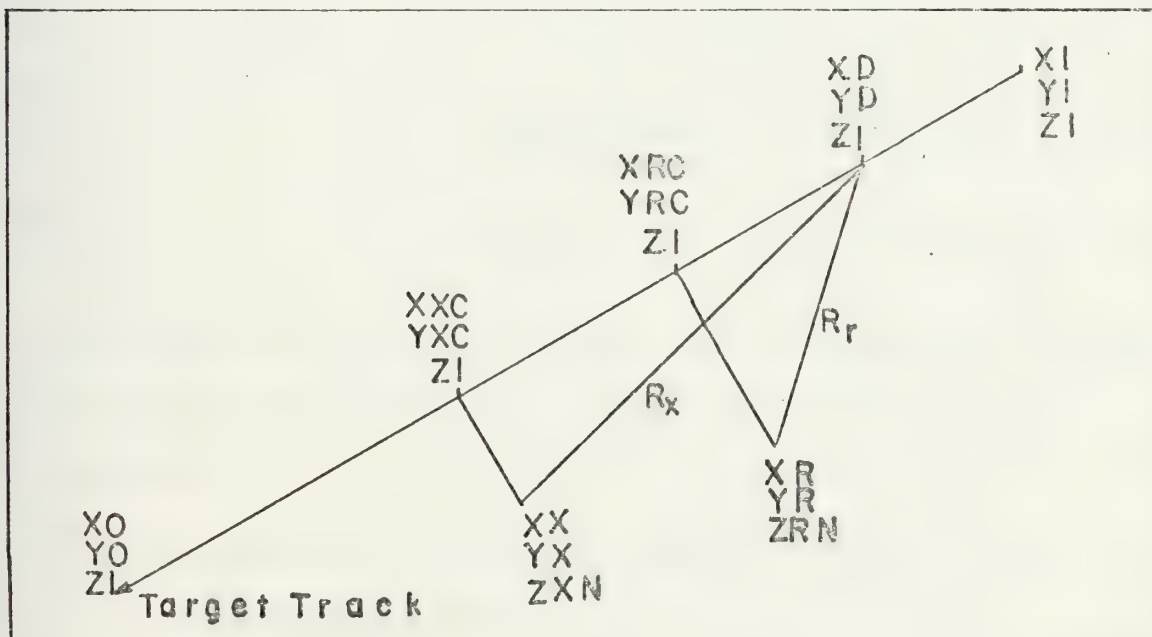


Figure A2
Bistatic Detection Geometry

Labels are as follows:

<u>Receiver</u>	<u>Transmitter</u>	<u>Value</u>
XR	XX	X Coord of position
YR	YX	Y Coord of position
ZRN	ZXN	antenna height in nautical miles
XRC	XXC	X Coord of track CPA
YRC	YXC	Y Coord of track CPA
CPR	CPX	Distance to CPA

Track

X1, Y1	initial position
Z1	altitude in nautical miles
XO, YO	terminal position
V	velocity in nm/min
Vx	velocity in X direction
Vy	velocity in Y direction
XD	X Coord of detection position = (X1+VxT) where T is the time of detection
YD	Y Coord of detection position = (Y1+VyT)

The equation $R_x^2(t)R_r^2(t) - \text{CHAR} = 0$ is expressed in terms of the stated positions; time is the independent variable.

For example:

$$\begin{aligned}
 R_r^2(t) &= (XR-XRC)^2 + (YR-YRC)^2 + (ZRN-Z1)^2 + (XRC-(X1+V_xT))^2 \\
 &\quad + (YRC-(Y1+V_yT))^2 \\
 &= (V_x^2 + V_y^2)T^2 - 2(V_x(XRC-X1) + V_y(YRC-Y1))T + (CPR)^2 \\
 &\quad + (XRC-X1)^2 + (YRC-Y1)^2 \\
 &= AT^2 + DT + E
 \end{aligned}$$

In a similar manner $R_x^2(t) = AT^2 + BT + C$ where $B = -2(V_x(XXC - X1) + V_y(YXC - Y1))T$ and $C = (CPX)^2 + (XXC - X1)^2 + (YXC - Y1)^2$.

The range equation in terms of t then reduces to

$$T^4 + \left(\frac{B+D}{A}\right)T^3 + \left(\frac{C+E}{A} + \frac{BD}{A^2}\right)T^2 + \left(\frac{BE+CD}{A^2}\right)T + \frac{CE - CHAR}{A^2} = 0$$

The real roots of this fourth order polynomial in ascending order are the times at which the target is first detectable, lost, redetected and then lost again. In the case where there are no real roots, the target is not detectable along its track. If only one pair of real roots exists, the radar has only one detection zone against the target.

The multiple detection zones occur when the target penetrates the contour of the equation $R_x R_r = CHAR^{\frac{1}{2}}$ in more than two locations. These contours plot as ovals of Cassini in the plane containing the base line between the transmitter and the receiver. The contours, shown in Figure A3, represent curves of constant sensitivity for the bistatic radar system and a given target. In the case of low sensitivity, the curves consist of two disjunct ellipses with the transmitter and receiver at the furthest foci. As sensitivity is increased the curves become ovals about the receiver and the transmitter and eventually become an ellipse with the transmitter and receiver at the foci. If this ellipse is rotated about its major axis, a prolate spheroid is generated which defines the detection surface for the bistatic radar.

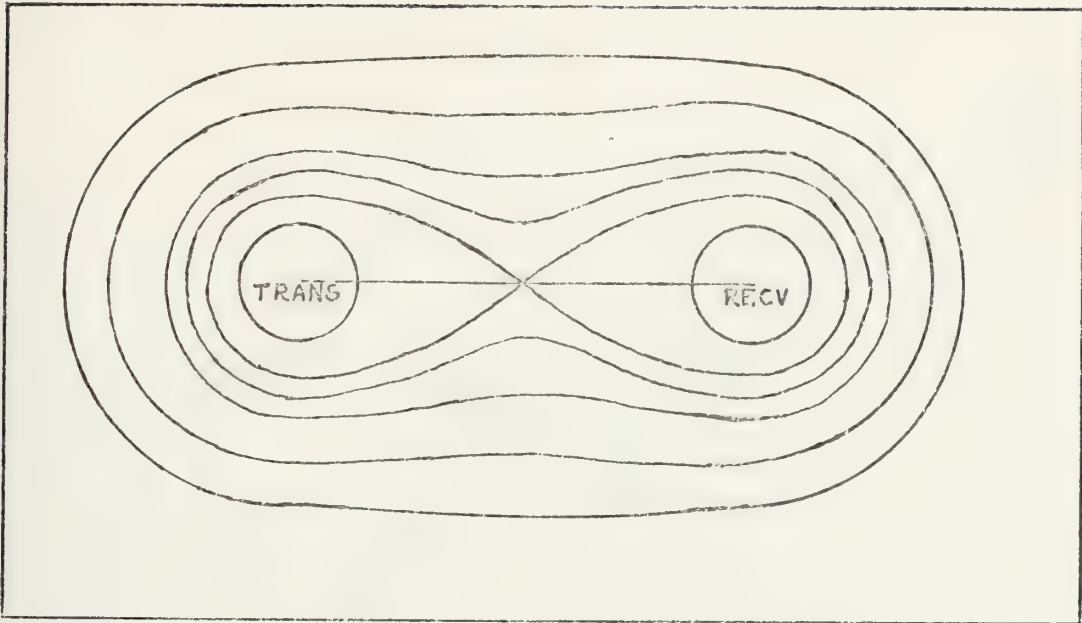


Figure A3

Curves of Constant Sensitivity for Bistatic Radar System

In addition to the requirement that a solution to the radar range equation exists, the target must also be above both the transmitter and the receiver radar horizon for a detection to occur. The radar horizon restrictions can be seen in figure A4, which uses the same track as presented in figure A2, along with an additional axis representing the aircraft position with respect to time.

The positions in figure A4 are defined in figure A2. HORX and HORB are the distances to the transmitter and receiver radar horizons for their respective antenna heights and the target's altitude. TR1 is the time the target first enters the radar horizon of the receiver; TR2 is the time it departs. TX1 and TX2 are similar times for the transmitter. The time that the target is simultaneously above both horizons is the interval (T_1^0, T_2^0) where $T_1^0 = \max (TR1, TX1)$ and $T_2^0 = \min (TR2, TX2)$.

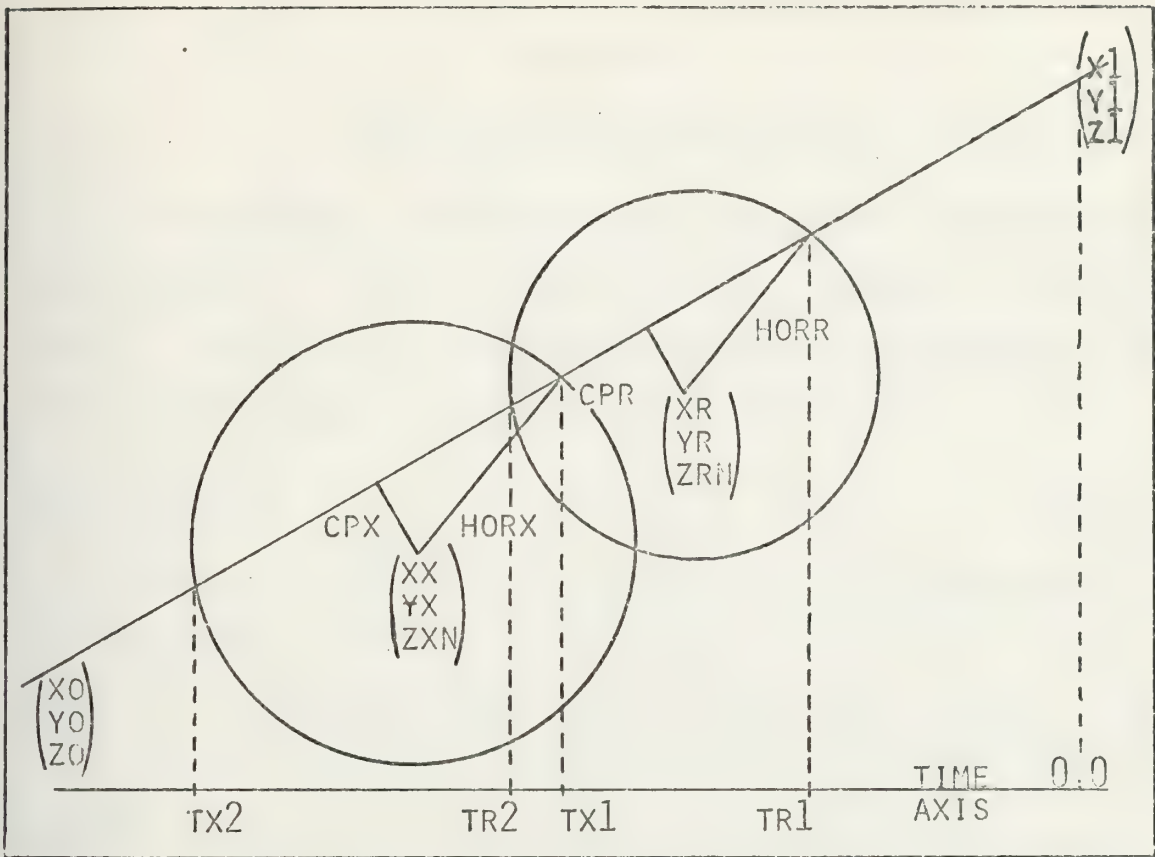


Figure A4
Intersection of the Bistatic Radar Horizons

The intersection of the joint horizon time interval (T_1^0, T_2^0) with the time intervals obtained from the range detection equation provides the time of detection and the time of lost detection for a target.

These times, in conjunction with the ranges which are related to the times, are then used in the simulation to determine "shoot events" for the defensive forces and to accumulate statistics on the detection ranges.

APPENDIX B

DESCRIPTION OF THE PROGRAM

This appendix provides a description of the FADS computer program. The MAIN portion of the program is presented first. The principal subroutines follow with the minor subroutines and functions covered last.

1. OVERVIEW

This paragraph gives an overview of the functions of the individual sections of the program.

- MAIN - The MAIN program reads in the input values, compiles statistics and controls the simulation through the specified number of iterations.
- EFFECT - Subroutine EFFECT controls the individual iteration by selecting the proper subroutine to play the next event in the events list.
- JULIE - Subroutine JULIE initializes or resets values for each iteration.
- EVENT - Subroutine EVENT controls the input and retrieval of events from the events list.
- REMOVE - Subroutine REMOVE retrieves higher priority targets from the events list.
- TARGET - Subroutine TARGET returns all of the "shoot" events which occur at a specified time.
- SUBE1 - Subroutine SUBE1 computes detections of the raiders by the BLUE forces and determines "shoot" events against the raiders.
- SUBE2 - Subroutine SUBE2 computes the RED ASM/SSM launches and subsequent detections followed by the "shoot" events against the ASM/SSMs.
- SUBE3 - Subroutine SUBE3 evaluates the engageability of a target based on the situation at the proposed BLUE missile launch time.

- SUBE4 - Subroutine SUBE4 determines ASM/SSM impacts on BLUE ships and evaluates out of action status for them.
- SUBE5 - Subroutine SUBE5 evaluates the BLUE missile intercepts.
- SUBE6 - Subroutine SUBE6 releases the fire control radar at the time of intercept.
- TIMMY - Subroutine TIMMY computes the predicted intercept point and flight time for the BLUE SAM/SSM and determines whether the intercept is within the missile's capability.
- JAMM - Subroutine JAMM determines the range at which a monostatic radar can detect a target in the presence of jamming.
- BIDET - Subroutine BIDET computes detection ranges and times of detection for bistatic radars in a clear or jamming environment.
- DTIMD - Subroutine DTIMD determines the real and imaginary roots of the fourth order polynomial used to solve for the bistatic radar detection times.
- CPA - Subroutine CPA computes the coordinates of the closest point of approach of a target to a unit.
- REACT - Subroutine REACT computes reaction time delays.
- PRIOR - Subroutine PRIOR determines the most threatening target among those that a defensive system may engage at a given time.
- RCHECK - Subroutine RCHECK evaluates a prospective target ship to determine if the target is above the raider's radar horizon and within the raider's maximum theoretical radar range.
- TMDASM - Subroutine TMDASM determines if and when a RED target will close within a specified range of a BLUE unit.
- TMDBOM - Subroutine TMDBOM determines the time when a RED raider will come within a given range of force center.
- ZLNKA - Subroutine ZLNKA is a sorting routine.
- TJSORT - Subroutine TJSORT is a sorting routine.

- LOCTIM - Subroutine LOCTIM computes the raider position at a given time.
- ASMTIM - Subroutine ASMTIM computes the ASM/SSM position at a given time.
- RANDOM - Subroutine RANDOM generates uniform (0,1) random numbers.
- HISTG - Subroutine HISTG provides a histogram and associated statistics of hits, hit intervals, and hits per minute for a specified BLUE unit.
- DISPL - Subroutine DISPL provides a geographical plot of the BLUE unit positions.
- RADIAN - Function RADIAN converts angles in degrees to angles in radians.
- RAIDIS - Subroutine RAIDIS provides a geographical plot of the RED raider tracks and launch points.
- SETIMX - Subroutine SETIMX provides the internal computer clock time.

2. MAIN

The simulation is initialized by MAIN which also compiles iteration results for the summaries. The MAIN program begins the first of its three principle functions by zeroing specified arrays. It then proceeds to read in the X array, the raider target list assignments (NRTGT), and the target lists (PLIST). The second principle function is to enter those initial values that will remain constant through all iterations into the various tables. MAIN's third principle function is the accumulation and printing of the statistical results.

The initial step in performing the above functions is the zeroing of the X array. In the next step, data are read into the X array by reading data cards in the format

(I10,5F10.3). The information is first read into an integer, IRT, and the array RXATA(5). From there, using IRT as the initial X address, MAIN fills the next five X array slots sequentially. X array addresses that are to remain 0.0 need not be read in unless they are within the neighborhood of the five addresses contained on an input card. In this case they must be specified 0.0. The sequence of reading data cards and filling the X array will continue until a card is read with the value 0 for IRT and 0.0 for the remainder of the card input. This is the flag for MAIN to proceed to the next step.

The program then obtains from the values previously read into the X array the starting values for ISEED, the seed value for the random number generator, and NI, the number of iterations to be played. End of game time is determined and the X array is printed as it was read in. MAIN now computes the weapon (RED ASM/SSM) horizon as follows:

$$\text{HORZ} = (\text{CURVATURE FACTOR}) \times (\text{CRUISING ALT})^{\frac{1}{2}}$$

HORZ is in miles and ALT is in feet. MAIN next converts all courses and bearings from degrees true to degrees in the cartesian coordinate system using the relationship:

$$\text{DEG(C)} = 450. - \text{DEG(T)}$$

All velocities are converted from knots to nautical miles per minute. Jammer and radar beam widths are converted to half beam widths in radians, and MAIN finds the fourth root of the raider and RED weapon radar cross sections. Next the

target list assignments and target lists are read in, and, if X(12) is set, MAIN prints the X-array, PLIST, and NTRGT as read in.

MAIN next fills out the ship table and the raid table. It counts up the number of BLUE missiles (both SAM and SSM) available, and, if X(15) has been set, MAIN prints the converted X array. If X(55) is set, MAIN calls SETIMX to start the internal timer.

MAIN now calls EFFECT to control the first iteration. Upon completion of the first iteration, MAIN prints the ASM table and the SAM-ASM-RAIDER table. It then computes and prints various statistics for this iteration and computes and prints cumulative statistics for all iterations thus far completed. If X(51) is set, the SHIP table is printed at the end of iteration one. If X(52) is set the RAID table is printed and if X(53) is set the SAM table is printed. If X(54) is set, all the random numbers used in the first iteration are printed, in the order of use.

At the end of iteration one, MAIN sets flags 9, 52, 53, 55, 56, 57, 58, 59, and 60 to 0. MAIN then loops back and calls EFFECT to begin the next iteration. Upon completion of the last iteration, additional statistics are printed and the program stops.

3. SUBROUTINE EFFECT

EFFECT controls each iteration. If X(55) is set for debugging, EFFECT calls subroutine GETIMX on entry and exit

to login and logout. EFFECT next calls JULIE to set the tables and arrays that were altered during the previous iteration back to their proper starting values. The simulation begins when EFFECT calls subroutine GETEV for the first event to be played. GETEV supplies EFFECT with the type of event to be played, NEXTEV, the time of the event, and a code identifying the type of event. If the event type returned by GETEV is 0, the iteration is over and the subroutine exits. If the event type is greater than 6, the program prints an error message and terminates. Otherwise EFFECT calls one of the following subroutines to continue the play:

- SUBE1 for a RED raider detection and intercept event.
- SUBE2 for a RED missile launch-target-detect-intercept event.
- SUBE3 for a BLUE missile firing event.
- SUBE4 for a RED ASM/SSM impact event.
- SUBE5 for a BLUE missile kill event.
- SUBE6 for a "set fire control channel free" event.

Upon return from one of the SUBE's, EFFECT again calls GETEV for the next event to be played. Event types used elsewhere in this manuscript correspond to the SUBE subroutine which plays the event.

4. SUBROUTINE JULIE

Subroutine JULIE initializes or resets those items that are required for each iteration. If X(55) is set, JULIE

calls GETIM upon entry and exit. JULIE is called by EFFECT and calls RANDOM, TMDBOM, STOREV, and EVENT.

EVENT is called to zero the events list, and to enter the end of game event into the events list. The following counters are then set to zero; NASM, NSAM, IFAG, IFBG, ITEMS, IFLASK, and IFIRST. The following arrays are zeroed; JAM, IHIT, ISAG, ISBG, STATS, TGTAV, IGAGE, NONO, JACK, and SAMASM. The RAID table and SHIP table are reset and the SAM table is zeroed. The missile batteries are reloaded and, if X(2) is set, the availability of each BLUE radar and launcher is determined. JULIE does this as follows. The first check is on the search radars; if at least one is operating, JULIE determines which fire control radars are operable. If no search radar is available, the program checks to see whether the horizon search mode for fire control radars is authorized, X(7), and if so, whether the ship in question has radars with this capability. If the ship has a search radar and fire control radar combination, or a search radar combined with active, HOJ, ARM, or some other type missile which does not require a fire control radar, the launch availability is checked. If the search radars are inoperative, the fire control radars are horizon search capable, and at least one is operable, the launchers are checked for availability. If the ship has no means of firing or of detection, it is marked a non-combatant and the next unit is evaluated. If the launcher can be coupled with a search/detection/acquisition system, the ship is marked as a G-ship,

the equipment status is entered in the NADAR array, and the next unit is evaluated.

For each RED raider, JULIE calls STOREV to store a type 1 event at time 0., and, if the raider carries ASMs or SSMS, a type 2 event is stored for launch time as determined by TMDBOM.

Finally, JULIE totals the number of BLUE SAM(SSM) batteries available, sets the RELOAD array to zero, and, if X(60) is set, prints the events list.

5. SUBROUTINE EVENT

Subroutine EVENT is called by JULIE. It enters the end of game time in the events list. If X(55) is set, EVENT calls GETIMX upon entry and exit. The event counter LOVER is set to one and the events list is zeroed. End of game time is set equal to the integer IT using the equation:

$$IT = 1000 \times (T + 0.0005)$$

where T is equal to the value stored in X(82). The end of game event, a type 0 event, is then entered in the events list along with the time IT. EVENT then returns to JULIE.

a. Entry GETEV

GETEV is an entry into Subroutine EVENT. It is called by EFFECT and calls GETIMX at entry and exit if X(55) is set. GETEV removes the first entry in the events array, IVENTS (1,1) and IVENTS (1,2), converts these back into event time, type, and participating units, and sends these three pieces of information back to EFFECT. The counter

LOVER is decremented and the entire events list is moved up one position. If the debugging switch X(60) is set, GETEV prints out TIME, NEXTEV, and IUNIT.

b. Entry STOREV

STOREV is an entry in Subroutine EVENT and its purpose is to place the given event in its proper place in the events list. STOREV is called by JULIE, SUBE1, SUBE2, SUBE3, SUBE5, and PRIOR. If X(55) is set, STOREV calls GETIMX upon entry and exit and prints the login/logout time. The inputs to STOREV are the time of the event, the type of event, and the code for the units involved. STOREV first checks to see whether the time the event is to be played exceeds the allotted game time. If it does, STOREV prints a message giving the time of the last event, type of event, and player code. If LOVER is greater than or equal to 1000, the event is lost and STOREV prints a similar message. If both tests are passed, STOREV combines the event type and player code into one 9 digit integer (ICODE). Time is converted to an integer using the same equation as is in EVENT. STOREV places the event in the events array by time. If the time is not unique, it proceeds to compare the stored values of ICODE to the one to be entered. These are ordered from smallest to largest. When the proper place is found, LOVER is incremented, and the remainder of the array is moved up one address. If no place is found to insert the event, including even just right before the end of game event, an error message is printed and the game stops. If the debug switch X(60) is set, STOREV prints the event stored.

6. SUBROUTINE REMOVE

Subroutine REMOVE is called by PRIOR when PRIOR discovers a more threatening target for the missile system being evaluated. If X(55) is set, REMOVE calls GETIMX upon entry and exit. REMOVE receives the code IUNYT from PRIOR. IUNYT is the (event type/player) combination that is stored in the events array. IUNYT was found by TARGET and evaluated by PRIOR as the next event to be played. REMOVE searches the events array for a matching code group. If it finds the group it removes both the code and the time and then moves the remainder of the array up one, and exits. If REMOVE can not find the code, it prints an error message. REMOVE then prints the events array and exits.

7. SUBROUTINE TARGET

Subroutine TARGET is called by PRIOR. Its purpose is to provide PRIOR with all Type 3 events which occur at the present game time. The input for TARGET is time and the outputs are IUNIT and MORE. If IFIRST is equal to zero, TARGET sets it equal to one. TARGET then converts time to the integer format of EVENT and compares it to the time in the array location indicated by IFIRST. If the times are equal, TARGET checks the event code. If it is a Type 3 event, TARGET increments IFIRST, sets MORE equal to one, and exits with the event code. If the times are not equal, or the code is not Type 3, MORE and IFIRST are set to zero and the subroutine exits. If MORE was set to one, PRIOR will

call again until MORE is set to zero. If X(55) is set, TARGET calls GETIMX each time it is entered or is exited.

8. SUBROUTINE SUBE1

SUBE1 is the RAIDER detection subroutine. It is called by EFFECT and in turn calls subroutines CPA, JAMM, STOREV, REACT, LOCTIM, RANDOM, TMDASM, BIDET, and, if X(55) is set, GETIMX on entry and exit. SUBE1 tracks the raider from its start of the game position to its end of game position and determines which BLUE units, if any, will be able to engage the raider. If it is determined an engagement is possible, detection delays, command and control delays, and equipment availability are checked to determine whether or not to enter a Type 3, or shoot, event in the events list array.

SUBE1 first sets flags NASA, NSURF, and NJ. If X(16) is set, SUBE1 checks the ASM counter to see if the BLUE force has been fired upon. If X(16) is set and NASM is zero, SUBE1 stores a Type 1 event at game time plus 2 minutes and then exits. Otherwise, the raider's altitude is checked to determine whether the raider is an aircraft or surface/sub-surface unit, and then the applicable raider characteristics are drawn from the X-array.

Each BLUE ship is next queried to determine whether it can engage the raider. If the ship has been sunk, or if it is a non-missile ship, the NONO table is set to 7 and the next unit is evaluated. The maximum missile range of the operable systems on the BLUE unit is obtained. The distinction between surface and air targets is made by comparing

target altitude to the fifty-foot ceiling for enemy surface units and the fifty-foot floor for enemy aircraft. A missile system must be designated as a surface to surface, or surface to air system when the system characteristics are input. There is no cross matching of systems to targets. SAM's are fired only at aircraft and ASM's, SSM's only at ships.

TMDASM is called to determine whether the target will enter the BLUE unit's missile envelope. If not, the NONO table is set to 9 and the next unit evaluated. If the target will enter the envelope after the end of game time, the NONO table is set to 8.

When it has been determined that the target can be engaged, the target CPA is obtained and the ship's engagement opportunity counter is incremented.

The detection phase begins with a check of the search radars. Each BLUE unit is allowed up to three. If the radar is operable, the clear detection range, jamming environment detection range, combined radar horizon, and theoretical maximum radar detection range are compared. The minimum of these is the radar's detection range for the target in question. This range is compared to that of the other search radars on board, and the maximum is taken as the ship's detection range.

The between radar comparison is made by converting detection ranges into time and adding in the reaction time delays obtained from REACT.

If there is no search radar operational, SUBE1 checks to see whether the target can be detected in the horizon search mode. If there has been no detection and the BLUE unit is operating a bistatic search radar, the subroutine checks to see whether BIDET indicated two detection zones. If so, the search radar portion of SUBE1 is redone using the second bistatic zone. If there remains no detection, or no radar capable of detection, the NONO table is set to 2 and the next BLUE unit evaluated.

Given a search radar detection, SUBE1 proceeds to evaluate the missile systems for fire control acquisition. This is done by obtaining the maximum fire control radar range from among those radars available, and converting this to a time as was done in the search radar algorithm. If the missile of a system requires no fire control radar, the maximum missile range is used as that system's acquisition range.

Having determined the maximum acquisition range, the probability of correct identification is compared to a random number drawn from RANDOM. If the ID check declares the target non-hostile, the NONO table is set equal to 3 and the next BLUE unit is evaluated. Otherwise, the time the target will be acquired is determined by calling TMDASM.

The reaction times for weapons direction equipment delays, target assignment, and acquisition (if the missile requires a fire control radar) are obtained from REACT and added to the search radar detection time. The last time to shoot is determined using the time the target leaves the maximum fire control range, and the SAM/SSM velocity.

The firing delay is obtained from REACT and added to the greater of the detection time and the acquisition time. The "shoot" time is compared to the last time to fire, and if the shot is still possible, the program stores a shoot, Type 3, event for each director-launcher combination in operation. If the missile requires no director, the number 7 is stored as the channel number, and only one shoot event is stored for that system. If the unit requires a director, no channel number is assigned.

If the delays have precluded a firing, SUBE1 checks to see whether there was a second bistatic detection. If so, it returns to the search radar portion of the algorithm and proceeds as above evaluating the second bistatic detection zone. Otherwise it sets the NONO table equal to 5 and processes the next BLUE unit.

The horizon search portion of SUBE1 is entered as described above. The program checks the NADAR table to see if the directors can operate in the horizon search mode. If so, the program proceeds in the same way as the search algorithm, using the fire control radar parameters. Having determined the detection time, the decisional and reaction delays for horizon scan mode are obtained from REACT. The shoot time is determined to be the detection time plus the acquisition time, plus the maximum of the firing time and decision to fire time. A range check is made by calling TMDASM and if the time to fire is less than the last time to fire, a Type 3 event is stored for each director operable in the horizon search mode.

After all the BLUE units have been processed, SUBE1 exits calling GETIMX if flag X(55) has been set.

9. SUBROUTINE SUBE2

SUBE2 is the ASM/SSM launch and detection subroutine. It is called by EFFECT and in turn calls RCHECK, REACT, STOREV, BIDET, RANDOM, TMDASM, TJSORT, CPA, LOCTIM, JAMM, and if X(55) is set, GETIMX on entry and exit.

The inputs to SUBE2 are launch time and raider number. The subroutine first checks the RAID table to see whether the raider has already been shot down or sunk. If so, the subroutine exits. Next the program checks the flag IFLASK to determine whether any RED ASM/SSM's have been fired. If IFLASK is greater than zero, the subroutine proceeds to check whether the launch time is greater than TMAX and exits if it is. If IFLASK equals zero, SUBE2 sets IFLASK to one and TMAX, the time by which all ASM's must be launched, to present time plus X(84). SUBE2 now retrieves the raider speed and, if the raider is an aircraft, determines the ASM launch interval, sets IFLASK equal to 2, and determines the total number of ASM's on board. If the raider is a surface unit; and no ASM's have been fired, IFLASK is set to 0.

SUBE2 determines which of the two possible missile types has the longest firing range, (firing range is measured from coordinate (0,0)). The missile parameters are drawn from the X vector, and the launching sequence begins.

The launching of ASM's is done by drawing a series of uniform (0,1) random numbers, depending upon how many missiles

are to be launched, and ordering them. The exact launch time of each ASM becomes the present time, plus the next random number times the launching interval. The launching of SSM's from surface units begins with the first launch at time plus some portion of the interval specified in X(86). Subsequent surface launches are at fixed increments, X(1809).

Having determined when, and in the case of surface to surface launches, how many RED missiles are to be launched, the targeting phase begins. LOCTIM is called to insert the raider position at launch into the RAID table. The raider target list is located and a temporary target list is constructed. Each ship on the raider's target list is cycled through RCHECK to determine whether it is afloat, above the radar horizon and within radar range. If all these tests are passed, the ship is entered on the temporary target list by putting the values from the original target list in the next slot of the temporary target list. Once the target list has been formed, a random number, Z, is drawn from RANDOM and the first ship with a cumulative probability of being targeted greater than Z is designated the target. If there is none, the first ship on the list is taken. A check is made to see whether this ship has been designated a non-radiating picket. If not, SUBE2 proceeds to the detection phase. If the target chosen is a non-radiating picket, checks are made to see whether the raider can correctly identify the target. This is done by determining whether the raider is within X(23) miles of the target. This

measurement is done in the horizontal plane. If the raider is close enough to the target, RANDOM is called for a random number to compare with the probability of correct identification. If the picket fails to qualify as a target, it is eliminated from the target list and the process starts again. If, at any time the situation arises where there are no targets on a raider's target list, launching stops and an event Type 2 is stored for time plus three minutes.

Upon acquiring a target, the ASM/SSM is considered launched. A random number is drawn and compared to the launch reliability. The ASM table is filled out and, if launch was unsuccessful, the NONO table is set equal to 1 and the next missile processed. Upon an unsuccessful launch, a check is made to see whether there is to be a second SSM in the same salvo. If so, the time is not advanced for this launch.

Assuming a successful launch, the detection phase begins. The target ship's position is stored in the RAID table for use in BIDEF, but otherwise, the detection sequence follows that outlined in SUBE1.

When all of the first type of missiles have been launched, and if the raider is carrying a second type of missile, SUBE2 decides whether or not the raider has reached its second launch point. If so, the appropriate parameters are extracted and the launching continues; otherwise an event Type 2 is stored for the new launch time and the subroutine exits. When there are no second type missiles, the subroutine exits after the last launch.

The exit sequence consists of checking X(58), (if set the NONO table is printed), and X(55), if set, (the exit clock time is printed). The NONO table codes for SUBE1 and SUBE2 are:

- 0 System can engage the target.
- 1 The ASM failed at launch.
- 2 The ship did not detect this target.
- 3 The missile or raider was not identified as a target suitable for engagement.
- 4 The ship can not acquire the target.
- 5 Reaction delay was too long.
- 6 The missile will impact prior to coming into max SAM range.
- 7 Non missile ship.
- 8 Detection will not occur until after end of game.
- 9 Can not engage.

10. SUBROUTINE SUBE3

This subroutine evaluates the engageability of the target in light of the current situation at the proposed launch time. SUBE3 is called by EFFECT, and it in turn calls PRIOR, STOREV, CPA, TIMMY, and, if X(55) is set, GETIMX on entry and exit.

The inputs to SUBE3 are event time and a participant code. The code is an integer of the following type, IIIJJKLM, where III is the target number, JJ is the firing ship, K is the missile system, L the director, and M is the channel number. The subroutine breaks down the code and then checks the appropriate portion of the SHIP table to determine whether the firing ship has been sunk, (if X(5) has been set, this check will indicate the ship has not been sunk

even if it has absorbed more hits than are considered necessary to put it out of action). If the ship has expended the magazine of this missile system, the subroutine exits. Having established the credibility of the firing ship, SUBE3 determines whether the raider has been shot down or sunk, and if so, it exits.

SUBE3 now determines the maximum missile range for the system under consideration and compares this with the raider's CPA. If the target will not enter this maximum missile envelope the subroutine exits. PRIOR is called to determine whether this ship/system/director combination has another shoot event at the present game time and, if so, if that target is more threatening. PRIOR logic will consider the closest target as most threatening. If PRIOR returns the same target, the subroutine continues. If not, it checks out the target as above and exits or continues as appropriate.

If the target has not been destroyed, SUBE3 checks the coordination set-up. If both the fleet and the firing ship are coordination capable, the subroutine checks the target availability. If the target is under engagement, the subroutine calls STOREV to store a Type 3 event at the time the target will become available. If the target remains engageable, SUBE3 checks the NONO table. If the value 0 is found the event continues. If not, the subroutine exits.

The subroutine now goes to the channel assignment phase. If the SAM or BLUE SSM requires no director, channel number

7 has already been assigned in SUBE1 or SUBE2, and the flag ICOT is set to 0. If the missile requires a director for part or all of its flight, and a channel has been assigned on a previous run through SUBE3, the subroutine checks to see whether the assigned channel is busy. If it is, ICOT is set to 1; if not, ICOT is set to 0. If the missile has not been assigned a channel previously, the availability of a channel is checked. A free channel, if found, is assigned and ICOT is set to 0; otherwise a search is made to determine which channel will first become available and this one is assigned. If at this point all channels are busy and the director is required for the full SAM/SSM flight, STOREV is called and a Type 3 event stored for the time the director will become available.

If the systems all indicate they are engaged in an intercept and upon searching the SAMASM and SAM tables no record of this can be found, the program terminates after printing an error message.

SUBE3 now proceeds to check whether the firing ship itself is engaging the target. If it is the subroutine exits. If the target is an ASM or SSM, the subroutine checks to see that the target will not impact prior to BLUE missile launch. If it will, the program exits.

At this point, if ICOT equals 1, the channels were all considered busy and the BLUE missile only requires the director for terminal homing. SUBE3 checks the SAMASM listing to determine when the channel will be available and stores a Type 3 event.

If ICOT equals 0, SUBE3 calls TIMMY to determine the intercept position, single shot kill probability, SAM/SSM flight time, and the intercept possibility given the BLUE missile flight and warhead characteristics. If TIMMY returns the possibility flag -1, the intercept is not possible, but may be in the future. SUBE3 stores a Type 3 event for present time plus six seconds. If the indicator is zero, the intercept is not and will not be possible, and the subroutine exits. If the indicator is one, the intercept is now possible and the program continues. If the intercept was possible, but the intercept point was in the hazard zone of another BLUE unit, TIMMY returns the indicator two. In this case, SUBE3 again stores a Type 3 event for present time plus six seconds.

If the SAM/SSM requires the director for only the terminal phase of flight, SUBE3 determines whether the director can be scheduled for the intercept. If not, the subroutine stores a Type 3 event for the time the director will be free, minus flight time, plus terminal homing time, plus 0.06 seconds.

If scheduling is not needed, or the director will be available when needed the missile is considered launched. The SAM-ASM-RAIDER and SAM tables are filled in and missiles on board and in the fleet counters are decremented. If there is coordination, and the firing ship is coordination capable, the target availability is up-dated. The launcher reload time is determined and stored. The channel

availability indicator is set to 1 and a Type 5 event is stored for intercept time.

Prior to exit, if X(9) is set, SUBE3 prints out the firing ship number, the target number, and the reason for exiting the subroutine are printed. The breakdown for the REASON code for SUBE3 follows:

- 0 Blue Salvo fired.
- 1 Firing ship sunk or out of action.
- 2 Target being engaged.
- 3 Target already destroyed.
- 4 Firing ship out of missiles.
- 5 Director required for entire missile flight and is not available.
- 6 Firing ship already engaging the target.
- 7 Missile requires director only part time but all channels are busy.
- 8 NONO table prohibits engagement.
- 9 Launcher not available.
- 10 ASM will impact prior to SAM launch.
- 11 Director cannot be scheduled for the intercept.
- 12 Director operation in horizon scan mode, busy.
- 13 Target will not close BLUE missile envelope or TIMMY indicates no intercept.
- 14 TIMMY indicates target may enter envelope later.
- 15 TIMMY indicates target intercept point is too close to another BLUE unit.

11. SUBROUTINE SUBE4

SUBE4 determines whether the RED missile failed in flight, and if not, increments certain counters indicating ship hits and possible sinking. SUBE4 is called by EFFECT and it in turn calls RANDOM, and, if X(55) is set, GETIMX on entry and exit.

SUBE4 first breaks down the input code into the RED ASM/SSM number, and the BLUE target ship number. The code enters SUBE4 as the integer RRRBB. It then checks to see whether the ASM/SSM has been shot down, or had its launch negated due to the loss of the launching raider prior to the actual missile launch time. If neither is the case, the probability of successful flight is drawn from the X array and RANDOM is called to produce a random number. If it is determined that a failure occurred, the ASM table is set to 3 and the subroutine exits. Otherwise the target ship is assumed to have been hit and the appropriate counters are incremented. If X(5) is not set, the subroutine compares the number of hits taken to the amount of damage the ship can withstand, and if too many hits have been taken, declares the ship sunk.

12. SUBROUTINE SUBE5

SUBE5 evaluates the BLUE missile intercept and performs checks on other ASM/SSM if the target shot down or sunk was a RED raider. SUBE5 is called by EFFECT and it in turn calls STOREV, REACT, RANDOM, and if X(55) is set, GETIMX on entry and exit.

SUBE5 is called with an input variable of salvo number. Using this, SUBE5 gets the target number, firing ship number, missile system, director, and channel number from the SAM-ASM-RAID table. The director reassignment and reacquisition delays are determined and stored, fleet and individual ship

statistical data are taken, and a check is made to insure that the target is still engageable. If the target has already been sunk or shot down, the SAM-ASM-RAID table is set to -1, indicating an overkill. If the target is an ASM/SSM that failed in flight or has already impacted, the salvo is determined to have been a failure and the SAM-ASM-RAID table is set to zero. If the target is engaged, the probability of BLUE missile successful flight and support is pulled from the X array, and the single shot kill probability is removed from the SAM-ASM-RAID table. RANDOM is called to provide a random number. Success is determined by comparing PK to the random number drawn. This is done by determining PK as follows:

$$PK = PS \times (1 - (1 - PKSS)^N)$$

Where PS is the probability of successful flight, PKSS is the single shot kill probability, and N is the number of BLUE missiles in the salvo. If the random number is less than PK, the shot was successful. If the shot was unsuccessful and the missile requires a director, the channel is released and Type 3, shoot, event is stored for present game time. If the missile doesn't require a director, just the shoot event is stored, and the subroutine exits.

If the shot was successful and the target was an ASM/SSM, the SAM, SAM-ASM-RAID, ASM, and kill counters are updated, a Type 6, channel free, event is stored, and the subroutine exits. If the target destroyed was an aircraft, or if the number of hits has been sufficient to disable a

surface raider, the following steps are taken prior to the regular table update and exit. A check is made to determine whether the raider has any ASM's or SSM's aboard. If so, the ASM counter is incremented and the appropriate numbers are entered in the ASM table indicating that these missiles were lost with the launching platform. Next the ASM table is checked to locate any missiles launched by the raider just destroyed. When one is found, its launch time is compared to raider kill time, and if the launch time is greater, entries are changed in the ASM table to correspond. Upon completing the search, the program continues to exit where it checks X(55), X(56), and X(58) for debug output.

13. SUBROUTINE SUBE6

SUBE6 releases the fire control radar channel at the time of the event. SUBE6 calls GETIMX upon entry and exit if X(55) is set.

The input value to SUBE6 is an integer code AABCD, where AA is the firing ship number, B is the missile system, C is the director number, and D the channel number. After breaking down the code, SUBE6 sets the appropriate portion of the CHANEL array to zero, and exits.

14. SUBROUTINE TIMMY

TIMMY computes the predicted intercept point and flight time for the BLUE SAM/SSM and determines whether the intercept lies within the intercept contour. TIMMY is called by SUBE3 and TIMMY in turn calls TMDASM, ASMTIM, RADIAN, ZLNKA, LOCTIM, and if X(55) is set, GETIMX on entry and exit.

Inputs to TIMMY are target number, firing ship number, missile system number, present target position, and present game time. Outputs are single shot kill probability, flight time, and an indicator flag which says the intercept is possible, is not and will not be possible, or is not but may be possible in the future.

Using the target number, TIMMY decides whether the target is a raider or an ASM/SSM and determines the end of game position for raiders and target ship position for an ASM/SSM. If X(8) is set, firing sectors have been assigned and TIMMY checks to ensure that the assigned firing sector and the launcher train limits permit a launch. If launch is prohibited, REASON is set to 2, flag IND is set to zero, and the subroutine exits. If the launch is possible, there may be as many as two firing zones. These two occurrences are shown in Figure B1.

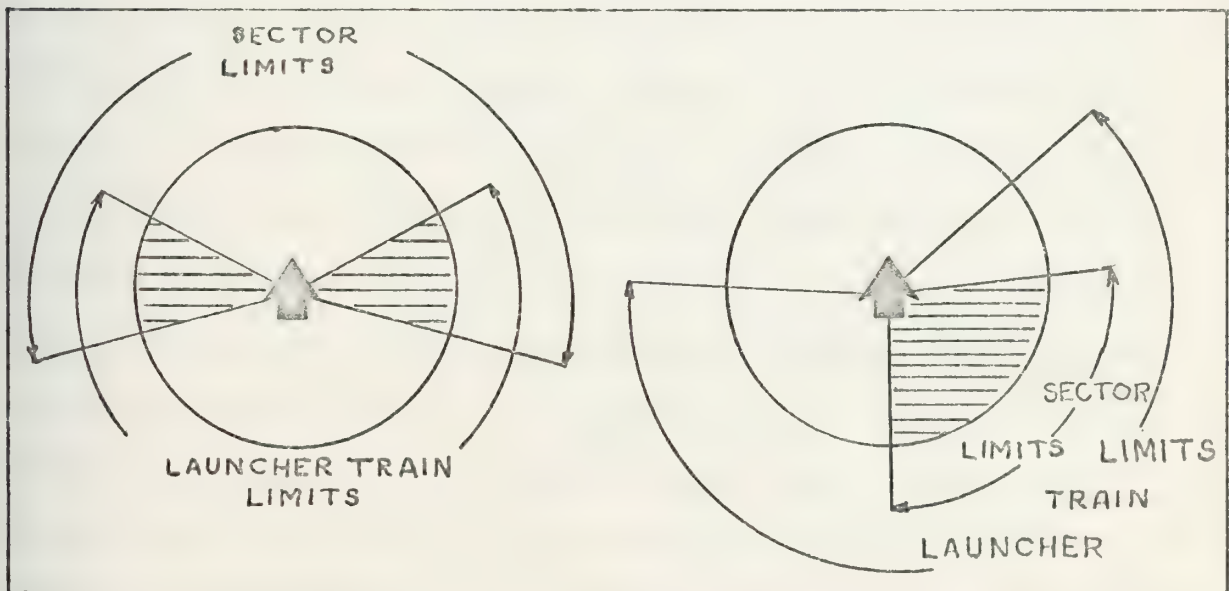


Figure B1

One or Two Firing Zones

Using the results of the ZLNKA reordering of the sector limits and launcher train limits, TIMMY determines whether there are two zones or one, and which of the bearings constitute the actual firing zone, or zones, limits. If no sectors have been assigned to the fleet, or this unit, the firing zone limits coincide with the launcher train limitations.

TIMMY next checks target altitude against the maximum SAM altitude. If the target is too high, REASON is set to eleven and the subroutine exits. Otherwise, the intercept parameters are determined. These intercept parameters are the values entered into the X-array that approximate the actual intercept contour. The intercept parameters are A, B, N, SLOPE, and SEEK. The actual intercept contour depends on target size, speed, and altitude as well as missile parameters. There are usually more than one contour for any given missile system. The actual contours are found in the various technical publications dealing with the specific missile. OP-3594, Performance and Installation Characteristics Surface Missile Weapon Systems, also contains general contour nomograms, and the Applied Physics Laboratory of Johns Hopkins University has developed computer simulations which generate contours. A typical contour, along with the TIMMY approximation, is shown in Figure B2. A is the off-range capability, B is the down-range capability, and N is a degree of curvature.

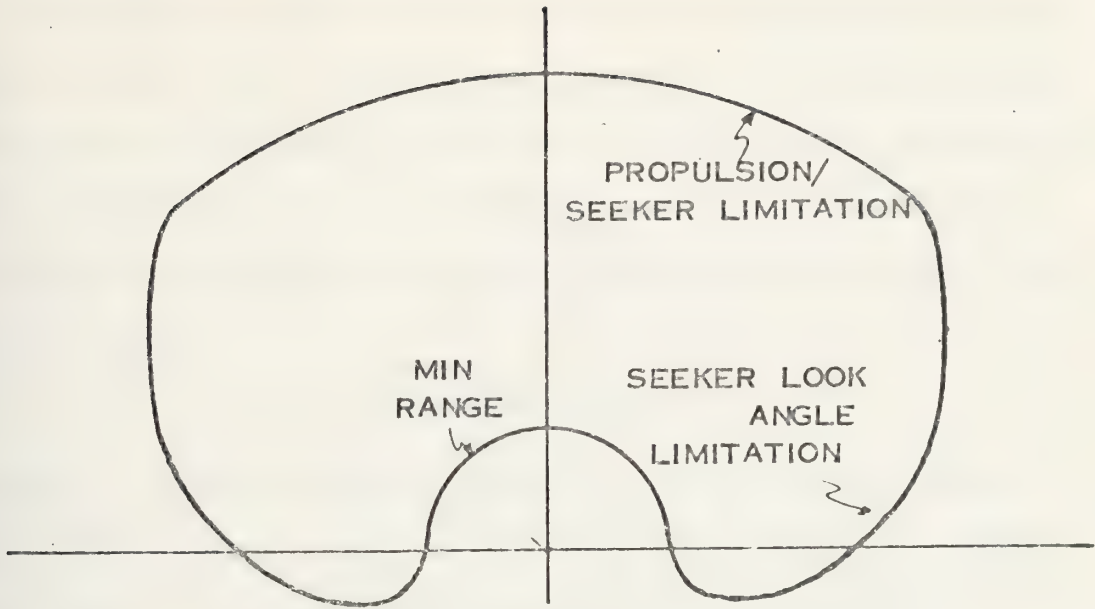


Figure B2a
The Actual Intercept Contour

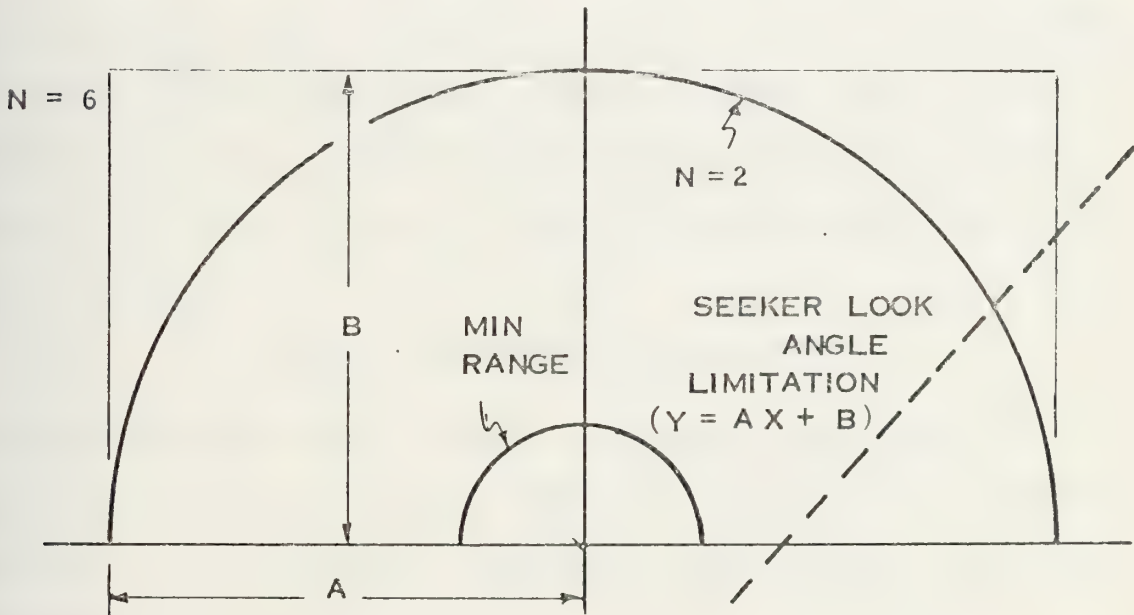


Figure B2b
The Approximation of the Contour

The maximum missile range for the given target altitude is determined, and if the target will not enter this range, as determined by TMDASM, TIMMY exits after setting REASON to seven. If the target is an ASM/SSM and the target ship is the firing ship, target course is found and SAM flight time is determined by:

$$FT = DLT / (SSPD + VEL)$$

where DLT is the distance between the firing ship and the target, SSPD is the speed of the SAM, and VEL is the speed of the target. In this case the PK that is returned to SUBE3 is that for a non-crossing target.

If the target ship is not the firing ship, or the target is a raider, the following angles are determined: ALPHA, the angle between the target flight path and the line of sight at launch, and THETA, the angle in Cartesian coordinates of the present line of sight. The quantity GSINE is determined by:

$$GSINE = \sin(\text{ALPHA}) * (VEL / SSPD)$$

If the absolute value of GSINE is greater than one, the intercept is impossible and TIMMY exits after setting REASON equal to ten. Otherwise, the angles GAMMA, BETA, and DELTA are computed.

$$\text{GAMMA} = \arcsin(\text{GSINE})$$

$$\text{BETA} = 180^\circ - \text{GAMMA} - \text{ALPHA}$$

$$\text{DELTA} = 180^\circ - \text{BETA}$$

GAMMA is the angle between the SAM/SSM flight path and the line of sight, BETA is the angle between the SAM/SSM flight path and the target flight path, and DELTA is the compliment of BETA. If X(59) is set, the values for target number, firing ship number, ALPHA, BETA, GAMMA, present target position, GSINE, and present range to the target are printed. PK for this type of target is determined by DELTA. If DELTA is greater than 45°, the target is declared a crossing target and the appropriate PK is retrieved from the X-array. Otherwise, the probability of kill for a non-crossing target is retrieved. Flight time is determined by:

$$FT = DET * SIN(ALPHA)/(SSPD * SIN(BETA))$$

Using present time plus flight time for the input, TIMMY now calls LOCTIM or ASMTIM, as appropriate, to determine the intercept coordinates. The range to the intercept is computed and compared to the minimum missile range. If the range is too short, IND is set to minus one, REASON to four, and the subroutine exits. The launch bearing is calculated and the first of two possible sets of firing zone bearings are compared to determine whether the launch bearing is within the firing bearings. If it is not, TIMMY checks to see if there was a second firing zone, if so it checks this one, otherwise, IND is set to minus one, REASON to three, and TIMMY exits. If the intercept angle is good, the intercept parameter is checked. A, B, and N are combined to form the equation:

$$(X/A)^N + (Y/B)^N = 1$$

A value of two for N results in a circle or an ellipse. A value of six results in a near rectangle. Fractional values for N are permitted.

The "ellipse" is translated so that its center is on the firing ship, and rotated so that the positive Y axis is opposite to the line of flight of the target. The intercept coordinates are substituted into the equation, in absolute value, and if the resulting number is less than or equal to one, the intercept will be within the ellipse. The next check is the seeker limit test. The y intercept value and the absolute value of the x coordinate are entered into the equation:

$$Z = YI - SLOPE * XI$$

If Z is greater than or equal to SEEK, the problem continues. If not, TIMMY exits after setting REASON to six. The subroutine now checks the X-vector to determine whether there are any restrictions on how close an intercept can be to another friendly unit. If there are, the hazard zone is constructed. If the intercept falls within the hazard zone, REASON is set to nine, IND is set to two, and TIMMY exits.

If the problem has progressed this far, the intercept is considered possible and the BLUE missile salvo is launched while IND is set to one. If the target is an ASM/SSM and the firing ship is the target, the program exits. If not, the target altitude is figured into the flight time prior to return to SUBE3. If X(9) is set, TIMMY prints out the ship number, target number, IND value, and REASON prior to exit.

Reason codes as used in TIMMY

- 1 Not used.
- 2 No firing zones for this system.
- 3 Firing bearing outside sector.
- 4 Target too close.
- 5 Target intercept point outside engagement contour.
- 6 Target beyond seeker limits.
- 7 Target beyond range and outbound.
- 8 Intercept after ASM/SSM impact.
- 9 Target too close to BLUE unit at intercept.
- 10 GSINE greater than one.
- 11 Target too high.

15. SUBROUTINE JAMM

The subroutine JAMM determines the range at which a monostatic radar can detect a given target in a multiple standoff and self-screening jamming environment.

The calling routine, either SUBE1 in the case of raiders, or SUBE2 in the case of missiles, first determines that there are jammers in the problem and that at least one jammer is on the same frequency band as the detecting radar. If both situations obtain, subroutine JAMM is called.

JAMM initially checks to see if the target will close the detecting unit within the minimum of the clear environment, radar horizon, and theoretical range of the radar. If the target will not close within this minimum range, the subroutine is exited with a flag set to show that detection would not occur. In the case where the target will enter this minimum range, JAMM computes the time at which the target will arrive at the closest point of approach (CPA) to

the detecting radar. Appropriate checks are made for stationary targets and targets with only minor changes in their X or Y position components. JAMM next obtains the bearing from the radar to the target at the CPA position for use in selecting the appropriate side-lobe coefficient. Individual radars are then checked to see if they have been shot down prior to the target arriving at CPA (applicable only for missile detections), if they are jamming on the frequency band of the detecting radar, and if they are above the detecting radar's horizon. If all of the conditions are met, the bearing from the jammer to the jammer's jamming target is found in order to determine whether the detecting radar is within the main beam or the side-lobe of the jammer.

The jamming power arriving at the radar from the individual jammer is then computed, taking into consideration the power of the jammer, the range from the jammer to the detecting radar, and the side-lobe/main beam relationship between the detecting radar and the individual jammer. The jamming power arriving at the detecting radar is then summed over all of the jammers and used to compute the burn-through range for the radar against the specified target. Prior to exiting the subroutine, the range to the target's CPA to the detecting radar is checked to ensure that it is less than the burn-through range. If the distance to CPA is greater than the burn-through range a flag is set indicating that detection did not occur due to CPA considerations. Otherwise the subroutine returns as the detection range the minimum of the clear, jamming, radar horizon, and theoretical ranges.

16. SUBROUTINE BIDET

This subroutine computes the number of detection zones, ranges, and times of detection for a bistatic radar in either a clear or jamming environment. BIDET is called by SUBE1 and SUBE2, and it in turn calls GETIMX on entry and exit if X(55) is set.

BIDET begins by setting the initial values of aircraft/ASM start position, final position, altitude, and velocity. The transmitter and receiver positions and radar antenna height are established for the bistatic system under consideration. A check for non-moving targets is conducted prior to entering the closest point of approach (CPA) routine. In the case where the target has moved less than 0.1 nautical mile in both the X and Y direction, the target's speed is considered to be zero and the target enters a special loop to determine whether it is detectable at its initial position within the constraints of both radar horizon and radar signal strength.

For the moving target, the CPA of the target's projected track to the transmitter is determined by solving simultaneously the equations of the target's track and the line perpendicular to the target's track and passing through the transmitter location. The CPA to the receiver is solved in a similar manner. If movement in either the X or Y directions is less than 0.1 nautical mile, the CPA is established by setting the CPA coordinate for the small changing axis to the target's original position corresponding coordinate and

the alternate coordinate to the corresponding alternate coordinate of the transmitter or receiver. For example, if the X coordinate of the target's positions changes less than 0.1 nautical mile, the CPA to the receiver is set to the X coordinate of the target's initial position and the Y coordinate of the receiver's position.

The radar horizon for the transmitter and the receiver are then compared to the distance to their respective target track CPAs to determine whether the target enters the radar horizon of both the transmitter and the receiver. If it fails to enter both, the routine is exited with a no detection. Otherwise, the times that the target first appears above and disappears below the transmitter and receiver radar horizons are computed. The time interval that the target is simultaneously above both horizons is determined by taking the maximum of the appearance times and the minimum of the disappearance times. If the target is never simultaneously above both horizons; or the appearance time is greater than maximum game time; or the disappearance time is prior to start of game time, the subroutine is exited with a no detection.

Next, detection times for the target based on radar signal strength are computed, and the intersection of these time intervals with the above joint radar horizon time interval determines the time during which the target is detected. No detection occurs if the intersection of the two time sets (i.e. radar strength detection and radar horizon detection) is the null set.

If a detection has occurred in the clear environment, the subroutine checks to see whether any jammers are in use and if they are on the same frequency band as the bistatic radar. If jammers are in use, the time that the target arrives at its midpoint in the bistatic detection envelope is determined. This time is used in arriving at an average jammer position to compute the jamming power at the radar during the detection phase. This will tend to provide a somewhat conservative estimate of detection ranges in the face of jamming because the jammers are in general going to be nearer to the radar and the range square losses of the jamming power will be reduced. In the case of the stationary target, midpoint time is set to an arbitrary three minutes after start of game time to allow for some movement of the jammers toward the force. The subroutine then adds the jamming power from each jammer. It does this by checking all of the raiders to determine if the individual raider has been shot down prior to the midpoint time, and if the jammer is above the radar horizon and is jamming on the frequency band of the radar. If these conditions are met, the subroutine examines the geometry of the jammer's position and the radar to determine the relationship between the jamming and radar antennas. With this relationship, the appropriate side-lobe/main beam antenna coefficients are used to adjust the jamming level.

The constant in the bistatic range equation is then adjusted to reflect the jamming environment and the computation

previously conducted in the clear environment are repeated to determine whether detection will occur in the jamming situation.

The subroutine exits with the number of detection zones which occurred; the time and range of initial detection in the first zone, the time of last detection in the first zone; and, if applicable, the time and range of first detection in the second zone along with the time contact is lost in the second zone.

17. SUBROUTINE DTIMD

Subroutine DTIMD is a double precision subroutine that determines the real and imaginary roots of the fourth order polynomial which is used to solve for the bistatic radar detection times. The subroutine employs the Newton-Raphson iterative technique with the final iteration on each root performed using the original polynomial rather than the reduced polynomial to avoid accumulated errors in the reduced polynomial. The subroutine was obtained from the Naval Postgraduate School Computer Center library.

18. SUBROUTINE CPA

Subroutine CPA obtains the closest point of approach of a target's track to a reference point by solving the simultaneous equations of the line representing the target's track and the line through the reference point and perpendicular to the target's track. Checks are conducted for target tracks which pass through the reference point,

represent stationary targets, or targets which have only minor changes in either the X or the Y direction.

19. SUBROUTINE REACT

Subroutine REACT allows the use of reaction time delays through the use of probability distribution functions. This subroutine is similar to, if not identical to, one developed for use in FLOATS by APL at the Johns-Hopkins University. The distribution functions may be entered for seven classes of delay. They are:

- 1 Target detectability to actual detection.
- 2 Detection to ID and designation to the weapons direction equipment.
- 3 Director assignment delay.
- 4 Director acquisition delay.
- 5 Firing delay.
- 6 Target detectability to detection for horizon scan mode.
- 7 Decision delay in horizon scan mode.

Within these class areas, up to five separate types may be designated. REACT uses the type and class numbers to determine a delay time which it returns to the calling subroutine. REACT is called by SUBE1, SUBE2, and SUBE5.

REACT in turn calls only RANDOM.

The inputs to REACT are the class number and type, and the output is the delay in minutes. The class number is used to locate that portion of the X-array where the delay is stored. The type number is used to localize the address within the area. In employing its Monte Carlo technique, REACT calls RANDOM and converts the returned uniform (0,1)

number to an integer. If this integer is 10, the subroutine sets it equal to 9. If the integer is zero, the RANGE, defined as the difference in time between two adjacent blocks, is set equal to the value in the first block. Otherwise, the address is determined using the class and type numbers and then adding on the integer. The delay consists of two parts. The first part is the time in the address block. The second part is determined by drawing another random number and multiplying it by RANGE. Except in the case where the integer is zero, RANGE is determined by subtracting the time in the address block from that in the next highest block. In the "zero" case, the total delay consists of this fraction of RANGE. In all other cases, the fraction of RANGE is added to the time stored in the address block to obtain the total delay. At this point REACT returns to the calling routine.

As an example of a distribution function, consider the waiting time for an aircraft for a catapult launch. Data is available for one hundred aircraft. The maximum waiting time was seven minutes. The distribution of waiting times was as follows:

<u>length of wait</u>	<u>0-1</u>	<u>1-2</u>	<u>2-3</u>	<u>3-4</u>	<u>4-5</u>	<u>5-6</u>	<u>6-7</u>
frequency	10	40	15	15	5	5	10

Figure B3
An Example of Waiting Time

The plot of length of time waiting against number of occurrences would look like this:

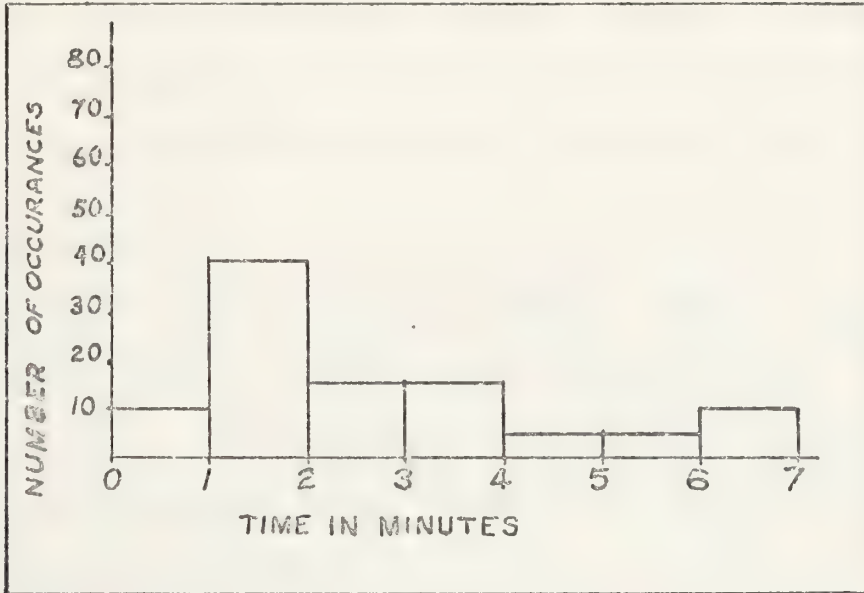


Figure B4
Histogram of Waiting Times

The probability of waiting between 0.0 and 1.0 minutes is 0.1, the probability of waiting between 1.0 and 2.0 minutes is 0.4. When the histogram is transformed into a cumulative probability distribution function, the following results.

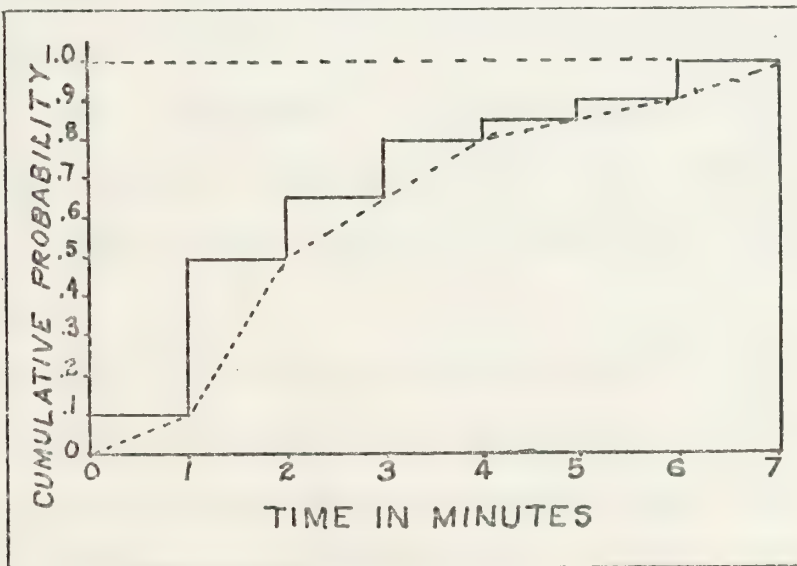


Figure B5
Cumulative Distribution Function of the Waiting Times

This distribution is what is entered in the X-array. The first block would contain the time for .1 cumulative probability. This would be one minute. Block two that for .2 cumulative probability, or 1.25 minutes, and so on up to block ten which would have entered a seven for seven minutes.

20. SUBROUTINE PRIOR

Subroutine PRIOR is called by SUBE3. PRIOR calls REMOVE, STOREV, LOCTIM, ASMTIM, TARGET, and if X(55) is set, GETIMX on entry and exit. The purpose of PRIOR is to determine the most threatening target among those that a system may choose from at present game time.

PRIOR first computes the value CHECK for the target being compared. CHECK is defined as maximum missile system range divided by present target range. TARGET is called to provide PRIOR with a candidate for comparison. The same measure of threat is obtained for the candidate target and stored in CHERRY. If the present value in CHECK is greater than or equal to CHERRY, PRIOR goes to the next candidate, if there is one. If CHERRY is greater than CHECK, the values of target number, channel number, and target position are saved. CHECK is made equal to CHERRY and PRIOR seeks a new comparison.

If the value returned by TARGET in MORE is not zero, there is another candidate to be evaluated. If MORE is zero, there are no more comparisons to make and the final section of PRIOR is entered. The stored value of most threatening target number is compared with the target sent to PRIOR

originally from SUBE3. If they are the same, the subroutine exits. If PRIOR has found a more threatening target, REMOVE is called to take the type 3 event associated with the new target out of the events list. STOREV is then called to enter a type 3 event for the target being intercepted.

The debug switch X(9) is checked at exit and if it is set, old target, new target, missile system (in the code AABC were AA is ship number, B is system number, and C is director number), old channel, and new channel are printed. X(55) is checked and PRIOR returns to SUBE3.

21. SUBROUTINE RCHECK

Subroutine RCHECK evaluates the prospective target ship to determine if the raider can in fact "see" the target. RCHECK is called by SUBE2 and RCHECK calls GETIMX on entry and exit if X(55) is set. The inputs to RCHECK are the raider number and proposed target ship number. The two dimensional distance between the two units is computed. The antenna heights on the target ship are compared and the tallest one is used to determine the ship's radar horizon. If the ship has no radar, a height of 15 feet is entered. The combined radar horizons, maximum theoretical radar range of the raider's radar, and the actual range are compared. If the target is within both the radar horizon and the maximum radar range, the go/nogo flag is set to zero. If either test fails, the flag is set to one and the subroutine exits.

22. SUBROUTINE TMDASM

This subroutine determines if the target, or other unit in question, will enter within a certain input range of a BLUE unit, and if so, at what time will it enter and leave. TMDASM is called by SUBE1, SUBE2, and TIMMY. TMDASM in turn calls GETIMX on entry and exit if X(55) is set.

TMDASM begins by determining the range from the reference ship to the target unit. If this range is less than or equal to the input range, the time of entry is considered to be the input time. If the range to the target unit is greater than the input range, TMDASM determines the slope of a line representing target unit movement. Using this and the present target unit position as a reference point, TMDASM forms the line equation. This equation and the equation for a circle with radius equal to the input range are solved simultaneously to determine the points of intersection. This is done by substituting the line equation into the circle equation and solving the quadratic equation. If the roots are imaginary or equal, the entry is either not made or the length of stay is infinitely small. These cases are rejected as no solution. Upon finding two real roots, the subroutine determines which of the two points the target unit would reach first, and which one it would reach second. If the target unit is already further down its track than the exit point, no entry is indicated. Otherwise the time of leaving the circle is determined and, if the target unit was not already inside the circle, the time of entering.

23. SUBROUTINE TMDBOM

This subroutine determines when the raider in question will reach a given range from the force center, position (0,0). TMDBOM is called by MAIN, and JULIE. TMDBOM in turn calls GETIMX on entry and exit if X(55) is set.

TMDBOM proceeds in the same way as TMDASM except that the reference position, center of the range circle, is always force center instead of a firing ship. TMDBOM only computes the time that the raider will cross a given range. It neglects the departure time.

24. SUBROUTINE ZLNKA

Subroutine ZLNKA is a copy of the subroutine SHSORT, mentioned below, as it existed on 1 February 1975. ZLNKA inputs a vector of real numbers and an ordered vector of integers. ZLNKA reorders the real vector from smallest to largest and reorders the integer vector to the same order as the real vector. ZLNKA is called by TIMMY.

25. SUBROUTINE TJSORT

Subroutine TJSORT is a modification of the subroutine SHSORT which is available from the Naval Postgraduate School Computer library. TJSORT is called by SUBE2, and BIDET. This subroutine inputs a vector of real numbers and rearranges them from smallest to largest.

26. SUBROUTINE LOCTIM

LOCTIM computes the raider position at time T. It is called by MAIN, SUBE1, SUBE2, SUBES, JAMM, BIDET, TIMMY, and PRIOR. LOCTIM in turn calls GETIMX on entry and exit if X(55) is set.

LOCTIM first determines raider velocity and the time of the raider position stored in the RAID table. The distance the raider travels between the present time and the stored time (DL) is computed. If the velocity is zero, present target position is set to the initial position and the program exits. The distance between the stored position and the end of game position (D) is determined and the ratio DL/D is computed. The X,Y position at the time desired is determined by:

$$XP = XZ - \Delta X * DT$$

$$YP = YZ - \Delta Y * DT$$

where

XP is the X position at the time of interest

YP is the Y position at the time of interest

XZ is the stored X position

YZ is the stored Y position

ΔX is the distance between XZ and the end of game position

ΔY is the distance between YZ and the end of game position

DT is the ratio DL/D

If the input flag IND has been set to 5, the new time and position are stored in the RAID table, otherwise the subroutine exits.

27. SUBROUTINE ASMTIM

ASMTIM computes the ASM/SSM position at time T. It is called by SUBE3, TIMMY, and PRIOR. ASMTIM calls GETIMX on entry and exit if X(55) is set.

The logic of ASMTIM is identical to that of LOCTIM but the definition of variables has been changed.

XZ becomes the ASM/SSM X launch coordinate

YZ becomes the ASM/SSM Y launch coordinate

ΔX becomes the distance between the launch position and the X coordinate of the target ship

ΔY becomes the distance between the launch position and the Y coordinate of the target ship

The ASM/SSM position is now computed in the same manner as in LOCTIM and the subroutine exits. The positions are not saved by ASMTIM.

28. SUBROUTINE RANDOM

Subroutine RANDOM is a generator of Uniform (0.0, 1.0) random numbers. It was programmed by Gerald P. Learmouth, of the W.R. Church Computer Center, Naval Postgraduate School. The following is taken from the library description of the subroutine:

"The basic generator is a Lehmer congruential of the form:

$$X(N) = A * X(N-1) \text{ MOD } (P)$$

where $A = 7^{**}5 = 16807$ and $P = (2^{**}31)-1$. The resulting $X(N)$'s are uniformly distributed random integers between 1 and P . The uniform REAL*4 numbers are formed by right-shifting the integer $X(N)$ and appending a proper floating point exponent to form a number between 0.0 and 1.0."

29. SUBROUTINE HISTG

Subroutine HISTG is found in the subroutine library of the Naval Postgraduate School subroutine library. A copy of HISTG has been included at the end of the program. The subroutine is used if the user wants a statistical display of the number of hits a certain specified BLUE unit will take. Also provided is a statistical display of the time interval over which the RED missiles arrive, and one of the hits per minute. A histogram of the selected parameter is provided in all cases. HISTG is called by MAIN just prior to run completion if X(85) has been set and the conditions detailed in section V.B have been met.

30. SUBROUTINE RAIDIS

This subroutine provides a plot of the raider tracks from their initial position to launch position. The maximum size of the plot is 800 nm from force center. In the case where a raider does not launch weapons, the 30 minute game time position is used as the terminal point of the track. If the launch or 30 minute position is more than 800 nm from force center, a label of "no launch" is displayed at the raider's initial position.

31. SUBROUTINE DISPL

DISPL is similar to RAIDIS except that the BLUE unit positions are plotted and they must be within 200 nm of force center. A 100 nm range circle is included in the display.

32. SUBROUTINE SETIMX

This subroutine sets the internal clock to zero. The entry GETIMX gives the internal clock time when called.

33. FUNCTION RADIAN

The function RADIAN converts degrees to radians. It is called by MAIN, JULIE, and TIMMY. The conversion is done with:

$$\text{RADIAN} = \text{RD} * 0.017453293$$

where RADIAN is the output angle in radians and RD is the input angle in degrees.

APPENDIX C

RADAR DETECTION RANGE INPUTS

This appendix provides the equations used to determine the β and α inputs for the individual radar classes.

1. CLEAR ENVIRONMENT

β is the range at which a one square meter target can be detected in a non-jamming environment. It is a constant of the radar system and in the monostatic case provides the range of detection for the radar by the relation:

Range = $\beta(\sigma)^{\frac{1}{4}}$ where σ is the target's radar cross section.

The general equation for β is:

$$\beta = \left[\left(\frac{P_t}{P_m} \right) \frac{G^2 \lambda^2}{(4\pi)^3} \right]^{\frac{1}{4}}$$

where P_t is the power of the transmitter in watts; G is the antenna gain coefficient; λ is the radar wave length in meters; and P_m is the minimum detectable signal of the radar with appropriate consideration for probability of detection and propagation losses. If the above units are used in calculating β , the result will be a detection range in meters which must be converted to nautical miles for use in the simulation. Values of β , in nautical miles for a one square meter target, are reported in Ref. 9 for standard U.S. Navy radar systems.

In the case of the bistatic system, the equation for β becomes

$$\beta = \left[\left(\frac{P_t}{P_m} \right) \frac{G_t G_r \lambda^2}{(4\pi)^3} \right]^{\frac{1}{4}}$$

where the possibility of different gains of the transmitter and receiver must be considered and the propagation losses in P_m must take into consideration the differences in the transmitter to target path and the target to receiver path. Additionally, in the bistatic situation, the detection range is not only a function of the range from the receiver (R_r) to the target but it is also a factor of the range from the transmitter (R_t) to the target. Thus the bistatic range equation becomes

$$R_t R_r = \beta^2 \sigma^{\frac{1}{2}}$$

The monostatic radar cross section provides a suitable estimate for the bistatic radar cross section [Ref. 10, p. 592].

2. JAMMING ENVIRONMENT

α is the range at which a one square meter target can be detected in a jamming level of one watt/mhz. The burn through range for a monostatic radar in a multiple-standoff jamming environment is:

$$R_{bt} = \alpha^{\frac{1}{2}} (\sigma/SJP)^{\frac{1}{4}}$$

where σ is the target's radar cross section and SJP is the sum of the jamming power arriving at the radar. The jamming power from an individual jammer on the radar's frequency is

a function of the power of the jammer; the side-lobe/main beam relationships between the jammer and the radar; and the square of the range from the jammer to the radar. The equation is:

$$SJP = \sum_i C_i JP_i / R_i^2$$

where C_i is the side-lobe coefficient for jammer i and the radar; JP_i is the jamming power of jammer i on the radar's frequency; and R_i is the range from the jammer to the radar. α is found by the relation:

$$\alpha = \left(\frac{P_t G_t^{1/2} G_r^{1/2}}{4\pi B_n (S/J)} \right)^{1/2}$$

where P_t is the power of the transmitter; G is the gain of the radar (In bistatic systems G is the square root of the product of the transmitter and receiver gains.); B_n is the receiver bandwidth of the radar; and S/J is the signal to jamming ratio for the desired probability of detection and appropriate propagation losses. In the bistatic range equation in a multiple standoff jamming environment, the burn through range is found in a manner similar to the clear environment to be

$$R_{bt} R_t = \alpha (\sigma / SJP)^{1/2}$$

where R_{bt} is the burn through range, R_t is the range from the bistatic transmitter to the target and the remaining factors are as defined above.

APPENDIX D
PROGRAM ARRAY LISTING

This appendix provides an alphabetical listing of the principal arrays used in the computer program. The listing contains the values of the arrays for the indicated array arguments. The arguments for the arrays are specified in the heading of their respective listing. The dimensions of the individual arrays are stated in the COMMON statement at the beginning of each subroutine.

ASMT (I,J)

The ASMT array contains data concerning the RED missiles.

I AMS/SSM launch sequence number

J=1 ASM/SSM status code as follows:

- 0 = Launch failure
- 1 = Successful launch
- 2 = Killed by SAM
- 3 = Inflight failure
- 4 = Hit target ship
- 5 = Launch platform shot down or sunk
prior to launch

J=2 Time of impact on target ship

J=3 Raid number of launch platform

J=4 Target ship number

J=5 Time of launch

J=6 Weapon class

J=7 X coordinate of launch position

J=8 Y coordinate of launch position

CHANEL (I,J,K,L)

An array used to keep track of which channels are busy.

- I Ship number
- J System number
- K Director number
- L Channel number
 - 0 = Free
 - 1 = Busy

JACK (I,J)

This array stores the engagement and detection statistics for individual ships.

- I Ship number
- J=1 Chances to engage. The number of targets that will enter within the maximum missile range of the ship
- J=2 Number of engagements
- J=3 Number of targets destroyed
- J=4 The number of raiders that will enter the missile envelope.
- J=5 The number of raiders that will enter the envelope and are detected
- J=6 The number of ASM/SSM that will enter the envelope
- J=7 The number of ASM/SSM that will enter the envelope and are detected

NADAR (I,J)

This array indicates the operational status of the on-board BLUE equipment.

- I Ship number

J=1 Search radar number 1
 0 = down
 1 = up

J=2 Search radar number 2

J=3 Search radar number 3

J=4 Battery one, fire control radar number 1
 0 = down
 1 = operational normal mode
 2 = no director needed for missile
 3 = operational in horizon scan mode

J=5 Battery one, fire control radar 2

J=6 Battery one, fire control radar 3

J=7 Battery two, fire control radar 1

J=8 Battery two, fire control radar 2

J=9 Battery two, fire control radar 3

J=10 Battery three, fire control radar 1

J=11 Battery three, fire control radar 2

J=12 Battery three, fire control radar 3

J=13 Battery four, fire control radar 1

J=14 Battery four, fire control radar 2

J=15 Battery four, fire control radar 3

J=16 Launcher for battery one
 0 = non operational
 1 = operational

J=17 Launcher for battery two

J=18 Launcher for battery three

J=19 Launcher for battery four

RAID (I,J)

This array stores information on the raider's location and weapons.

I	Raider number
J=1	X vector starting index of the raid class
J=2	Time that raid was at position indicated in J=3,4
J=3	X coordinate at time T
J=4	Y coordinate at time T
J=5	X coordinate at end of game
J=6	Y coordinate at end of game
J=7	X coordinate at launch if the raider has weapons and can reach the launch position, otherwise the X coordinate at end of game.
J=8	Y coordinate at launch, same as J=7
J=9	Raider altitude in feet
J=10	Raider's radar horizon
J=11	Weapon class of raider's longest range weapon
J=12	Total number of weapons assigned
J=13	Status 0 = destroyed or sunk N = number of hits the raider may take until destroyed
J=14	X coordinate of raider at end of game or X coordinate of target ship for ASM/SSM launched by raider I
J=15	Y coordinate comparable to J=14
J=16	Time raider will reach second launch point if it is carrying two types of missiles
J=17	Time the raider was destroyed

SAMASM (I,J)

This array contains information covering the BLUE missile launch, target, engagement outcome, and probability of kill.

- I BLUE salvo number
- J=1 Target number, 1-90 are raiders, 91-191 are ASM/SSM
- J=2 Ship number followed by system number
- J=3 Director number followed by channel number
- J=4 Time of launch
- J=5 Engagement outcome. Negative number indicates an overkill, zero a failure, and a positive number a successful shot.
- J=6 Time the channel will be free for reassignment
- J=7 Single shot probability of kill

SHIP (I,J)

The SHIP array contains information concerning the BLUE units.

- I Ship number
- J=1 Ship class
- J=2 X coordinate of ship position
- J=3 Y coordinate of ship position
- J=4 Number of hits ship can receive until declared out of action. If 0, ship is out of action.
- J=5 Ship class starting index
- J=6 Missile status code
 - 0 = no missile capability
 - 1 = missile capability

SMAT (I,J)

The SMAT array lists the results of the SAM firings.

- I SAM number
- J=1 SAM class index
- J=2 Firing ship number
- J=3 Number of missiles remaining in the battery firing the SAM
- J=4 Time fire control radar channel 1 free
- J=5 Time fire control radar channel 2 free
- J=6 Time fire control radar channel 3 free
- J=7 Time fire control radar channel 4 free
- J=8 Time fire control radar channel 5 free
- J=9 Time fire control radar channel 6 free
- J=10 Number of SAMs in the salvo

STATS (I,J)

The STATS array is used to compile statistics concerning the BLUE units.

- I Ship number
- J=1 Sum of the detection ranges on raiders
- J=2 Sum of the detection ranges on missiles

APPENDIX E

GLOSSARY FOR PROGRAM VARIABLES

1. MAIN PROGRAM

ALFA	REAL*8 variable used for conversion of degrees to radians.
AMF	Small real constant used for conversion from floating point variables to integer variables.
ASMT	The table containing RED ASM/SSM launch and targeting information.
BWJ	Beam width of the jammer.
BWR	Beam width of the radar receiver.
HISA	Vector used to store data for use with subroutine HISTG.
HISO	Vector used to store data for use with subroutine HISTG.
HISTG	Subroutine in the NPS computer library that provides a histogram display of an input vector.
HISX	Vector used to store data for use with subroutine HISTG.
IBAT	An array used to keep track of the number of missiles remaining in each missile battery of a BLUE unit.
IFAG	Integer constant containing the number of RED missiles engaged by the BLUE fleet.
IFBG	Integer constant containing the number of RED raiders engaged by the BLUE fleet.
IHIT	Vector containing the number of hits received by each BLUE unit.
IIF	The number of RED missiles that failed in flight.
IKS	The number of RED missiles shot down by BLUE SAMs.
ILF	The number of RED missiles that failed when launched.

ILS The number of RED missiles that were in flight at the end of the iteration.

IMF The number of RED missiles destroyed when the launching aircraft or ship was destroyed.

IMK The number of RED missiles destroyed by SAMs over all iterations.

IMM The number of RED missiles destroyed prior to launch over all iterations.

INSECT The original seed value used with the random number generator. Used to reproduce the random number chain if X(54) is set to 1.

IRT The starting address in the X vector for the next five input quantities.

ISAG An array containing the number of RED missiles first engaged by each BLUE ship.

ISBG An array containing the number of RED raiders first engaged by each BLUE ship.

ITS The number of RED missiles that impacted on their target.

JACK The array containing the BLUE ship detection and engagement counters.

KOUNT The iteration number.

MARY The vector containing the data for the hit frequency histogram.

NADAR The array that stores the BLUE radar and missile system availability for each iteration.

NASM The number of ASM/SSMs.

ND Index used to convert true bearings to cartesian bearings.

NI The number of iterations to be performed.

NMIF The number of missiles in the BLUE fleet.

NR The number of armed and unarmed RED raiders.

NRTGT The vector containing the RED units target list assignment.

NS The number of BLUE ships.

NSAM The number of BLUE missile salvos fired.

PLIST The array containing the target lists.

RAID The table containing the RED raider position and
weapon information.

RAT REAL*8 variable used to convert degrees to radians.

RXATA Dummy array used to read in data and fill the X
vector.

SAMASM The array containing the BLUE missile RED target
engagement information.

SETIMX The subroutine that sets the internal clock if
X(55) is set to 1.

SHIP The table containing the BLUE ship position infor-
mation.

SMAT The table containing the BLUE missile battery en-
gagement data.

STATS The array containing the BLUE unit detection ranges.

T Time.

2. SUBROUTINE EFFECT

IUNIT The code containing the units involved in playing
the next event.

NEXTEV The next event type.

TIME The time the next event is to be played.

TIMES The internal clock time used for entry and exit
if X(55) is set.

3. SUBROUTINE JULIE

BNG A REAL*8 variable used to convert degrees to radians.

CHANEL The array that keeps track of which BLUE missile
channels are busy.

IA The X vector address of the fire control radar
class number.

IBAT The array that keeps track of the number of BLUE missiles remaining in each battery.

IC The radar class of the fire control radar associated with the number one director of the indicated BLUE missile battery.

IFAG Integer constant containing the number of RED missiles engaged by the BLUE fleet.

IFBG Integer constant containing the number of RED raiders engaged by the BLUE fleet.

IFIRST Flag used for checking a target's priority.

IFLASK Flag used to set the time by which all RED raiders must reach their launch point in order to launch their missiles.

IFOG Flag to indicate a) horizon search mode, and b) the system has a launcher that is operable.

IGAGE A vector that keeps track of which targets have been engaged by BLUE missiles.

IHIT A vector that keeps track of how many hits each BLUE unit has taken.

IJ The ship class starting index in the X vector.

IOR The raid class starting index in the X vector.

IP Missile system class number.

IS The ship class starting index in the X vector.

ISAG Integer constant to determine how many RED missiles the ship was the first to engage.

ISBG Integer constant to determine how many RED raiders the ship was the first to engage.

IT Search radar class number.

ITEMS The number of events that have been retrieved from the events list.

IVENTS The array containing the events list.

JACK The array containing the ship detection and engagement statistics.

JAM The vector that keeps track of the number of jammers operating on a given radar frequency band.

KFOG Flag to indicate that a search radar is available.

LOVER The number of events in the events list.

MAMBAT The number of missile batteries available to the BLUE force.

MISLFT The array that keeps track of how many missiles a RED raider has left on board.

NADAR The array that keeps track of the operational mode of the BLUE equipment.

NASM The number of RED missiles.

NONO The array that keeps track of engageability of a RED unit or missile with respect to each BLUE unit.

NR The number of armed and unarmed RED raiders.

NS The number of BLUE units.

NSAM The number of BLUE missile salvos.

PROB The probability that a given piece of equipment is operational.

RAID The table with the raider location and weapon information.

RELOAD The array that stores the time the launcher will be reloaded by after a missile firing.

RGE The launch range of the longest ranged missile carried by each raider.

SHIP The table containing the ship position information.

SMAT The table with the BLUE missile system launch information.

STATS The table of BLUE detection ranges.

TGTAV The table that tells when a target will be available for engagement by another BLUE unit.

4. SUBROUTINE EVENT

ICODE The participating units-event type code that is stored in the events list.

ID The event type.

IT The time of the event converted to the integer format used to store it in the events list.

ITB Used to determine where in the events list the next event to be stored should go.

ITEMS The number of events retrieved.

ITIM The time as stored in the events list.

ITM The time as stored in the events list.

IUNIT The units involved in playing the next event.

IVENTS The events list.

IVET The participating units as stored in the events list.

LOVER The number of events stored in the events list.

NEXTEV The next event type.

NUMBER The code for the participating units.

T The time of the event.

TIME The time of the event.

5. SUBROUTINE REMOVE

IUNYT The code stored in the events list of the event to be removed from the events list.

IVENTS The events list.

LOVER The number of items in the events list.

6. SUBROUTINE TARGET

IFIRST The flag that indicates that the counter has been zeroed.

IT The game time in events list code.

IUNIT The code of the event to be compared by PRIOR.

IVENTS The events list.

MORE The flag indicating that there is an event with the same playing time and of type three.

NPGS The counter that is used as an index in searching the events list.

TYME Present game time.

7. SUBROUTINE SUBE1

ALT The raider's altitude.

AREA The fourth root of the raider's radar cross section.

DELR The detection delay.

FCRH The radar horizon of the fire control radar.

FRG The minimum of the clear environment detection range, the radar horizon, and the radar's theoretical maximum detection range.

HFCSR The radar horizon of the fire control radar.

HORZ The combined radar horizons of the radar and the target.

HRAG The combined radar horizons of the radar and the target.

HRFC The combined radar horizons of the radar and the target.

HSFR The minimum of the clear environment detection range, the radar horizons, and the maximum theoretical detection range.

HT The height of the fire control radar antenna.

IA Used to check the class numbers of the various systems.

IC Missile system class number.

ICH Used to enter the NADAR table.

ICL Fire control radar class number.

ICPA Flag telling whether the target will come within the maximum detection range.

IFA Integer to store the radar number.

IFC Integer to store the battery number.

IFCR Fire control radar class number.

IF Radar frequency band.

IR The raid number.

ISI The ship class starting index in the X vector.

JACK The table of engagements and detections.

JAM The table that keeps track of how many jammers there are on each radar frequency band.

JAMM The subroutine for determining the detection range of a monostatic radar in a jamming environment.

JCPA The flag that tells whether or not the target will come within the detection range.

JFOG The flag that tells whether or not this is the second bistatic detection zone.

KEY The type of probability distribution associated with this unit's time delays.

KFLAG Flag that says that this unit has a search radar that is operational.

LCPA Flag that tells whether or not a target will close to within the detection range.

MFOG Counter giving the number of second bistatic detection zones to be processed.

MJL Index for table lookup.

MTY Missile system class number.

NADAR The table containing the equipment availability.

NASA The flag indicating that raider is an aircraft.

NASM The number of ASM/SSM launched or destroyed.

NB The battery number.

ND The number of bistatic detection zones.

NF The director number.

NFOG Flag telling whether or not there are any more bistatic detection zones to check.

NJ The number of jamming raiders.

NONO The table that contains the reason for non-engageability.

NSR The search radar index.

NSURF Flag that says that this ship has a surface to surface missile system.

PROB Probability of acquisition.

RAGJ Detection range in a jamming environment.

RAID The table with raider location and weapon information.

RCPS Range at CPA squared.

REACT Subroutine for determining reaction time delays.

RFCJ Fire control radar detection range in the jamming environment.

RG The minimum of the clear environment detection range, the radar horizon range, and the theoretical maximum detection range.

RGE Detection range.

RGF Jamming environment detection range.

RGFC Detection range of the fire control radar.

RGI Detection range in a jamming environment.

RGIA Storage for second bistatic detection range.

RGIB Storage for second bistatic detection range.

RGIC Storage for second bistatic detection range.

RGM Missile range.

RIP The maximum detection range, or present target position, whichever is smaller.

RRFC Clear environment fire control radar detection range.

RRH Radar horizon of the search radar.

R2 The detection range in the second bistatic detection zone.

SALT The radar horizon of the raider.

SAMVEL The BLUE missile's speed.

SHIP The table with the ship position information.

SIGMA The raider radar cross section.

SRAG Missile range.

SRFC Fire control radar clear environment detection range.

STATS Ship's detection range storage.

SVEL Missile speed.

TD Time raider will close to the given range.

TDES The designation time delay.

TDET The time of detection.

TD2 The time of detection in the second bistatic detection zone.

TFIR The last time to fire.

TFIRE The firing time delay.

TFR Time the target will close to fire control acquisition range.

THR Theoretical radar maximum detection range.

THSCAN Horizon scan detection delay.

TI Time the target will close to the given range.

TIME Present game time.

TIML Time the target will go beyond the given range.

TIMLA Storage for lose detection time.

TIMLB Storage for lose detection time.

TIMLC Storage for lose detection time.

TIML2 Time of lose detection in the second bistatic de-
detection zone.

TLS Last time to fire.

TRGE Time of detection.

TSHOOT Time of launch.

TSR Total reaction delay.

TTA Storage for detection time in second detection zone.

TTB Storage for detection time in second detection zone.

TTC Storage for detection time in second detection zone.

TWDS Reaction time delay for weapons designation equip-
ment.

VEL Raider speed.

XCP The X coordinate of the CPA.

YCP The Y coordinate of the CPA.

8. SUBROUTINE SUBE2

ALT Altitude of the RED ASM/SSM during flight in feet.

ALTN2 Altitude of the RED ASM/SSM squared in miles.

AREA The fourth root of the radar cross sectional area
of the RED missile.

ASMT The table containing RED missile launch and target-
ing information.

DELR The detection time delay.

DELTAX The distance in the X direction between the target
ship and the ASM/SSM launch point.

DELTAY The distance in the Y direction between the target
ship and the ASM/SSM launch point.

DIST The three dimensional distance from the ASM/SSM
launch point to the target ship. This distance
assumes launch at cruising altitude.

HORZ The combined radar horizons of the firing ship and
the RED missile.

HRAG The combined radar horizons of the firing ship and the RED missile.

HT The BLUE radar antenna height.

IA Fire control radar class number.

IC The BLUE missile system class number.

ICL Fire control radar class number.

ICOP Constant for X vector entry set by SUBE2.

ICPA Flag telling whether or not a RED missile will come within the detection range.

IDP Index counter used to make up the RED raider's temporary target list.

IFA The director number.

IFC The battery number.

IFCR BLUE missile system class number.

IFLAG Flag indicating RED unit is firing a two missile salvo.

IFLASK Flag indicating the first air launch has occurred, set TMAX.

IHIT Table of hits taken by BLUE ships.

IJ Raider class number.

IJI Radar frequency band.

IOU Target ship number.

IPQ Target hit number.

IR Raider number.

ISI Ship class starting index in the X vector.

JACK Ship detection and engagement table.

JAM Table that keeps track of the number of jammers on the radar frequency bands.

JAMM Subroutine to determine monostatic radar detection ranges in a jamming environment.

JFLAG Flag indicating that there are more second bistatic detection zones to evaluate.

JFOG Flag indicating that there were two bistatic detection zones.

KATHY Flag indicating that a second type ASM/SSM is being processed.

KEY Type of probability distribution to be used in computing the reaction time delay.

KFLAG Flag indicating BLUE unit has an operational search radar.

KING Flag for one or two missile salvos.

KQED Flag indicating whether or not raid could target a particular BLUE unit.

LNUM The class number of the raider's long range missiles.

MARIE Number of hits required to put the BLUE unit out of action.

MFOG Counter indicating the number of second bistatic detection zones.

MISLFT Array to indicate the number of ASM/SSM left on board a raider.

NADAR The array that stores BLUE equipment operability.

NASM The number of ASM/SSMs processed.

ND The number of bistatic detection zones.

NEXT Flag indicating the short range RED missiles.

NFOG Flag indicating there are more detection zones to process.

NJ The number of jammers.

NMIS The number of ASM/SSM of this type to be launched.

NONE The index used to draw random numbers from the random number vector.

NONO The array specifying the target-firing ship relationship.

NOW The type missile being processed now.

NR The number of raiders.

NRTGT The target list assignments.

NS The number of BLUE units.

NTOT The total number of ASM/SSM on board.

PLIST The target lists.

PROB The probability of acquisition in horizon scan mode of operation.

QRT The vector of (0,1) random numbers used to determine missile launch times.

RAGJ The search radar detection range in a jamming environment.

RAID The table with the raider location and weapon information.

RCPS The slant range to CPA.

RELI The RED missile's inflight reliability.

RFCJ Detection range of fire control radar in a jamming environment.

RG The minimum of the clear, jamming, and theoretical detection ranges.

RGE Detection range.

RGF Detection range.

RGFC Fire control radar detection range.

RGI Detection range.

RGIA Storage for secondary bistatic detection range.

RGIB Storage for secondary bistatic detection range.

RGIC Storage for secondary bistatic detection range.

RGM BLUE missile range.

RGS Detection range squared.

RIP Minimum of present range and detection range.

RRFC Horizon search clear environment detection range.

RRH Radar horizon.

RT Cumulative probability of targeting this target or one previous.

R2 Second bistatic detection range.

SALT The radar horizon of the RED weapon.

SAMVEL BLUE missile speed.

SHIP The table containing ship position information.

SIGMA The RED weapon radar cross sectional area.

SPD The RED weapon speed.

SRAG Search radar detection range in a clear environment.

SRFC Fire control radar detection range in a clear environment.

SRGE BLUE ship missile range.

STATS Array containing the sum of a ship's detection ranges.

SVEL BLUE missile speed.

TAC Acquisition time delay.

TD Time of detection.

TDES Designation time delay.

TDET Time of detection.

TD2 Time of detection in the second bistatic detection zone.

TFIR Last time to fire based on search radar range and maximum range missile.

TFIRE Firing time delay.

TFR Time target will come within the fire control detection range.

THR Maximum theoretical radar range.

THSCAN Reaction time delay for horizon scan mode of operation.

TI Time target will come within the search radar de-
 tection range.

TIFA Time target will come within the horizon scan
 detection range.

TIME Present game time.

TIMF Time target will exit the fire control radar detec-
 tion range.

TIML Time the target will go beyond the search radar
 detection range.

TIMLA Storage for second bistatic detection zone loss of
 target time.

TIMLB Storage for second bistatic detection zone loss of
 target time.

TIMLC Storage for second bistatic detection zone loss of
 target time.

TIML2 Time target will go beyond detection range in the
 second bistatic detection zone.

TINT The time interval over which all missiles must be
 launched.

TLS Last time to fire based on fire control radar range.

TM Proposed RED missile launch time.

TMAX Time limit on launch of RED missiles.

TRGE a) Hazard zone range squared, b) time of detection.

TSHOOT Time of proposed BLUE missile launch.

TSR Total reaction time delay.

TTA Storage for second detection zone detection time.

TTARG The temporary target list.

TTB Storage for second detection zone detection time.

TTC Storage for second detection zone detection time.

TWDS Delay for weapons direction equipment processing.

TX Time between RED missile launchings.

VEL RED missile speed.

XCPA CPA position in the X direction.
YCPA CPA position in the Y direction.
Z (0,1) random number.

9. SUBROUTINE SUBE3

ASMT The table containing the RED missile launch and targeting information.
CHANEL The array that indicates which system channels are in use.
EBTJR The Y coordinate of CPA.
FT BLUE missile flight time.
IBAT Array giving the number of BLUE missiles available by battery.
ICOT Flag indicating channel assigned.
IP Ship class starting index in the X vector.
IU Input code giving target, ship, system, and director information.
JAPL A channel number.
JULIA RED missile number for table lookup.
K Firing ship number.
KA Target ship number.
M Number of original target.
MFOG Flag used to check director scheduling.
M1 Target number after searching PRIOR.
NADAR Array to check launcher operability.
NB Director number.
NC Channel number.
NCH Number of channels associated with this radar.
NC1 Channel number.
NMS Missile system number.

NSAM BLUE salvo number.
 PROB Probability of kill.
 RAID Table of raider positions.
 REASON Code for non-engageability.
 RELOAD Table that tells if the launcher is loaded.
 RGE Systems maximum range.
 RJL The X coordinate of CPA.
 RLT Launcher reload time.
 SAMASM The table of BLUE missile and RED target engagement data.
 SHIP Table of ship positions.
 SMAT Table of BLUE missile system data.
 TCF Dummy vector for storing the times the channels will be free for other use.
 TFT Time director first available for channel use.
 TF Time director needed.
 TGTAV Time target available for engagement by another unit.
 TIM Time channel free.
 TIME Present game time.
 TL Time director no longer needed.
 TT Time director needed for homing.
 XP Present target X coordinate.
 YP Present target Y coordinate.

10. SUBROUTINE SUBE4

ID Used as a class indicator, i.e. ASM type, or as an integer constant, i.e. number of hits to sink the target ship.
 IHIT The table containing the number of hits sustained thus far in the game.

IU The input code containing the RED missile number and the BLUE target ship number.

K The target ship number.

NAM The RED ASM/SSM number for table lookup.

NAS The RED ASM/SSM number in the input code.

PB The probability of successful flight for the RED missile. Also used in determining the input and output time of the subroutine if X(55) is set.

11. SUBROUTINE SUBE5

ASMT The table containing the data on the RED missile engagement.

CHANEL The table that keeps track of which BLUE missile channels are being used.

ID An integer constant used for the starting address in the X-array of the BLUE firing ship's class inputs. Also used as the number of RED ASM/SSMs launched up to the present game time.

IFAG Integer constant that totals up the number of RED missiles engaged by the BLUE fleet.

IFBG Integer constant that totals up the number of RED raiders engaged by the BLUE fleet.

IGAGE Integer constant that keeps track of which targets have been engaged.

IP Radar class of the BLUE fire control radar associated with the engagement.

IQ BLUE missile system class number.

ISAG Integer constant that totals up the number of RED missiles first engaged by this firing ship.

ISBG Integer constant that totals up the number of RED raiders first engaged by this firing ship.

JACK The table that keeps track of the number of missiles and raiders engaged by the firing ship.

JAM The table that totals up the number of jammers operating on a particular radar frequency band.

JFK Integer used in table lookup.

K The BLUE firing ship.

KEY As used in the statement -- CALL REACT (KEY,4,TA) -- where 4 is the type of delay, KEY is the class of the particular distribution within the type, and TA is the delay.

M The BLUE salvo number.

MISLFT The table that keeps track of the number of missiles remaining on board the RED raider.

N The number of missiles in the BLUE salvo.

NA The RED ASM/SSM number for table lookup.

NASM The number of RED ASM/SSMs processed thus far.

NB The BLUE ship's director involved in the engagement.

NC The channel number of the fire control system engaged in the intercept.

NDU The starting address of the class associated with the raider involved in the intercept.

NMS The number of the ship's missile system involved in the intercept.

NT The target number, 1-90 for a raider, 91-190 for a RED missile.

NTOT The number of missiles left on board the raider.

PB The probability that the BLUE missile will receive the proper support during flight.

PROB The overall probability of a successful intercept.

SAMASM The table that keeps BLUE salvo information.

SMAT The table that keeps BLUE system information.

TA The time delay for target acquisition.

TF The time delay for firing.

TK The time delay for kill assessment.

12. SUBROUTINE SUBE6

CHANEL The table that keeps track of which BLUE missile channels are being used.

K The firing ship.

M The input code containing the ship, system, director, and channel number to be released.

NB The director number.

NC The channel number.

NMS The system number.

T The input and output time for the subroutine, used if X(55) is set.

13. SUBROUTINE TIMMY

A The cross range factor in the intercept contour.

ALPHA The angle between the target flight path and the line of sight to the target.

ALT The target altitude.

ASMT The table containing the data on the RED missile engagement.

ASMTIM Subroutine to determine RED missile position at a given time.

B The downrange factor in the intercept contour.

BETA The angle between the BLUE missile flight path and the target's direction of movement.

CS The target course.

DELTA The reciprocal of BETA.

DELTA X Used for a) the X distance from the target ship to the RED missile, b) the present distance in the X direction from the firing ship to the target, and c) the distance in the X direction from the firing ship to the intercept point.

DELTA Y Same as DELTA X but in the Y direction.

DIS Range to the intercept point.

DLT Range to the intercept point.

DX Distance in the X direction from the initial target position to the intercept point. Used if intercept point is over the firing ship.

DY Distance in the Y direction from the initial target position to the intercept point. Used if the intercept point is directly over the firing ship.

EX The exponent that defines the super ellipse of the intercept contour.

FT BLUE missile flight time.

FZL Left hand limit of the firing zone.

FZL1 Left hand limit of the second firing zone if a second exists.

FZR Right hand limit of the firing zone.

FZR1 Right hand limit of the second firing zone.

GAMMA Angle between the BLUE missile flight path and the line of sight to the target at launch.

GSINE The sine of GAMMA.

ID RED missile type.

IND Flag indicating the feasibility of the intercept.

IR RED missile's launching raid number.

JOAN RED missile's target ship number.

JULIA RED missile number for table lookup.

K Firing ship number.

KL Starting index for the BLUE missile class.

KR Raider class number.

LOCTIM Subroutine for determining raider position at a desired time.

M Target number.

NMS BLUE missile system number.

NS The number of ships in the BLUE force.

PHI The BLUE firing bearing.

PHI1 The angle of axis rotation for intercept contour engagement evaluation.

PI 3.141592654.

PIZ The hazard range squared.

PK The single shot kill probability.

PM The probability of successful launch.

PROB PK times PM.

RADIAN A function for converting angles in degrees to angles in radians.

RAID The table with the raider position and weapon information.

RAT A REAL*8 variable for use with RADIAN.

REASON A code to indicate the reason for non-engagement.

RMAX The maximum range of the BLUE missile.

RMIN The minimum range of the BLUE missile.

RUTH Target altitude in miles.

RXATA Dummy vector use to determine the firing zone.

SEEK Y intercept of the intercept contour seeker limitation approximation.

SLOPE The slope of the line that approximates the seeker look limitation.

SSPD Speed of the BLUE missile.

THETA The angle, measured in the normal X,Y plane, of the line from the firing ship to the present target position.

TH1 The reciprocal of THETA.

TIME The time of the proposed missile launch.

TKIL The time of intercept.

TX The time the target will enter the maximum missile range for this system.

TXL The time the target will depart the maximum missile range for this system.

VEL The speed of the target.

XI The X coordinate of the intercept.

XIP The X intercept coordinate after axis rotation and translation.

XIS The X intercept coordinate after axis translation.

XP The X coordinate of the present target position.

XT The end of game X coordinate for the target if it is a raider, or the target ship coordinate if the BLUE missile's target is a RED ASM/SSM.

XW The initial position of the target in the X direction.

YI The Y coordinate of the intercept point.

YIP The Y intercept coordinate after axis rotation and translation.

YIS The Y intercept coordinate after axis translation.

YP The Y coordinate of the present target position.

YT The end of game Y coordinate for the target.

YW The Y coordinate of the initial target position.

ZLNKA A sorting subroutine.

14. SUBROUTINE JAMM

AREA Fourth root of target's radar cross section.

COFF Jammer's main beam/side-lobe coefficient.

DELX Target's track change in X direction minus 0.1 nm.

DELY Target's track change in Y direction minus 0.1 nm.

HJBW One-half jammer beam width in radians.

HRBW One-half radar beam width in radians.

ITS Target ship number.

JJTBR Bearing from jammer to the jamming target.

JRBRG Bearing from the jammer to the detecting radar.

LJBW Left bearing of the jamming beam.

LTBRG Left bearing of the detecting radar's beam while pointed at the target.

NASM Number of the ASM.

NR Number of raiders.

PJ Power of the jammer on the detecting radar's frequency.

RCOF Detecting radar's side-lobe coefficient.

RCOFF Detecting radar's side-lobe coefficient for specific jammer-target-radar geometry.

RCPS Range to track CPA squared.

RJBRG Detecting radar to jammer bearing.

RJBW Right bearing of jammer beam.

RJHS Detecting radar-jammer horizon squared.

RRJS Range from the detecting radar to the jammer squared.

RTBRG Right bearing of the detecting radar's beam width while pointed at the target.

SUMJP Sum of the jamming power arriving at the detecting radar.

TBRG Target bearing from the detecting radar.

TIMC Time constant used to adjust midpoint time. Base on target's launch time or game time of target's initial position.

TIMI Time target is at its midpoint in detecting radar's detection envelope.

TIMX Time target is at the X coordinate of its midpoint in the detecting radar's detection envelope.

TIMY Time target is at the Y coordinate of its midpoint in the detecting radar's detection envelope.

VD Divisor used in obtaining the X and Y components of the target's velocity.

VX X component of the target's velocity.

VY Y component of the target's velocity.

XC X coordinate of target's CPA to detecting radar.

XCOF Product of the jammer and detecting radar coefficients based on the jammer-target-radar geometry.

XJ X coordinate of the jammer when the target is at its midpoint.

XJJ X coordinate of the jammer at game time 0.

XJJT Difference in X coordinates of the jammer's position and the jammer's target position.

XJR Difference in X coordinates of the detecting radar's position and the jammer's position.

XJT X coordinate of the jammer's target.

XO X coordinate of the target's terminal position.

XR X coordinate of the detecting radar's position.

XRT Difference in Y coordinates of the detecting radar's position and the target's midpoint position.

XI X coordinate of the target's initial position.

YC Y coordinate of target's CPA to detecting radar.

YJ Y coordinate of the jammer when the target is at its midpoint.

YJJ Y coordinate of the jammer at game time 0.

YJJT Difference in Y coordinates of the jammer's position and the jammer's target position.

YJR Difference in Y coordinates of the detecting radar's position and the jammer's position.

YJT Y coordinate of the jammer's target.

YO Y coordinate of the target's terminal position.

YR Y coordinate of the detecting radar's position.

YRT Difference in Y coordinates of the detecting radar's position and the target's midpoint position.

Y1 Y coordinate of the target's initial position.

Z1 Target altitude in nautical miles.

15. SUBROUTINE BIDET

A Coefficient used in solution of bistatic detection and radar horizon equations. See Appendix A for bistatic equation.

A1 2A.

A2 A squared.

B Similar to A. See Appendix A.

C Similar to A. See Appendix A.

CC Constant used in solution of receiver and transmitter radar horizons equations.

CHAR Constant of bistatic detection equation. See Appendix A.

CHAS Bistatic radar detection range in clear environment against one square meter target.

COF Array used only in calling subroutine DTIMD.

COFF See definition in subroutine JAMM portion of this glossary.

CPRS Range squared from track CPA to bistatic receiver position.

CPXS Range squared from track CPA to bistatic transmitter position.

D Similar to A. See Appendix A.

DELX Same definition as in subroutine CPA.

DELY Same definition as in subroutine CPA.

E Similar to A. See Appendix A.

EE Constant used in the solution of bistatic receiver and transmitter radar horizon equations.

HJBW Defined in subroutine JAMM.

HORRS Receiver's radar horizon range squared.

HORXS Transmitter's radar horizon range squared.

HRBW Defined in subroutine JAMM.

IFLAG Flag set to 1 for stationary targets.

IT Ship number of bistatic transmitter.

JAM Array indicating the number of active jammers on each radar frequency band.

JFLAG Flag set to 1 when the algorithm has completed the jamming section of the detection phase.

JJTBR Defined in subroutine JAMM.

JRBRG Defined in subroutine JAMM.

LJBW Defined in subroutine JAMM.

LTBRG Defined in subroutine JAMM.

NASM ASM number.

PJ Defined in subroutine JAMM.

Q Track change in Y direction divided by track change in X direction.

RCOF Defined in subroutine JAMM.

RCOFF Defined in subroutine JAMM.

RD2 Square of the range from the bistatic receiver to stationary target's position.

RJBRG Defined in subroutine JAMM.

RJBW Defined in subroutine JAMM.

RJHS Defined in subroutine JAMM.

RRAD Radical part of solution to quadratic equation for time above bistatic receiver's radar horizon.

RRH Range to receiver's radar horizon.

RRJS Defined in subroutine JAMM.

RTBRG Defined in subroutine JAMM.

SUMJP Defined in subroutine JAMM.

T An array containing the bistatic detection times.

TBRG Defined in subroutine JAMM.

TIMC Time constant based on target's launch time of missile. Otherwise start of game time.

TIME Array containing the real parts to the solution of the bistatic equation.

TIMEI Array containing the complex parts to the solution of the bistatic equation.

TIMI Defined in subroutine JAMM.

TR1 Time target enters receiver's radar horizon range.

TR2 Time target departs receiver's radar horizon range.

TX1 Time target enters transmitter's radar horizon range.

TX2 Time target departs transmitter's radar horizon range.

T1 Time target enters bistatic radar detection envelope.

T10 Time target is first above both transmitter and receiver's radar horizon.

T2 Time target departs bistatic radar detection envelope.

T20 Time target is no longer above both the transmitter and receiver's radar horizon.

V Target's velocity in nautical miles per minute.

VD Defined in subroutine JAMM.

VX X component of target velocity.

VY Y component of target velocity.

XCOF Defined in subroutine JAMM.

XCOFF Defined in subroutine JAMM.

XD2 Square of the range from the bistatic transmitter to the stationary target's position.

XJ Defined in subroutine JAMM.

XJJ Defined in subroutine JAMM.

XJJT Defined in subroutine JAMM.
 XJR Defined in subroutine JAMM.
 XO X coordinate of target's terminal position.
 XR X coordinate of bistatic radar receiver position.
 XRAD Similar to RRAD above.
 XRC X coordinate of target track CPA to bistatic receiver.
 XRT Defined in subroutine JAMM.
 XX X coordinate of the bistatic transmitter.
 XXC X coordinate of target track CPA to bistatic transmitter.
 X1 X coordinate of target's initial position.
 YJ Defined in subroutine JAMM.
 YJJ Defined in subroutine JAMM.
 YJJT Defined in subroutine JAMM.
 YJR Defined in subroutine JAMM.
 YJT Defined in subroutine JAMM.
 YO Y coordinate of target's terminal position.
 YR Y coordinate of bistatic receiver's position.
 YRC Y coordinate of target track CPA to bistatic receiver.
 YRT Defined in subroutine JAMM.
 YX Y coordinate of the bistatic transmitter position.
 YXC Y coordinate of target track CPA to bistatic transmitter.
 Y1 Y coordinate of target's initial position.
 ZR Bistatic receiver antenna height in feet.
 ZRN Bistatic receiver antenna height in nautical miles.
 ZX Bistatic transmitter antenna height in feet.

ZXN Bistatic transmitter antenna height in nautical miles.
Z1 Target altitude in nautical miles.
Z12 Target altitude in nautical miles squared.

16. SUBROUTINE CPA

DELX First used as a test variable to determine if track passes through reference position. Second usage is to indicate track change in X direction.
DELY First used as a test variable to determine if track passes through reference position. Second usage is to indicate track change in Y direction.
Q Track change in Y direction divided by track change in X direction.
XC X coordinate of CPA position.
XI X coordinate of initial track position.
XO X coordinate of terminal track position.
XP X coordinate of reference position.
YC Y coordinate of CPA position.
YI Y coordinate of initial track position.
YO Y coordinate of terminal track position.
YP Y coordinate of reference position.

17. SUBROUTINE RCHECK

DELX The distance along the X axis from the raider position to the potential target position.
DELY The distance along the Y axis from the raider position to the potential target position.
DIS The square of the distance from the raider to the potential target.
HT The height of the highest radar on the potential target ship.
HTR The radar horizon for HT.

ID The class number of the potential target ship.

IR The raider number.

IT The potential target ship number.

K Flag for go/nogo situation.

RADAR The combined radar horizons of the raider and the potential target.

RADAR2 RADAR squared.

RR The maximum theoretical range for the raider's radar.

RR2 RR squared.

RTR Radar horizon for the raider.

SHIP The table containing the BLUE ship location information.

XS The raider's present position along the X axis.

XT The ship's present position along the X axis.

YS The raider's present position along the Y axis.

YT The ship's present position along the Y axis.

18. SUBROUTINE TMDASM

A Coefficient A in the quadratic equation.

B Coefficient B in the quadratic equation.

B1 B in $Y = mX + b$

C Coefficient C in the quadratic equation.

DELTAX The distance in the X direction from present position to the end of game position.

DELTAY The distance in the Y direction from present position to the end of game position.

DELX The distance in the X direction from the intercept position to the present position.

DELY The distance in the Y direction from the intercept position to the present position.

DEX The distance in the X direction from the firing ship to the target at present time.

DEY The distance in the Y direction from the firing ship to the target at present time.

DIC The distance in either the X or Y direction from intercept to end of game.

DIF The distance in either the X or Y direction from present position to end of game position.

D1 Distance from present position to first intercept point, squared.

D2 Distance from present position to second intercept point, squared.

IFLAG Flag indicating target is already within the indicated range.

IRAID Raider number of target or launching raid.

ISAMBT Battery number.

ITS Target ship number when target is an ASM/SSM.

KFLAG Flag indicating target moving in a north or south direction.

M Raider number.

NFS Firing ship number.

RAID The raid array.

RIP The range to the target or to intercept, whichever is smaller.

ROOT $B^2 - 4AC$.

SHIP The ship array.

SLM m in $Y = mX + b$.

SRG Range of interest.

TIME Time target crosses range inbound.

TIML Time target crosses range outbound.

TML Present game time.

TOAST $B^2 - 4AC$.

VEL Target speed.
XI Inbound crossing point.
YI Inbound crossing point.

19. SUBROUTINE TMDBOM

A A in the quadratic equation.
B B in the quadratic equation.
BA b in $Y = mX + b$.
C C in the quadratic equation.
DELTAX The distance from present position to the end of
game position in the X direction.
DELTAY The distance from the present position to the end
of game position in the Y direction.
DELX Distance from the intercept point to present posi-
tion in the X direction.
DELY Distance in the Y direction from the intercept
point to the present position.
DIC Distance from the intercept point to the end of
game position in the X direction.
DIF Distance from the present position to the end of
game position in the X direction.
IR Raider number.
RAID Raid array.
RGE The launch range.
SLM m in $Y = mX + b$.
T Time raider will reach the launch range.
VEL The raider speed.

20. SUBROUTINE LOCTIM

D The distance between the raider end of game position and the position stored in the RAID table.

DELTAX The distance along the X axis from the end of game position to the position stored in the RAID table.

DELTAY Distance along the Y axis.

DL Distance traveled in the time interval defined as the difference between the time stored in the RAID table and the time for which the raider position is desired.

K The raider number.

PTIME The time stored in the RAID table.

RAID The table that contains the position and weapon information.

T The time for which the raider position is desired.

VEL The raider speed.

XP The X position at time T.

XZ The X position stored in the RAID table.

YP The Y position at time T.

YZ The Y position stored in the RAID table.

21. SUBROUTINE ASMTIM

ASMT The table containing the data on the RED missile engagement.

D The distance between the missile launch point and the impact point.

DL The distance the missile will travel in the time defined as the difference between the launch time and the time for which the missile position is desired.

ID The RED missile type.

M The RED missile target number.

MA The RED missile number for table lookup.

T The time for which the ASM/SSM position is desired.

VEL The missile speed.

XP The X position at the time T.

YP The Y position at the time T.

CC

420 MAIN
430 MAIN
440 MAIN
450 MAIN
460 MAIN
470 MAIN
480 MAIN
490 MAIN
500 MAIN
510 MAIN
520 MAIN
530 MAIN
540 MAIN
550 MAIN
560 MAIN
570 MAIN
580 MAIN
590 MAIN
600 MAIN
610 MAIN
620 MAIN
630 MAIN
640 MAIN
650 MAIN
660 MAIN
670 MAIN
680 MAIN
690 MAIN
700 MAIN
710 MAIN
720 MAIN
730 MAIN
740 MAIN
750 MAIN
760 MAIN
770 MAIN
780 MAIN
790 MAIN
800 MAIN
810 MAIN
820 MAIN
830 MAIN
840 MAIN
850 MAIN
860 MAIN
870 MAIN
880 MAIN
890 MAIN

ISAG	VECTOR TO KEEP TRACK OF HOW MANY ASM/SSMS A SHIP FIRST ENGAGED
ISBG	SAME AS ISAG, BUT FOR RAIDERS
ISEED	THE INPUT FOR THE CALL RANDOM NUMBER GENERATOR
ITEMS	THE NUMBER OF EVENTS THAT HAVE BEEN RETRIEVED FROM THE EVENTS LIST
IVENTS	THE EVENTS LIST
JACK	USED TO KEEP STATISTICS OF ENGAGEMENT AND DETECTION
JAM	A VECTOR TO KEEP TRACK OF THE PRESENCE OF JAMMING ON EACH OF THE FOUR SIMULATED RADAR FREQUENCY BANDS
KMART	AN ARRAY USED WITH ZLNKA TO DETERMINE THE REORDERING OF THE INPUT VECTOR
KOUNT	THE ITERATION IN PROGRESS
LOVER	THE NUMBER OF EVENTS CURRENTLY IN THE EVENTS LIST
MAMBAT	THE NUMBER OF AVAILABLE SAM BATTERIES
MARY	THE VECTOR THAT KEEPS THE TOATAL HITS STATISTIC
MISLFT	AN ARRAY TO KEEP TRACK OF ASMS LEFT ON BOARD EACH RAIDER
NADAR	THE ARRAY CONTAINING SEARCH RADAR, FC RADAR, AND LAUNCHER UP/DOWN STATUS
NASM	THE NUMBER OF ASMS LAUNCHED
NONO	THE ARRAY THAT GIVES THE SHIP VS. ASM/RAIDER AN OK OR THE REASON FOR NON ENGAGEMENT
NPGS	A FLAG USED IN PRIOR
NR	THE NUMBER OF RED RAIDERS
NRTGT	A VECTOR LISTING THE TARGET LIST ASSIGNED TO EACH RAIDER
NS	THE NUMBER OF SHIPS IN THE BLUE FLEET
NSAM	NUMBER OF SALVOS FIRED

PLIST THE ARRAY CONTAINING THE TARGETING PROBABILITIES
QRT A DUMMY ARRAY USED FOR STORING RANDOM NUMBERS
RAID THE ARRAY WITH THE RED RAIDER DATA
REASON A FAILURE TO SHOOT A SAM CODE
RELOAD THE ARRAY THAT TELLS WHETHER A LAUNCHER IS THROUGH
WITH ITS RELOAD CYCLE
RXATA A DUMMY ARRAY USED TO LOAD INPUT
SAMASM THE ARRAY WITH THE PARTICULAR SAM AND ASM ENGAGEMENT DATA
SMAT THE ARRAY WITH THE SAM FIRING RESULT
SHIP THE ARRAY WITH BLUE FORCE INFO
STATS THE ARRAY FOR COMPILING SHIP DETECTION AND ENGAGEMENT
STATISTICS
TCF USED TO REORDER THE CHANNEL AVAILABILITY TIMES
TGTAVAL THE COORDINATION OF FIRE ARRAY
TMAX THE TIME BY WHICH ALL AIR ASM LAUNCHES MUST BE COMPLETED
X THE INPUT ARRAY HOLDING SCENARIO DATA, BLUE SHIP(AC)
DATA AND THE RED RAIDER DATA
CALL OVFLOW
AMF = 5.0E-3
DO 30 I=1,40
DO 20 J=1,6
PLIST(I,J) = 0.
20 CONTINUE

MAIN 900
MAIN 910
MAIN 920
MAIN 930
MAIN 940
MAIN 950
MAIN 960
MAIN 970
MAIN 980
MAIN 990
MAIN1000
MAIN1010
MAIN1020
MAIN1030
MAIN1040
MAIN1050
MAIN1060
MAIN1070
MAIN1080
MAIN1090
MAIN1100
MAIN1110
MAIN1120
MAIN1130
MAIN1140
MAIN1150
MAIN1160
MAIN1170
MAIN1180
MAIN1190
MAIN1200
MAIN1210
MAIN1220
MAIN1230
MAIN1240
MAIN1250
MAIN1260
MAIN1270
MAIN1280
MAIN1290
MAIN1300
MAIN1310
MAIN1320
MAIN1330
MAIN1340
MAIN1350
MAIN1360
MAIN1370


```

30 CONTINUE
    SET ALL X ARRAY TO ZERO
    DO 40 I=1,2744
    X(I) = 0.
40 CONTINUE

    DO 50 I=1,100
    MARY(I) = 0
50 CONTINUE

    READ IN THE DATA
    DO 70 IJ=1,548
    READ (5,1170) IRT,RXATA
    IF (IRT.EQ.0) GO TO 80
    JRT = IRT+4

    DO 60 J=IRT,JRT
    X(J) = RXATA(J-IRT+1)
60 CONTINUE

70 CONTINUE

    ISEED = IFIX(X(11))+AMF)
    NI = IFIX(X(6))+AMF)
    IF (X(82).EQ.0.) X(82)=120.
    INSECT = ISEED

    PRINT OUT THE X ARRAY AS READ INTO THE COMPUTER
    IF (X(12).EQ.0.) GO TO 100
    WRITE (6,1190)

    DO 90 I=1,343
    IJ = I+343
    IK = IJ+343
    IL = IK+343
    IM = IL+343
    IO = IM+343
    IP = IO+343
    WRITE (6,1200) I,X(I),IJ,X(IJ),IK,X(IK),IL,X(IL),IM,X(IM),
1,IO,X(IO),IP,X(IP)

```

```

MAIN1380
MAIN1390
MAIN1400
MAIN1410
MAIN1420
MAIN1430
MAIN1440
MAIN1450
MAIN1460
MAIN1470
MAIN1480
MAIN1490
MAIN1500
MAIN1510
MAIN1520
MAIN1530
MAIN1540
MAIN1550
MAIN1560
MAIN1570
MAIN1580
MAIN1590
MAIN1600
MAIN1610
MAIN1620
MAIN1630
MAIN1640
MAIN1650
MAIN1660
MAIN1670
MAIN1680
MAIN1690
MAIN1700
MAIN1710
MAIN1720
MAIN1730
MAIN1740
MAIN1750
MAIN1760
MAIN1770
MAIN1780
MAIN1790
MAIN1800
MAIN1810
MAIN1820
MAIN1830
MAIN1840
MAIN1850

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MAIN1860
 MAIN1870
 MAIN1880
 MAIN1890
 MAIN1900
 MAIN1910
 MAIN1920
 MAIN1930
 MAIN1940
 MAIN1950
 MAIN1960
 MAIN1970
 MAIN1980
 MAIN1990
 MAIN2000
 MAIN2010
 MAIN2020
 MAIN2030
 MAIN2040
 MAIN2050
 MAIN2060
 MAIN2070
 MAIN2080
 MAIN2090
 MAIN2100
 MAIN2110
 MAIN2120
 MAIN2130
 MAIN2140
 MAIN2150
 MAIN2160
 MAIN2170
 MAIN2180
 MAIN2190
 MAIN2200
 MAIN2210
 MAIN2220
 MAIN2230
 MAIN2240
 MAIN2250
 MAIN2260
 MAIN2270
 MAIN2280
 MAIN2290
 MAIN2300
 MAIN2310
 MAIN2320
 MAIN2330

```

90 CONTINUE
C
C   COMPUTE WEAPON HORIZON
C
100 IF (X(81).GT.0.) GO TO 110
   X(81) = 1.23
C
110 DO 120 I=2002,2192,10
   IF (X(I-1).EQ.0.) GO TO 130
   IK = I+7
   X(IK) = X(81)*SQRT(X(I))
120 CONTINUE
C
C   CHANGE TRUE ANGLES TO CARTESIAN FOR SHIPS
C   SET SAM VELOCITY TO NM/MIN
C
130 IN = IFIX(X(78)+AMF)
   DO 140 I=1,10
   ID = 502+(I-1)*40
   IK = ID+7
   IF (X(ID-1).EQ.0.) GO TO 150
   X(ID) = X(ID)/60.
   X(IK) = X(IK)/60.
140 CONTINUE
C
C   CONVERT RADAR BEAM WIDTH TO 1/2 BEAM WIDTH IN RADIAN
C   AND REPLACE SIDELOBE COEFFICIENT IN -DB WITH DIRECTIVE LOSSES
C
150 RAT = .8726646D-2
   DO 160 NN=1,15
   NX = 20*(NN-1)
   IF (X(903+NX).EQ.0.) GO TO 170
   BWR = DBLE(X(911+NX))*RAT
   X(911+NX) = BWR
   BWR = X(904+NX)
   X(904+NX) = 10.**-(BWR/10.)
160 CONTINUE
C
170 NS = IFIX(X(88)+AMF)
   IF (IN.EQ.1) GO TO 190
C
C   DO 180 I=1,NS
C   IX = 5*(I-1)+1203
C   X(IX) = 450.-X(IX)
C   IF (X(IX).GE.360.) X(IX)=X(IX)-360.
180 CONTINUE

```


MAIN2340
 MAIN2350
 MAIN2360
 MAIN2370
 MAIN2380
 MAIN2390
 MAIN2400
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 MAIN2450
 MAIN2460
 MAIN2470
 MAIN2480
 MAIN2490
 MAIN2500
 MAIN2510
 MAIN2520
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 MAIN2780
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 MAIN2800
 MA

CHANGE RAIDER BEARINGS AND COURSES TO CARTESIAN
 FIGURE FOURTH ROOT OF RAIDER AND WEAPON CROSS SECTION
 CHANGE KNOTS TO NM/MIN
 COMPUTE 1/2 JAMMER BEAM WIDTH IN RADIAN
 REPLACE SIDELobe COEFFICIENT IN -DB WITH DIRECTIVE LOSSES

```

190 DO 200 I=1,10
    IX = 20*(I-1)
    IF (X(IX+1815).EQ.0.) GO TO 210
    X(IX+1814) = X(1814+IX)/60.
    RRC = DBLE(X(IX+1815))
    X(IX+1816) = DSQRT(RRC)
    IF (X(IX+1817).EQ.0.) GO TO 200
    BWJ = DBLE(X(IX+1817))*RAT
    X(IX+1817) = BWJ
    X(IX+1818) = X(IX+1818)
    X(IX+1818) = 10.**{(BWJ/10.)
200 CONTINUE
  
```

```

210 DO 220 I=1,20
    IX = (I-1)*10
    IF (IX+2001.EQ.0.) GO TO 230
    X(IX) = X(IX)/60.
    RRC = DBLE(X(IX+2006))
    X(IX+2010) = DSQRT(RRC)
220 CONTINUE
  
```

```

C 230 NR = IFIX(X(89)+AMF)
C
DO 240 I=1,NR
IX = (I-1)*6
IF (X(IX+2205).GE.360.) X(IX+2205) = X(IX+2205) - 360.
IF (X(IX+2203).GE.360.) X(IX+2203) = X(IX+2203) - 360.
IF (X(IX+2203).GE.360.) X(IX+2203) = X(IX+2203) - 360.
240 CONTINUE
  
```

```

C READ (5,1210) NRTGT
IF (X(12).EQ.0.) GO TO 260
C
DO 250 I=1,10
IA = I+10
IB = I+20
  
```


MAIN2820
 MAIN2830
 MAIN2840
 MAIN2850
 MAIN2860
 MAIN2870
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 MAIN2970
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 MAIN2990
 MAIN3000
 MAIN3010
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 MAIN3030
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 MAIN3070
 MAIN3080
 MAIN3090
 MAIN3100
 MAIN3110
 MAIN3120
 MAIN3130
 MAIN3140
 MAIN3150
 MAIN3160
 MAIN3170
 MAIN3180
 MAIN3190
 MAIN3200
 MAIN3210
 MAIN3220
 MAIN3230
 MAIN3240
 MAIN3250
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 MAIN3270
 MAIN3280
 MAIN3290

```

IC = I+30
IE = I+40
IEE = I+50
IF = I+60
IH = I+70
IH = I+80
WRITE (6,1220) I, NRIGT(I), IA, NRIGT(IA), IB, NRIGT(IB), IC, NRIGT(IC), I
1D, NRIGT(ID), IE, NRIGT(IE), IF, NRIGT(IF), IG, NRIGT(IG), IH, NRIGT(IH)
250 CONTINUE
C
WRITE (6,1240)
260 READ (5,1230) PLIST
IF (X(12).EQ.0.) GO TO 280
C
DO 270 I=1,40
WRITE (6,1250) I, PLIST(I,1), I, PLIST(I,2), I, PLIST(I,3), I, PLIST(I,4),
I, PLIST(I,5), I, PLIST(I,6)
270 CONTINUE
C
DO 280 I=1, NS
IX = 5*(I-1)+1204
X(IX) = 450.-X(IX)
IF (X(IX).GE.360.) X(IX)=X(IX)-360.
X(IX+1) = 450.-X(IX+1)
IF (X(IX+1).GE.360.) X(IX+1)=X(IX+1)-360.
C
DO 290 K=1,19
NADAR(I,K) = 0
CONTINUE
C
SET THE SHIP TABLE
IJ = 1201+(I-1)*5
IK = IJ+1
IL = IK+1
IM = 101+(X(IJ)-1)*40
SHIP(I,1) = X(IJ)
IF (IN.EQ.0) GO TO 300
SHIP(I,2) = X(IK)
SHIP(I,3) = X(IL)
GO TO 310
300 RAT = DBLE(X(IL))
RD = RADIAN(RAT)
SHIP(I,2) = X(IK)*COS(RD)
SHIP(I,3) = X(IK)*SIN(RD)
310 IS = IM+20
SHIP(I,4) = X(IS)
  
```


MAIN3300
 MAIN3310
 MAIN3320
 MAIN3330
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 MAIN3370
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 MAIN3410
 MAIN3420
 MAIN3430
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 MAIN3480
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 MAIN3690
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 MAIN3720
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 MAIN3750
 MAIN3760
 MAIN3770

```

C      SHIP(I,5) = FLOAT(IM)
C      IT = X(IM)
C
C      DO 320 K=1,4
C      IBAT(I,K) = 0
C      CONTINUE
C
C      IF (II.GT.0) GO TO 330
C      SHIP(I,6) = 0.
C      GO TO 340
C      SHIP(I,6) = 1.
C      CONTINUE
C
C      DO 360 I=1,10
C
C      DO 350 J=1,3
C      ND = 120+(I-1)*40+J*2
C      X(ND) = 450.-X(ND)
C      IF (X(ND).GE.360.) X(ND)=X(ND)-360.
C      X(ND+1) = 450.-X(ND+1)
C      IF (X(ND+1).GE.360.) X(ND+1)=X(ND+1)-360.
C      CONTINUE
C
C      CONTINUE
C
C      THE INITIAL RAID TABLE
C
C      IF (X(55).EQ.0.) GO TO 370
C      CALL SETIMX
C
C      DO 490 I=1,NR
C      IJ = 2201+(I-1)*6
C      IK = IJ+1
C      IL = IJ+2
C      IM = IJ+3
C      IN = IJ+4
C      IT = IFIX(X(IJ)+AMF)
C      JJC = 1801+(I-1)*20
C      VELR = X(JJC+13)
C      RAID(I,1) = FLOAT(JC)
C      ALFA = DBLE(X(IL))
C      RAT = RADIAN(ALFA)
C      COSI = DCOS(RAT)
C      SINI = DSIN(RAT)
C      RAID(I,2) = 0.
C      RAID(I,3) = DBLE(X(IK))*COSI
C      RAID(I,4) = DBLE(X(IK))*SINI
  
```


MAIN3780
 MAIN3790
 MAIN3800
 MAIN3810
 MAIN3820
 MAIN3830
 MAIN3840
 MAIN3850
 MAIN3860
 MAIN3870
 MAIN3880
 MAIN3890
 MAIN3900
 MAIN3910
 MAIN3920
 MAIN3930
 MAIN3940
 MAIN3950
 MAIN3960
 MAIN3970
 MAIN3980
 MAIN3990
 MAIN4000
 MAIN4010
 MAIN4020
 MAIN4030
 MAIN4040
 MAIN4050
 MAIN4060
 MAIN4070
 MAIN4080
 MAIN4090
 MAIN4100
 MAIN4110
 MAIN4120
 MAIN4130
 MAIN4140
 MAIN4150
 MAIN4160
 MAIN4170
 MAIN4180
 MAIN4190
 MAIN4200
 MAIN4210
 MAIN4220
 MAIN4230
 MAIN4240
 MAIN4250

```

IU = IFIX(X(JC+3)+AMF)
RRK = DBLE(X(82))*VELR)
RRAT = RADIAN(RRK)
RAID(I,5) = RRK*DCOS(RAT)+RAID(I,3)
RAID(I,6) = RRK*DSIN(RAT)+RAID(I,4)
IF (IU.GT.0) GO TO 390
RAID(I,7) = RAID(I,5)
RAID(I,8) = RAID(I,6)
GO TO 450
IX = IFIX(X(JC+5)+AMF)
IW = 2003+(IU-1)*10
IF (IW.EQ.0) GO TO 400
IY = 2003+(IW-1)*10
IF ((X(IX)-X(IY)).LT.0.) GO TO 410
RK = X(IX)
RB = X(IY)
GO TO 420
KK = X(IX)
GO TO 430
RK = X(IX)
GO TO 440
CALL TMDROM (I, RB, T)
RAID(I,16) = T, RK, T)
CALL TMDROM (I, RK, T)
GO TO 380
IF (T.EQ.0.) GO TO 440
CALL LOCTIM (I, T,3,XX,YY)
RAID(I,7) = XX
RAID(I,8) = YY
GO TO 450
RAID(I,7) = RAID(I,3)
RAID(I,8) = RAID(I,4)
GO TO 450
RAID(I,9) = X(IM)
RAID(I,10) = X(81)*SQRT(X(IM))
IF (IU.EQ.0) GO TO 470
IF (IW.EQ.0) GO TO 460
IF (X(IX).GT.X(IY)) GO TO 460
RAID(I,11) = X(JC+5)
GO TO 480
RAID(I,11) = X(JC+3)
GO TO 480
RAID(I,11) = 0.
RAID(I,12) = X(JC+2)+X(JC+4)
490 CONTINUE
IF (X(24).EQ.2..OR.X(24).EQ.3.) CALL DISPL
  
```

380
 390
 400
 410
 420
 430
 440
 450
 460
 470
 480
 490

C

MAIN4260
 MAIN4270
 MAIN4280
 MAIN4290
 MAIN4300
 MAIN4310
 MAIN4320
 MAIN4330
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 MAIN4730

```

C IF (X(24).EQ.1..OR.X(24).EQ.3.) CALL RAIDIS
C GET THE NUMBER OF SAM IN THE FLEET
C NMIF = 0
C
C DC 510 L=1,NS
C IF (SHIP(L,6).EQ.0.) GO TO 510
C IT = IFIX(SHIP(L,5)+AMF)
C
C DO 500 K=1,4
C IF (X(IT-1+K).EQ.0.) GO TO 510
C MT = IFIX(X(IT-1+K)+AMF)
C NT = 527+(MT-1)*40
C NMIF = NMIF+IFIX(X(NT)+AMF)
C 500 CONTINUE
C
C 510 CONTINUE
C
C X(75) = FLGAT(NMIF)
C WRITE (6,1260) NMIF
C IF (X(2).EQ.1.) GO TO 610
C
C DO 600 I=1,NS
C IS = IFIX(SHIP(I,5)+AMF)
C
C DO 520 J=4,6
C K = J-3
C IF (X(IS+J).EQ.0.) GO TO 530
C NADAR(I,K) = 1
C 520 CONTINUE
C
C 530 DO 590 J=1,4
C IP = IFIX(X(IS+J-1)+AMF)
C IF (IP.EQ.0) GO TO 600
C
C DO 570 L=1,3
C IA = IFIX(X(516+(IP-1)*40+2*L)+AMF)
C IF (IA.GT.0) GO TO 560
C GO TO (540,580,580), L
C
C 540 DO 550 LK=1,3
C NADAR(I,(3+(J-1)*3+LK))=2
C 550 CONTINUE
C
C GO TO 580
C 560 NADAR(I,(3+(J-1)*3+L))=1
  
```


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 MAIN5200
 MAIN5210

```

570 CONTINUE
580 NADAR(I, (15+J)) = I
590 CONTINUE
600 CONTINUE
610 IF (X(15).EQ.0.0) GO TO 630
    WRITE (6,1180)
    DO 620 I=1,343
      IJ = I+343
      IK = IJ+343
      IL = IK+343
      IN = IL+343
      IO = IN+343
      WRITE (6,1200) I, X(IL), IJ, X(IJ), IK, X(IK), IL, X(IL), IM, X(IM), IN, X(IN)
    I, IO, X(IO), IP, X(IP)
620 CONTINUE
    START THE GAME
630 DO 990 I=1,NI
      KOUNT = I
      CALL EFFECT
      IJ = IFIX(X(75)+AMF)
      WRITE (6,1270) KOUNT, IJ
      WRITE (6,1280) KOUNT
    PRINT THE ASM TABLE
    WRITE (6,1290)
    DO 640 L=1,NASM
      LA = L+90
      WRITE (6,1300) LA, (ASMT(L, J), J=1,8)
    CONTINUE
    IM = 0
640 CONTINUE
    DO 650 L=1,NR
      IF (RAID(L,13).GT.0.) IM=IM+1
    CONTINUE
650 CONTINUE
    WRITE (6,1310) NR, IM
    WRITE (6,1320)
  
```



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```

C      WRITE (6,1330) ((SAMASM(L,J),J=1,6),L=1,NSAM)
C      FORMULATE THE STATISTICS FOR EACH ITERATION
C
ILF = 0
ILS = 0
IKS = 0
ITS = 0
IMF = 0
C
DO 720 L=1,NASM
IL = IFIX(ASMT(L,1)+AMF)
IL = IL+1
GO TO (660,670,680,690,700,710), IL
660 GO TO ILF+1
670 GO TO ILS+1
680 GO TO IKS+1
690 GO TO ITS+1
700 GO TO ITS+1
710 GO TO IMF+1
720 CONTINUE
C
X(61) = X(61)+FLOAT(NASM)
X(62) = X(62)+FLOAT(ILF)
X(63) = X(63)+FLOAT(IKS)
X(64) = X(64)+FLOAT(IMF)
X(65) = X(65)+FLOAT(ILS)
X(70) = X(70)+FLOAT(ITS)
WRITE (6,1340) KOUNT,ITS
IF (IM.NE.0) GO TO 730
PI = 0.
PC2 = 0.
PC3 = 0.
GO TO 740
PC1 = (FLOAT(IM)+PC1)/PC1*100.
PC2 = (FLOAT(IM)-FLOAT(ILF))/PC2*100.
PC3 = (FLOAT(IKS)+PC3)/PC3*100.
PC4 = (FLOAT(NASM)+PC4)
730
740

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PC5 = (FLOAT(IMF)/PC4)*100.
WRITE (6,1350) IM,ILF,PI,IKS,PC2,IIF,PC3
WRITE (6,1360) IMF,PC5
JL = 0
IL = 0
IF (NSAM.EQ.0) GO TO 770
DO 760 L=1,NSAM
  IFIX(SAMASM(L,5))
  IF (IN.NE.-1) GO TO 750
  IL = IL+IFIX(SMAT(L,10))+AMF)
GO TO 760
IF (IN.NE.0) GO TO 760
  JL = JL+IFIX(SMAT(L,10))+AMF)
760 CCNTINUE
C
X(66) = X(66)+FLOAT(IK)
X(67) = X(67)+FLOAT(JL)
X(68) = X(68)+FLOAT(IL)
PC1 = FLOAT(JL)
PC2 = (PC1/FLOAT( IK))*100.
PC3 = (PC2/FLOAT( IK))*100.
WRITE (6,1370) IK,JL,PC2,IL,PC3
GO TO 780
770 WRITE (6,1060)
780 IT = IFIX(X(13)+AMF)
  WRITE (6,1380) IT
  X(14) = X(14)+X(13)
  X(13) = 0.
C
      DG THE SUMMARY STATISTICS FOR ITERATIONS COMPLETED
C
WRITE (6,1390) KOUNT
IM = IFIX(X(61)+AMF)
IMF = IFIX(X(65)+AMF)
IM = IM-IMF
IF (IM.GT.0) GO TO 790
PC1 = 0.
PC2 = 0.
PC3 = 0.
IMK = 0
IML TO 800
GO TO 800
790 PC1 = (X(62)/FLOAT(IM))*100.
  PW = FLOAT(IM)-X(62)
  IMK = IFIX(X(63)+AMF)

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MAIN6180
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```

PC2 = (X(63)/PW)*100.
IML = (X(64)/PW)+AMF.
PC3 = (X(64)/PW)*100.
800 ILF = (X(65)/X(61))*100.
PC4 = (6,1350) IML, ILF, PC1, IML, PC2, IML, PC3
WRITE (6,1360) IML, ILF, PC4
HITS = X(70)/FLOAT(KOUNT)
WRITE (6,1400) KOUNT, HITS
IF (X(66).EQ.0.) GO TO 810
IP1 = (X(67)+AMF)
IP2 = (X(68)+AMF)
PC1 = (X(67)/X(66))*100.
PC2 = (X(68)/X(66))*100.
810 WRITE (6,1370) IP, IP1, PC1, IP2, PC2
IT = (X(14)+AMF)
WRITE (6,1380) IT
WRITE (6,1410) KOUNT
WRITE (6,1420)
WRITE (6,1430)
WRITE (6,1080) (L, (JACK(L,ND),ND=1,7),L=1,NS)
C
DO 860 L=1,NS
IF (JACK(L,5).EQ.0) GO TO 820
USC = STATS(L,1)/FLOAT(JACK(L,5))
820 GO TO 830
USC = 0.
830 IF (JACK(L,7).EQ.0) GO TO 840
PC1 = STATS(L,2)/FLOAT(JACK(L,7))
GO TO 850
840 PC1 = 0.
850 WRITE (6,1090) L,USC,PC1
860 CONTINUE
C
WRITE (6,1070) IFAG,IFBG
WRITE (6,1100)
C
DO 870 L=1,NS
WRITE (6,1110) L,ISAG(L),ISBG(L)
870 CONTINUE
C
WRITE (6,1120)
C
DO 880 L=1,NS
WRITE (6,1130) L,IHIT(L)
880 CONTINUE
C

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C      DO 890 L=1,NS
      IJ = IHIT(L)
      MARY(IJ) = MARY(IJ)+1
      CONTINUE
C
C      890  IF (X(85).EQ.0.) GO TO 920
      L = IFIX(X(85)+AMF)
      HISX(I) = FLOAT(IHIT(L))
      TMA = 0
      TMIN = i0000.
C
C      DO 900 LL=1,NASM
      IF (ASMT(LL,1).NE.4.) GO TO 900
      IF (ASMT(LL,4).NE.X(85)) GO TO 900
      IF (ASMT(LL,2).LT.TMIN) TMIN=ASMT(LL,2)
      IF (ASMT(LL,2).GT.TMA) TMA=ASMT(LL,2)
      CONTINUE
C
C      900  IF (HISX(I).LE.1.) GO TO 910
      HISA(I) = TMA-TMIN
      HISO(I) = HISX(I)/HISA(I)
      GO TO 920
C
C      910  HISO(I) = 0.
      HISA(I) = 0.
      IF (KOUNT.GT.1) GO TO 980
      IJ = IFIX(X(51)+AMF)
      IF (IJ.EQ.0) GO TO 930
      WRITE (6,1440) (L,(SHIP(L,J),J=1,6),L=1,NS)
      IJ = IFIX(X(52)+AMF)
      IF (IJ.EQ.0) GO TO 940
      WRITE (6,1450) (L,(RAID(L,J),J=1,13),L=1,NR)
      IJ = IFIX(X(53)+AMF)
      IF (IJ.EQ.0) GO TO 950
      WRITE (6,1460)
      WRITE (6,1470) (L,(SMAT(L,J),J=1,10),L=1,NSAM)
      IJ = IFIX(X(54)+AMF)
      IF (IJ.EQ.0) GO TO 970
      X(54) = 0
      WRITE (6,1480)
      IS = IFIX(X(14)+AMF)
C
C      DO 960 L=1,IS
      CALL RANDOM (INSECT,Z,1)
      WRITE (6,1490) Z
      CONTINUE
C
C      960
C      970 X(55) = 0.
  
```



```

11090 110X, 'ASMS'//))
11100 1090, 'I3, 7X, F9.2, 7X, F9.2) BOMBERS FIRED AT'//)
11110 1100, 'SHIP ASMS FIRED AT
11120 1110, 'I13, I19)
11130 1120, 'I15)
11140 1130, 'I47X, 'FINAL STATISTICS'//(' , 10('NO. OF', 6X))
11150 1140, 'I10('HITS FREQ. ')
11160 1150, 'I10('I4, I6, 1X))
11170 1160, 'I10, 5F10.3)
11180 1170, 'I1, 45X, 'THE X ARRAY AFTER CONVERSION'//, 8(' ADR CONTENT
11190 1180, 'I1, 48X, 'THE X ARRAY AS READ IN'//, 8(' ADR CONTENT '))
1200 1190, 'I15, F10.2))
1210 1200, 'I8('I12)
1220 1210, 'I9('I13, I2, 5X))
1230 1220, 'I10, F8.4)
1240 1230, 'I10, 39X, 'THE TARGET LISTS'//(' SHIP C-PROB '))
1250 1240, 'I6('I5, F7.4, 2X))
1260 1250, 'I10, 'NMIF IS', I6)
1270 1260, 'I1, 'THE NUMBER OF SAMS LEFT AT THE END OF ITERATION', I3,
1 WAS: I5//)
1280 1270, 'I10, 55X, 'ASM TABLE'//('55X, 'ITERATION ', I2//('26X, 'ASM
1 STATUS TIME OF LAUNCH TARGET LAUNCH WEAPON X SHIP. TIME C
1290 1280, 'I1, 24X, 'NUMBER CODE IMPACT RAID SHIP. TIME C
1 LAUNCH LAUNCH'//)
1300 1290, 'I10, 25X, I3, F8.0, F8.3, 2F8.0, F9.2, F6.0, 2F10.2)
1310 1300, 'I10, 'THE ORIGINAL ATTACK CONSISTED OF', I3, ' RAIDERS.
1, I3, 'WERE LEFT AFTER THE ATTACK'//)
1320 1310, 'I10, 49X, 'SAM-ASM-RAID KILL CODE LAUNCHER
1 CHANNEL TIME OF LAUNCH TIME CHANNEL FREE'//)
1330 1320, 'I20X, F7.0, F10.0, F12.0, F14.0, F16.2, F14.0, F21.2)
1340 1330, 'I1, 10X, 'STATISTICS FOR ITERATION NO.', I4//('20X, 'THE SHIPS
1 TOOK', I5, 'HITS. '))
1350 1340, 'I20X, 'OF', I5, ' ASMS FIRED', I5, ' ('F6.2, ' PERCENT) FAILED
1 AT LAUNCH, I20X, 'OF LAUNCHED ASM', I5, ' ('F6.2, ' PERCENT) WERE
2 ILL BY SAMS, I38X, 'I5, ' ('F6.2, ' PERCENT) FAILED IN FLIGHT', I3))
1360 1350, 'I20X, 'OF THE TOTAL ASMS AVAILABLE', I5, ' ('F6.2, ' PERCENT)
1 WERE DESTROYED WHEN', I62X, 'MOTHER KILLED BY SAMS', I3))
1370 1360, 'I10, 16X, I4, ' SAMS WERE LAUNCHED OF WHICH', I4, ' ('F6.2, '
1 PERCENT) FAILED AND', I50X, I4, ' ('F6.2, ' PERCENT) WERE OVERKILLS.
2))
1380 1370, 'I10, 'RANDOM NUMBERS WERE DRAWN', I3))
1390 1380, 'I10, 'SUMMARY FOR', I3, ' ITERATIONS',
1400 1390, 'I10, 'AVERAGE NUMBER OF HITS ON FLEET FOR', I3, ' ITERA
1 TIONS IS: F6.2//)
1410 1400, 'I10, 'SHIP STATS FOR ITERATION', I3)
1420 1410, 'I10, 'SHIP CHANCES FOR ITERATION', I3) TARGETS BOMBERS

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MAIN7990
MAIN8000
MAIN8010
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MAIN8030
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MAIN8070
MAIN8080
MAIN8090

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1 KILLED ASMS, 9X, ASMS, / ( , NO DEFECTABLE TO ENGAGE ENGAGEMENTS
2 KILLED DETECTABLE DETECTED DETECTED, / ) )
1430 FORMAT ( , I4, I10, I11, I13, I10, I13, I9, I11 )
1440 FORMAT ( , SHIP CLASS HITS TO SINK CLA-ADR
1450 UP/DOWN, / ( , I4, F7, 0, F10, 2, F10, 2, F9, J, F12, 0, F11, 0 ) )
1450 FCRMAT XL RAIDER, CLASS HORZ WEP-CLASS XR XEOG Y
1460 F10, 0, F9, 2, F7, 1, 3F8, 1, 2F7, 1, F8, 1, F7, 0, F10, 0, F8, 0, F7, 0 ) )
1470 F10, 0, F9, 2, F7, 1, 3F8, 1, 2F7, 1, F8, 1, F7, 0, F10, 0, F8, 0, F7, 0 ) )
1480 CH1 FREE CH2 FR SAM CH3 FR CH4 FR CLASS INDEX SHIP NUMBER SAM LEFT
1490 F10, 0, F9, 2, F7, 1, 3F8, 1, 2F7, 1, F8, 1, F7, 0, F10, 0, F8, 0, F7, 0 ) )
1500 F10, 0, F9, 2, F7, 1, 3F8, 1, 2F7, 1, F8, 1, F7, 0, F10, 0, F8, 0, F7, 0 ) )
END

```

```

SUBROUTINE EFFECT
THIS SUBROUTINE CONTROLS EACH ITERATION
COMMON X(2744), ASMT(100, 8), SAMASM(300, 7), RAID(90, 17), SHIP(40, 6), SMEEFT
1AT(300, 10), IVENTS(1000, 2), STATS(40, 2), IBAT(40, 4), NJND(190, 40), ISEEEFT
2M, MAMBA, KOUNT, NADAR(40, 19), RXATA(5), LUVER, ITEMS, PLIST(40, 6), REAS,
3RI(50), IFLASK, IGA(190), ISAG(40), IFAG, ISBG(40), NR, NS,
4MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), TCF(6), IHIT(4
5), AMF, HISX(100), JACK(40, 7), HISA(100)
IF ( IJ.EQ.0 ) GO TO 20
CALL GETIMX ( IET )
TIMES = IET*.000026
WRITE ( 6, 130 ) TIMES
CALL JULIE ( TIME, NEXTEV, IUNIT )
30 IF ( NEXTEV.EQ.0 ) GO TO 100
IF ( NEXTEV.GT.6 ) GO TO 120
GO TO ( 40, 50, 60, 70, 80, 90 ), NEXTEV
CALL SUBEL. ( TIME, IUNIT )
40 GO TO 30
CALL SUBE2 ( TIME, IUNIT )
50 GO TO 30
CALL SUBE3 ( TIME, IUNIT )
60 GO TO 30
CALL SUBE4 ( IUNIT )
70 GO TO 30
CALL SUBE5 ( IUNIT )
80 GO TO 30

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CC


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320 TTTTTTTTTTTTTTTT
330 EEEEEEEEEEEEEEE
340 EEEEEEEEEEEEEEE
350 EEEEEEEEEEEEEEE
360 EEEEEEEEEEEEEEE
370 EEEEEEEEEEEEEEE
380 EEEEEEEEEEEEEEE
390 EEEEEEEEEEEEEEE
400 EEEEEEEEEEEEEEE
410 EEEEEEEEEEEEEEE
420 EEEEEEEEEEEEEEE
430 EEEEEEEEEEEEEEE
440 EEEEEEEEEEEEEEE
450 EEEEEEEEEEEEEEE

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```

90 CALL SUBE6 (IUNIT)
GO TO 30
100 IF (IJEQ.0) GO TO 110
CALL GETIMX (IET)
TIMES = IET*.000026
WRITE (6,140) TIMES
110 RETURN
120 WRITE (6,150) NEXTEV
STOP
C
130 FORMAT ('0',, EFFECT LOGIN AT ',F11.7)
140 FORMAT ('0',, EFFECT LOGOUT AT ',F11.7)
150 FORMAT ('0',,** NON-EXISTENT EVENT CALLED *** TYPE ',I3)
END

```

```

10 JJJJJJJJJJJJJJJ
120 JJJJJJJJJJJJJJJ
130 JJJJJJJJJJJJJJJ
140 JJJJJJJJJJJJJJJ
150 JJJJJJJJJJJJJJJ
160 JJJJJJJJJJJJJJJ
170 JJJJJJJJJJJJJJJ
180 JJJJJJJJJJJJJJJ
190 JJJJJJJJJJJJJJJ
200 JJJJJJJJJJJJJJJ
210 JJJJJJJJJJJJJJJ
220 JJJJJJJJJJJJJJJ
230 JJJJJJJJJJJJJJJ
240 JJJJJJJJJJJJJJJ
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270 JJJJJJJJJJJJJJJ
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300 JJJJJJJJJJJJJJJ
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SUBROUTINE JULIE
THIS SUBROUTINE INITIALIZES OR RESETS ITEMS REQUIRED
TO BE RESET FOR EACH ITERATION.
REAL *8RAT,BNG,RAN
COMMON X(27+4),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SMJULG
1AT(300,10),EVENTS(100,2),STATS(40,2),IBAR(40,4),NONDU(190,40),ISEEJL
2AT,MAMBAT,KOUNT(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASQJL
3NT,CHANNEL(40,4,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFT(90,2),NR,NS,
4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELOAD(40,4),
5MARY(100),CHECK,IFIRST,NPGS,KMART(4),NSAM,IGTAV(190),THIT(4
60),AMP,HISX(100),JACK(40,7),HISA(100)
IF (X(55).EQ.(IET)
CALL GETIMX (IET)
TIMES = IET*.000026
WRITE (6,530) TIMES
CALL EVENT
IFIRST = 0
NASM = 0
IFLASK = 0
ITEMS = 0
NSAM = 0
IFAG = 0
IFBG = 0
20 SET CHANNEL ARRAY TO ZERO
DO 60 I=1,NS
DO 50 J=1,4

```


C	190	CONTINUE	JL
C	200	CONTINUE	JL
C	IF (X(2).EQ.0.)	GO TO 450	JL
C	IF THE FLAG IS SET,	THE AVAILABILITY OF ALL RADARS AND	JL
C	LAUNCHERS IS DETERMINED	FOR EACH ITERATION. IF ALL	JL
C	SEARCH RADARS ARE DOWN,	THE ROUTINE CHECKS TO SEE IF	JL
C	THE FIRE CONTROL RADARS	ARE TO SEE IF AT	JL
C	THIS TIME IT WILL ALSO	CHECK TO SEE IF THE MISSILES ARE	JL
C	PASSIVE (HOJ OR ARM) OR	IF THEY REQUIRE A REMOTE ILLUM-	JL
C	INATOR.		JL
C	DOES SHIP I HAVE A	MISSILE SYSTEM? NO GO TO 540	JL
C	DO 440	I=1,NS	JL
C	IF (SHIP(I,6).EQ.0.)	GO TO 440	JL
C	IS = IFIX(SHIP(I,5)+AMF)		JL
C	IFOG = 0		JL
C	WRITE (6,550) I		JL
C	KFOG = 0		JL
C	CHECK FOR AT LEAST	ONE UP SEARCH RADAR	JL
C	DO 220	J=4,6	JL
C	K = J-3		JL
C	IF IX(X(IS+J)+AMF)		JL
C	IF (IT.EQ.0)	GO TO 230	JL
C	PROB = X(913+{(IT-1)*20)		JL
C	CALL RANDOM(ISEED,Z,I)		JL
C	X(I5) = X(I3)+I		JL
C	IF (Z.GT.PRQB)	GO TO 210	JL
C	KFOG = 1		JL
C	WRITE (6,560) K		JL
C	NADAR(I,K) = 1		JL
C	GO TO 220		JL
C	210	WRITE (6,570) K	JL
C	220	NADAR(I,K) = 0	JL
C	230	IF (KFOG.EQ.1) GO TO 270	JL
C	CONTINUE		JL

1770 JLEEE
 1780 JLEEE
 1790 JLEEE
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 2190 JLEEE
 2200 JLEEE
 2210 JLEEE
 2220 JLEEE
 2230 JLEEE
 2240 JLEEE

```

C 240 J=1,4
    DO 240 J=1,4
      IF IX(X(IS+J-1)+AMF)
        IP = IP.EQ.0) GO TO 260
      IF (IP.EQ.0) GO TO 260
      IC = IF IX(X(518+(IP-1)*40)+AMF)
      IF (IC.NE.0) GO TO 250
    CONTINUE
  240
C 250 IF (X(7).EQ.1.) GO TO 270
    250 SHIP(I,6) = 0.
    260 GO TO 440
C 270 DO 390 J=1,4
    IP = X(IS+J-1)
    IF (IP.EQ.0) GO TO 390
C 280 DO 380 L=1,3
    IA = IF IX(X(516+(IP-1)*40+2*L)+AMF)
    IF (IA.GT.0) GO TO 300
    GO TO (280,390,390), L
    IFOG = I
    280 WRITE (6,580) J
C 290 DO 290 LK=1,3
    NADAR(I, (3+(J-1)*3+LK))=2
    CONTINUE
C 300 GO TO 390
    PROB = X(913+(IA-1)*20)
    CALL RANDOM (ISEED,Z,I)
    X(I3) = X(I3)+I
    IF (PROB.GT.Z) GO TO 320
    NADAR(I, (3+(J-1)*3+L))=0
    310 WRITE (6,590) L, J
    GO TO 380
    320 IF (KFOG.EQ.0) GO TO 330
    NADAR(I, (3+(J-1)*3+L))=1
    330 WRITE (6,600) L, J
    IFOG = I
    GO TO 380
    340 IF IX(X(523+(IP-1)*40)+AMF)
      GO TO (340,350,360), L
    350 IF (ID.EQ.1.OR.ID.EQ.11.OR.ID.EQ.101.OR.ID.EQ.111) GO TO 370
    360 IF (ID.EQ.10.OR.ID.EQ.110.OR.ID.EQ.110) GO TO 370
    370 IF (ID.EQ.100.OR.ID.EQ.101.OR.ID.EQ.110.OR.ID.EQ.111) GO TO 370
    380 IF (ID.EQ.310
  
```



```

MAMBAT = 0
DO 480 I=1,NS
DO 470 J=16,19
MAMBAT = MAMBAT+NADAR(I,J)
CONTINUE
470 CONTINUE
480 CONTINUE
DO 500 I=1,NS
DO 490 J=1,4
RELOAD(I,J) = 0.
CONTINUE
490 CONTINUE
500 CONTINUE
IF (X(60).EQ.0.) GO TO 510
WRITE (6,650)
WRITE (8,660) (I,(IVENTS(I,J),J=1,2),I=1,LOVER)
510 IF (X(55).EQ.0.) GO TO 520
CALL GETIMX(IET)
TIMES = IET*.000026
WRITE (6,670) TIMES
RETURN
520
530 FORMAT ('0',' JULIE CALLED AT',F15.5)
540 FORMAT ('0','IBAT TABLE',/(,'5110'))
550 FORMAT ('0','EQUIPMENT STATS FOR SAM SHIP ',I3)
560 FORMAT ('0','RADAR ',I2,' UP,')
570 FORMAT ('0','RADAR ',I2,' DOWN,')
580 FORMAT ('0','SYSTEM',I2,' REQUIRES NO DEDICATED FC RADAR')
590 FORMAT ('0','FC RADAR',I2,' SYSTEM',I2,' UP,')
600 FORMAT ('0','FC RADAR',I2,' SYSTEM',I2,' UP,')
610 FORMAT ('0','FC RADAR',I2,' SYSTEM',I2,' OPERATING IN HORIZON SEARCH MODE,')
620 FORMAT ('0','SHIP DESIG NON-COMBAT DUE TO DOWN EQUIPMENT,')
630 FORMAT ('0','LAUNCHER',I2,' DOWN,')
640 FORMAT ('0','LAUNCHER',I2,' UP,')
650 FORMAT ('0','EVENTS LIST',/(, SLOT TIME CODE'))
660 FORMAT ('17,I12,I13)
670 FORMAT ('0',, JULIE OUT AT',F15.9)
END

```

```

EVT 10
SUBROUTINE EVENT

```


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 850
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 900
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 950
 960
 970

```

CALL GETIMX (IET)
TIMES = IET*.0000026
WRITE (6,230) TIMES
IETIM = IVENTS(I,1)
IVENTS(I,2)
HOTDOG = DFLOAT(IIVET)
NEXTEV = HOTDOG*.10D-8
TIME = .00100*IIM
IUNIT = NEXTEV*100000000
ITEMS = IIVET-IVEN
ITEMS+1
IF (X(60).EQ.0.) GO TO 70
WRITE (6,240) TIME;NEXTEV,IUNIT,ITEMS

C
70 DO 80 I=2,LOVER
   IVENTS((I-1),1) = IVENTS(I,1)
   IVENTS((I-1),2) = IVENTS(I,2)
80 CONTINUE

C
IVENTS(I,1) = 0
LOVER = LOVER-1
IF (X(55).EQ.0.) GO TO 90
CALL GETIMX (IET)
TIMES = IET*.0000026
WRITE (6,250) TIMES
90 RETURN

ENTRY STOREV(T, ID, NUMBER)

C
C THIS SUBROUTINE ENTRY STORES THE INDICATED EVENT IN
C ITS PROPER PLACE IN THE EVENTS STORE LIST.  INPUTS ARE
C
C T.....THE TIME OF THE EVENT
C ID.....THE TYPE OF EVENT
C NUMBER.....THE CODE FOR THE UNITS INVOLVED
C
C THE PROGRAM STORES THE EVENT BY TIME.  IN CASE OF TIES
C IT SORTS BY LOWEST EVENT TYPE.  IF THERE IS STILL A DUPLI-
C CATION IT RESORTS TO THE LARGEST "NUMBER".
C
C
C IQ = X(55)
IF (IQ.EQ.0) GO TO 100
CALL GETIMX (IET)
TIMES = IET*.0000026
WRITE (6,260) TIMES
IF (X(82).LT.1) GO TO 190
IF (LOVER.GE.100) GO TO 160
ICD = ID*100000000

```

60
 70
 80
 90
 100


```

C
ICDCE = ICDCE+NUMBER
IT = 1000*(I+.0005)
DO 110 I=1,1000
ITB = IVENTS(I,2)
IF (ITB.EQ.0) GO TO 130
ITM = IVENTS(I,1)
IF (IT.LT.ITM) GO TO 130
IF (IT.EQ.ITM) GO TO 120
CONTINUE
110 CONTINUE
C
WRITE (6,200)
STOP
IF (ITB.LT.ICDCE) GO TO 110
120 ILOVER = LOVER+1
IF (X(60).EQ.0.) GO TO 140
WRITE (6,270) IT,ICDCE,LOVER
C
DO 140 M=I,LOVER
MORE1 = IVENTS(M,1)
MORE2 = IVENTS(M,2)
IVENTS(M,1) = IT
IVENTS(M,2) = ICDCE
IT = MORE1
ICDCE = MORE2
CONTINUE
140 CONTINUE
C
GO TO 170
160 WRITE (6,280) T, ID, NUMBER
IF (I.EQ.0) GO TO 180
CALL GETIMX (IET)
TIMES = IET*.000026
WRITE (6,290) TIMES
RETURN
180 IF (X(60).EQ.1.) WRITE (6,300) T, ID, NUMBER
GO TO 170
C
FORMAT ('
EVENTS LIST ITERATED THROUGH ERROR')
FORMAT ('
EVENT IN AT',F15.8)
FORMAT ('
EVENT OUT AT',F15.8)
FORMAT ('
GETEV IN AT',F15.8)
FORMAT ('
GETEV DATA RETRIEVED THIS WAS, TIME',F7.3,'
EVENT TYPE',
I2,'
IUNIT', I12,'
GETEV OUT AT',F15.8)
FORMAT ('
STORED IN AT',F15.8)
FORMAT ('
EVENTS STORED')
FORMAT ('
EVENTS LISTED')
FORMAT ('
TAKE NOW',I5,'
EVENT LOST--TIME',F9.3,'
TYPE',I2,'
CODE IS',I10,'
THERE
EVENT',I9,'
OVERT
1450

```



```

1460 1ER 1000 EVENTS LISTED.'
1470 290 FORMAT ('0',, STOREV OUT AT',F15.8)
1480 300 FORMAT ('0',, EVENT LOST DUE TO TIME CONSTRAINT. TIME OF LOST
1490 1EVENT WAS',F15.4,' TYPE',I2,' CODE',I10)

```

```

RMV 10
RMV 20
RMV 30
RMV 40
RMV 50
RMV 60
RMV 70
RMV 80
RMV 90
RMV 100
RMV 110
RMV 120
RMV 130
RMV 140
RMV 150
RMV 160
RMV 170
RMV 180
RMV 190
RMV 200
RMV 210
RMV 220
RMV 230
RMV 240
RMV 250
RMV 260
RMV 270
RMV 280
RMV 290
RMV 300
RMV 310
RMV 320
RMV 330
RMV 340
RMV 350
RMV 360
RMV 370
RMV 380
RMV 390
RMV 400
RMV 410
RMV 420

```

```

SUBROUTINE REMOVE (IUNYT)
COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMRMV
IAT(300,10), IVENTS(1000,2), SATS(40,2), IBAT(40,4), NOND(190,40), ISSEERMV
2D,MAMBAT,KOUNT,NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASORMV
3N,CHANNEL(40,4,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFT(90,2),NR,NS,QORMV
4RT(50),IFLASK,IAGE(190),ISAG(40),IFAG,ISBG(40),IFBC,RELOAD(40,4),RRMV
5MARY(100),CHECK,IFIRST,NPGS,KMARI(4),NSAM,IGTAV(190),TCF(6),THIT(4)
60),AMF,HISX(100),JACK(40,7),HISA(100)
RMV 10
RMV 20
RMV 30
RMV 40
RMV 50
RMV 60
RMV 70
RMV 80
RMV 90
RMV 100
RMV 110
RMV 120
RMV 130
RMV 140
RMV 150
RMV 160
RMV 170
RMV 180
RMV 190
RMV 200
RMV 210
RMV 220
RMV 230
RMV 240
RMV 250
RMV 260
RMV 270
RMV 280
RMV 290
RMV 300
RMV 310
RMV 320
RMV 330
RMV 340
RMV 350
RMV 360
RMV 370
RMV 380
RMV 390
RMV 400
RMV 410
RMV 420

```

```

C THIS ENTRY REMOVES THE TARGET FROM THE EVENTS LIST THAT
C PRIOR HAS DETERMINED IS MORE THREATENING THAT THE ONE
C GIVEN IT BY SUBE3.
C
C IQ = X(55)
C IF (IQ.EQ.0) GO TO 20
C CALL GETIMX (IET)
C TIM = IET*2.6E-5
C WRITE (6,70) TIM
C
C 20 DO 30 I=1,LOVER
C 30 IF (IVENTS(I,2).EQ.IUNYT) GO TO 40
C CONTINUE
C
C WRITE (6,80) IUNYT
C WRITE (6,90) ((IVENTS(I,J),J=1,2),I=1,LOVER)
C STOP
C
C 40 DO 50 J=1,LOVER
C IVENTS(J,1) = IVENTS((J+1),1)
C IVENTS(J,2) = IVENTS((J+1),2)
C 50 CONTINUE
C
C LOVER = LOVER-1
C IF (IQ.EQ.0) GO TO 60
C CALL GETIMX (IET)
C TIM = IET*2.6E-5
C WRITE (6,100) TIM
C RETURN
C
C 70 FORMAT (' REMOVE IN AT',F15.8)
C 80 FORMAT ('0',,ERROR IN REMOVE IUNYT NOT FOUND',I10)/(RMV

```



```

1, EVENTS LIST IS (/))
90 FORMAT (2I14)
100 FORMAT (' REMOVE OUT AT',F15.8)

```

430
440
450

SUBROUTINE TARGET (TYME,IUNIT,MORE)

```

COMMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SMITGT
IAT(300,10),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NONO(190,40),ISEEIGT
2D,MAMBAT,KOUNT,NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASOIGT
3N,CHANEL(40,4,3,6),NASM,JAM(4),TMAX,NKIGT(90,2),NR,NS,QTIGT
4RT(50),IFLASK,IGAGE(190),ISSAG(40,4),IFAG,ISBG,RELOAD(40,4),TIGT
5MARY(100),CHECK,IFIRST,NPGS,KMART(4),NSAM,IGTAV(190),TGF(6),IHIT(4
60),AMF,HISX(100),JACK(40,7),HISA(100)

```

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THIS ENTRY CHECKS THE EVENTS LIST TO SEE IF THERE IS A CANDIDATE FOR EVALUATION BY PRIOR

```

C  
C  
C  

IQ = X(55)
IF (IQ.EQ.0) GO TO 20
CALL GETIMX (IET)
T = IET*2.6E-5
WRITE (6,70) T
20 IF (IET.NE.0) GO TO 30
IFIRST = 1
MORE = 1
NPGS = 1
30 IF (IVENTS(NPGS,1).NE.I) GO TO 60
IF (IVENTS(NPGS,2).LT.3000000000.OR.IVENTS(NPGS,2).GE.4000000000) GO
1 TO 60
IUNIT = IVENTS(NPGS,2)
NPGS = NPGS+1
40 IF (IQ.EQ.0) GO TO 50
CALL GETIMX (IET)
T = IET*2.6E-5
WRITE (6,80) T
50 RETURN = 0
60 IFIRST = 0
MORE = 0
GO TO 40

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400

TARGET IN AT,F15.8)
TARGET OUT AT,F15.8)
END

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360
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SUBROUTINE SUBE1 (TIME,IR)

10


```

C C C THIS SUBROUTINE INPUTS THE RAIDER NUMBER AND TIME OF THE EVENT,
C C C AND WILL STORE SHOOT EVENTS IN THE EVENTS LIST AS APPROPRIATE.
COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMS
1 AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NDNOD(190,40), ISE
2 D, MAMBAT, KOUNT, NADAR(40,19), RXATA(15), LOVER, ITEMS, PLIST(40,6), REAS
3 NT, CHANNEL(40,4,3,6), NASM, JAM(4), TMAX, NRTGT(90), MISLFT(90,2), NR, NS,
4 RT(50), IFLASK, IGAGE(190), ISAG(40), IFFAG, ISBG(40), IFBG, RELOAD(40,4),
5 MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, IGTAV(190), TCF(6), IHI
6 0), AMF, HISX(100), JACK(40,7), HISA(100)
  NASA = 0
  NSURF = 0
  NJ = IFIX(X(17)+AMF)
  IF (X(55).EQ.0.) GO TO 20
  CALL GETIMX (IET)
  TIM = IET*.000026
  WRITE (6,910) TIM GO TO 30
  IF (X(16).EQ.0.) GO TO 30
  IF (NASM.GT.0) GO TO 30
  TIME = TIME+2.
  CALL STOREV (TIME, I, IR)
  GO TO 740
C C C CHECK AIR TARGET OR SURFACE TARGET
30 ID = 2201+(IR-1)*6
  IF (X(ID+3).GT.50.) NASA=1
  NOTE = IFIX(X(ID)+AMF)
  NIP = (NOTE-1)*20
C C C GET RAIDER PARAMETERS
AREA = X(1816+NIP)
SIGMA = X(1815+NIP)
ALT = X(ID+3)
VEL = X(1814+NIP)
SALT = X(81)*SQRT(ALT)
IFLAG = 0
KFLAG = 0
DQ 730 I=1,NS
  IF (SHIP(I,6).GT.0.) GO TO 40
  NONG(IR, I) = 7
  GO TO 730
C C C CHECK SHIP FOR TYPE MISSILES

```

```

SUI 20
SUI 30
SUI 40
SUI 50
SUI 60
SUI 70
SUI 80
SUI 90
SUI 100
SUI 110
SUI 120
SUI 130
SUI 140
SUI 150
SUI 160
SUI 170
SUI 180
SUI 190
SUI 200
SUI 210
SUI 220
SUI 230
SUI 240
SUI 250
SUI 260
SUI 270
SUI 280
SUI 290
SUI 300
SUI 310
SUI 320
SUI 330
SUI 340
SUI 350
SUI 360
SUI 370
SUI 380
SUI 390
SUI 400
SUI 410
SUI 420
SUI 430
SUI 440
SUI 450
SUI 460
SUI 470
SUI 480
SUI 490

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```

IF (SRAG.LE.RGE) GO TO 140
RGE = SRAG
L2 = L
SAMVEL = X(ICS+1)
CCCONTINUE
140 C
150 C IF (TIME.EQ.0.) GO TO 160
CALL LOCIM (IR, TIME, 5, XCP, YCP)
RAID(IR, 14) = RAID(IR, 5)
RAID(IR, 15) = RAID(IR, 6)
C
C CHECK TO SEE IF TARGET WILL COME WITHIN MAX MISSILE RANGE
C
160 CALL TMDASM (IK, 0, L2, I, VEL, RGE, TIME, TD, XI, YI, RIP, TIML, IR)
IF (TD.LT.9120.) GO TO 170
NCNO(IR, I) = 9
GO TO 730
170 C IF (TD.LT.X(82)) GO TO 180
NCNO(IR, I) = 8
GO TO 730
180 C IF IR = TIML-RGE/SAMVEL
IF (TFIR.GT.TD) GO TO 190
NCNO(IR, I) = 8
GO TO 730
190 C KFLAG = 0
TAG = 0.1000.
IRGTI = 0.
RGE = 0.
JACK(I, I) = JACK(I, I)+1
JACK(I, 4) = JACK(I, 4)+1
NFOG = 0
MFOG = 0
JFOG = 0
CALL CPA (RAID(IR, 3), RAID(IR, 4), RAID(IR, 14), RAID(IR, 15), SHIP(I, 2),
SHIP(I, 3), XCP, YCP)
1-RCPS = (SHIP(I, 2)-XCP)**2+(SHIP(I, 3)-YCP)**2+(RAID(IR, 9)/6000.)**2
C CHECK SEARCH RADARS SEE IF ONE IS OPERABLE
C
DC 280 NSR=1,3
IF (NADAR(I, NSR).EQ.0) GO TO 280
KFLAG = 1
ID = IFIX(X(ISI+3+NSR)+AMF)
IA = IFIX(X(90I+(ID-I)*20)+AMF)
C BI-STATIC/MONO-STATIC FLAG
C

```

```

SUI 980
SUI 990
SUI 1000
SUI 1010
SUI 1020
SUI 1030
SUI 1040
SUI 1050
SUI 1060
SUI 1070
SUI 1080
SUI 1090
SUI 1100
SUI 1110
SUI 1120
SUI 1130
SUI 1140
SUI 1150
SUI 1160
SUI 1170
SUI 1180
SUI 1190
SUI 1200
SUI 1210
SUI 1220
SUI 1230
SUI 1240
SUI 1250
SUI 1260
SUI 1270
SUI 1280
SUI 1290
SUI 1300
SUI 1310
SUI 1320
SUI 1330
SUI 1340
SUI 1350
SUI 1360
SUI 1370
SUI 1380
SUI 1390
SUI 1400
SUI 1410
SUI 1420
SUI 1430
SUI 1440
SUI 1450

```


1460	SUI	1460
1470	SUI	1470
1480	SUI	1480
1490	SUI	1490
1500	SUI	1500
1510	SUI	1510
1520	SUI	1520
1530	SUI	1530
1540	SUI	1540
1550	SUI	1550
1560	SUI	1560
1570	SUI	1570
1580	SUI	1580
1590	SUI	1590
1600	SUI	1600
1610	SUI	1610
1620	SUI	1620
1630	SUI	1630
1640	SUI	1640
1650	SUI	1650
1660	SUI	1660
1670	SUI	1670
1680	SUI	1680
1690	SUI	1690
1700	SUI	1700
1710	SUI	1710
1720	SUI	1720
1730	SUI	1730
1740	SUI	1740
1750	SUI	1750
1760	SUI	1760
1770	SUI	1770
1780	SUI	1780
1790	SUI	1790
1800	SUI	1800
1810	SUI	1810
1820	SUI	1820
1830	SUI	1830
1840	SUI	1840
1850	SUI	1850
1860	SUI	1860
1870	SUI	1870
1880	SUI	1880
1890	SUI	1890
1900	SUI	1900
1910	SUI	1910
1920	SUI	1920
1930	SUI	1930

```

IF (IA.EQ.0) GO TO 790
MONOSTATIC DETECTION ALGORITHM
SRAG = X(902+(ID-1)*20)*AREA
RRH = X(81)*SQRT(X(ISI+6+NSR))
HRAG = X(RRH+SALT)
THR = X(905+(ID-1)*20)
RG = AMINI(SRAG,HRAG,THR)
IF (NJ.EQ.0) GO TO 200
IJ = IFIX(X(907+(ID-1)*20)+AMF)
CALL JAMM (RG,I,IR,IJ,ID,VEL,RRH,AREA,0,ICPA,RGI)
IF (ICPA.EQ.0) GO TO 280
RAGJ = RGI
GO TO 210
200 IF (RCPS.GE.RG*2) GO TO 280
RGI = RG
RAGJ = 999.0
IF (X(3).EQ.0.) GO TO 220
WRITE (6,930) I,IR,NSR
WRITE (6,940) SRAG,RAGJ,HRAG
CALL TMDASM (IR,0,NSR,I,VEL,RGI,TIME,TI,XI,YI,RIP,TIML,IR)
IF (TA.LI.TIML) TA = TIML
PUT IN DETECTION REACTION TIME
IF (X(10).EQ.0.) GO TO 250
IF (VEL.LI.1.0E-5) GO TO 240
RGE = ABS(RIP-DELR*VEL)
GO TO 260
240 DELR = X(87)
KEY = 260
250 KEY = IFIX(X(906+(ID-1)*20)+AMF)
CALL REACT (I,KEY,DELR)
260 TDET = TI+DELR
CHECK FOR MAXIMUM RANGE
IF (TRGE.LE.TDET) GO TO 270
RGE = RIP-DELR*VEL
TRGE = TDET
270 IF (NFOG.GT.0) GO TO 830
280 CONTINUE
IF KFLAG IS 0 NO SEARCH RADARS ARE UP GO CHECK
DIRECTORS FOR HORIZON SEARCH MODE

```


SUI 1940
 SUI 1950
 SUI 1960
 SUI 1970
 SUI 1980
 SUI 1990
 SUI 2000
 SUI 2010
 SUI 2020
 SUI 2030
 SUI 2040
 SUI 2050
 SUI 2060
 SUI 2070
 SUI 2080
 SUI 2090
 SUI 2100
 SUI 2110
 SUI 2120
 SUI 2130
 SUI 2140
 SUI 2150
 SUI 2160
 SUI 2170
 SUI 2180
 SUI 2190
 SUI 2200
 SUI 2210
 SUI 2220
 SUI 2230
 SUI 2240
 SUI 2250
 SUI 2260
 SUI 2270
 SUI 2280
 SUI 2290
 SUI 2300
 SUI 2310
 SUI 2320
 SUI 2330
 SUI 2340
 SUI 2350
 SUI 2360
 SUI 2370
 SUI 2380
 SUI 2390
 SUI 2400
 SUI 2410

```

290 IF (KFLAG.EQ.0) GO TO 610
    IF (TRGE.LI.TA) GO TO 290
    IF (MFOG.GT.0) GO TO 830
    NONG(IR,I) = 2
    GO TO 730
    RGFC = 0.
C
C   INCRIMENT THE ENGAGEMENTS POSSIBLE AND RAIDERS ENGAGABLE
C   COUNTERS, THEN CHECK TO SEE IF DETECTION OCCURED.. IF
C   IT DID, SET THE TARGET PROCESSING DELAYS.
    JACK(I,5) = JACK(I,5)+1
    STATS(I,1) = STATS(I,1)+RGFC
C
C   DETERMINATION OF FC RADAR ACQUISITION RANGE.
    DO 380 NB=1,4
    MTY = IFIX(X(ISI-1+NB)+AMF)
    IF (MTY.EQ.0) GO TO 390
    MTQ = NB+15
    IF (NADAR(I,MTQ).EQ.0) GO TO 380
C
C   DO 370 NF=1,3
    MTY = (MTY-1)*40
    NPQ = 3+(NB-1)*3+NF
    NAD = NADAR(I,NPQ)+1
    GO TO (370,300,340), NAD
    IAFC = IFIX(X(516+NF*2+MTZ*40)+AMF)
    SFCRH = X(902+(IA-1)*20)*AREA
    FFCRH = X(81)*SQRT(X(ISI+9+NB))
    HRCR = X(905+(IA-1)*20)
    THR = AMINI(SKFC,HRCR,THR)
    IF (NJ.EQ.0) GO TO 310
    IJ = IFIX(X(907+(IA-1)*20)+AMF)
    CALL JAMM (FRG,I,IR,IJ,IA,VEL,FCRH,AREA,0,JCPA,RGF)
    IF (JCPA.EQ.0) GO TO 370
    RFCJ = RGF
    GO TO 320
    IF (RCPS.GE. FRG**2) GO TO 370
    RGF = FRG
    RFCJ = 999
    IF (X(57).EQ.0) GO TO 330
    WRITE (6,950) I,IR,NB,NF,HRCR
    WRITE (6,940) SRFC,RFCJ,HRCR
    IF (RGFC.GE. RGF) GO TO 370
    RGF = RGF
  
```


SUI 2900
 SUI 2910
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 SUI 2990
 SUI 3000
 SUI 3010
 SUI 3020
 SUI 3030
 SUI 3040
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 SUI 3090
 SUI 3100
 SUI 3110
 SUI 3120
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 SUI 3180
 SUI 3190
 SUI 3200
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 SUI 3270
 SUI 3280
 SUI 3290
 SUI 3300
 SUI 3310
 SUI 3320
 SUI 3330
 SUI 3340
 SUI 3350
 SUI 3360
 SUI 3370

```

440 IF (ALT.GT.X(77)) GO TO 450
    SVEL = X(508+MTZ)
    GO TO 460
450 SVEL = X(502+MTZ)
460 TLS = TIML-RGFC/SVEL
    C
    C
    C
      COMPARE LAST TIME TO FIRE TO FINAL DETECT PLUS PROCESS TIME.
      IF (TSR.LT.TLS) GO TO 470
      IF (MFOG.GT.0) GO TO 830
      NNNO(IR,I) = 5
      GO TO 730
    C
    C
      GET LAUNCH TIME AND COMPARE WITH LAST TIME TO FIRE.
      KEY = IFIX(X(ISI+18)+AMF)
      CALL REACT(5,KEY,TFIRE)
      IF (TRGE.GT.TFR) GO TO 480
      TSHOOT = TFR+TFIRE
      GO TO 490
      TSHOOT = TSR+TFIRE
480 IF (X(3).EQ.0.) GO TO 500
490 WRITE(6,980) IR,I,TSHOOT,DELR,TWDS
      WRITE(6,990) TDES,TFIRE
500 IF (TSHOOT.LT.TLS) GO TO 510
      IF (MFOG.GT.0) GO TO 830
      NNNO(IR,I) = 5
      GO TO 730
510 IF (NASA.EQ.0) GO TO 560
    C
    C
    C
    C
    C
    C
      ENTER A SHOOT EVENT FOR EACH OPERATIONAL DIRECTOR LAUNCHER
      COMBINATION IN THIS BATTERY.
      IF THE MISSILE FLIES INDEPENDENTLY OF THE DIRECTOR THROUGHOUT
      ITS FLIGHT, ASSIGN THE NUMBER 7 TO THE CHANNEL SLOT.
      DO 540 MS=1,4
      MJL = 15+MS
      IF (NADAR(I,MJL).EQ.0) GO TO 540
      ID = IFIX(X(ISI+MS-1)+AMF)
      IF (X(536+(ID-1)*40).EQ.1.) GO TO 540
      MP = 3+(MS-1)*3
    C
      DO 530 MT=1,3
      MPI = MP+MT
      LARRY = NADAR(I,MPI)+1
      GO TO (530,520,550,530), LARRY
520 KS = I*1000+MS*100+MT*10+IR*100000
  
```



```

530 CALL STOREV (TSHOOT,3,KS)
531 CONTINUE
532
533
534 CONTINUE
535
536 GO TO 730
537 KS = I*1000+MS*100+MT*10+IR*100000+7
538 CALL STOREV (TSHOOT,3,KS)
539 GO TO 540
540
541 DO 590 MS=1,4
542 MJL = 15+MS
543 IF (NADAR(I,MJL).EQ.0) GO TO 590
544 ID = IFIX(X(ISI+MS-1)+AMF)
545 IF (X(536+(ID-1)*40).EQ.0.) GO TO 590
546 MP = 3+(MS-1)*3
547
548 DO 580 MT=1,3
549 MPI = MP+MT
550 LOIS = NADAR(I,MPI)+1
551 GO TO (580,570,600,580), LOIS
552 KS = I*1000+MS*100+MT*10+IR*100000
553 CALL STOREV (TSHOOT,3,KS)
554 CONTINUE
555
556 CONTINUE
557
558 GO TO 730
559 KS = I*1000+MS*100+MT*10+IR*100000+7
560 CALL STOREV (TSHOOT,3,KS)
561 GO TO 590
562
563
564 THE HORIZON SEARCH DETECTION ALGORITHM
565
566 RGFC = 0.
567
568 DC 660 NB=1,4
569 IFCR = IFIX(X(ISI-1+NB)+AMF)
570 IF (IFCR.EQ.0) GO TO 660
571 ICH = (NB-1)*3+3
572
573 DO 650 NF=1,3
574 NFG = ICH+NF
575 IF (NADAR(K,NFG).NE.3) GO TO 650
576 HT = X(ISI+10+NF)
577 HFCSR = X(81)*SQRT(HT)
578 HORZ = HFCSR+SALT
579 ICL = IFIX(X(516+(IFCR-1)*40+2*NF)+AMF)

```


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3990
4000
4010
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4070
4080
4090
4100
4110
4120
4130
4140
4150
4160
4170
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4240
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4270
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4290
4300
4310
4320
4330

```

RRFC = X(902+(ICL-1)*20)*AREA
THR = X(905+(ICL-1)*20)
HSFR = AMINI(RRFC,HORZ,THR)
IF (NJ.EQ.0) GO TO 620
IF = FIX(X(907+(ICL-1)*20)+AMF)
IF (JAM(IJ).EQ.0) GO TO 620
CALL JAMM(HSFR,I,IR,IJ,ICL,VEL,HFCRSR,AREA,0,LCPA,RGF)
IF (LCPA.EQ.0) GO TO 650
RFCJ = RGF
GO TO 630
620 IF (RCPS.GE.HSFR*2) GO TO 650
RFG = HSFR
RFGJ = 999
IF (X(57).EQ.0.) GO TO 640
630 WRITE(6,1000) I,IR
WRITE(6,940) RFG,RFCJ,HORZ
640 IF (RFG.LT.RGFC) GO TO 650
RFGC = RGF
IFC = NB
IFA = NF
650 CONTINUE
660 CONTINUE
C
C
C
C
    
```

THE HORIZON SEARCH DELAY TO FIRE REACTION TIMES ASSESSMENT

```

JACK(I,5) = JACK(I,5)+1
MTZ = IFIX(X(ISA-1)+IFC)+AMF)
NTZ = (MTZ-1)*40
KEY = IFIX(X(510Y+(IA-1)*20)+AMF)
CALL REACT(6,KEY,TAC)
KEY = IFIX(X(510Y+18)+AMF)
CALL REACT(5,KEY,TFIRE)
KEY = IFIX(X(510Y+19)+AMF)
CALL REACT(7,KEY,THSCAN)
CALL TMDASM(IR,0,IFC,I,VEL,RGFC,TIME,TD,XI,YI,RIP,IR)
TSHOOT = TD+TAC+AMAXI(1,1)+RIP
IF (TSHOOT.GT.X(82)) GO TO 670
STATS(I,1) = STATS(I,1)+RIP
IF (NASA.EQ.0) GO TO 680
IF (ALT.GT.X(77)) GO TO 680
SVEL = X(508+MTZ)
GO TO 690
670 NONO(IR,1) = 4
GO TO 730
680 SVEL = X(502+MTZ)
690 TLS = TML-RGFC/SVEL
IF (TSHOOT.LE.TLS) GO TO 700
    
```



```

4340 SUI
4350 SUI
4360 SUI
4370 SUI
4380 SUI
4390 SUI
4400 SUI
4410 SUI
4420 SUI
4430 SUI
4440 SUI
4450 SUI
4460 SUI
4470 SUI
4480 SUI
4490 SUI
4500 SUI
4510 SUI
4520 SUI
4530 SUI
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4550 SUI
4560 SUI
4570 SUI
4580 SUI
4590 SUI
4600 SUI
4610 SUI
4620 SUI
4630 SUI
4640 SUI
4650 SUI
4660 SUI
4670 SUI
4680 SUI
4690 SUI
4700 SUI
4710 SUI
4720 SUI
4730 SUI
4740 SUI
4750 SUI
4760 SUI
4770 SUI
4780 SUI
4790 SUI
4800 SUI
4810 SUI

NCNO(IR,I) = 5
GO TO 730
IF (NASA.EQ.0) GO TO 760
C
700 DC 720 MS=1,4
IPQ = 15+MS
IF (NADAR(I,IPQ).EQ.0) GO TO 720
ID = IFIX(X(ISI-1+MS)+AMF)
IF (X(536+(ID-1)*40).EQ.1.) GO TO 720
MP = 3+(MS-1)*3
C
710 DO 710 MT=1,3
MPI = MP+MT
IF (NADAR(I,MPI).NE.3) GO TO 710
KS = I*1000+MS*100+MT*10+IR*100000
CALL STOREV (TSHOOT,3,KS)
CONTINUE
C
720 CONTINUE
C
730 CONTINUE
C
740 IF (X(55).EQ.0.) GO TO 750
CALL GETIMX (IET)
TIM = IET*.000026
WRITE (6,1010) TIM
750 RETURN
C
C ONE OF THE SURFACE TO SURFACE SHOOT ENTRIES.
C
760 DO 780 MS=1,4
IPQ = 15+MS
IF (NADAR(I,IPQ).EQ.0) GO TO 780
ID = IFIX(X(ISI-1+MS)+AMF)
IF (X(536+(ID-1)*40).EQ.0.) GO TO 730
MP = 3+(MS-1)*3
C
770 DO 770 MT=1,3
MPI = MP+MT
IF (NADAR(I,MPI).NE.3) GO TO 770
KS = I*1000+MS*100+MT*10+IR*100000
CALL STOREV (TSHOOT,3,KS)
CONTINUE
C
780 CONTINUE
C
C GO TO 730
C

```



```

C      C
C      THE BI-STATIC DETECTION ALGORITHM
790  CALL BIDET (I,NSR,ALT,IR,VEL,SIGMA,ND,II,TIML,RGI,TD2,TIML2,R2,0)
      IF (TI.LT.TIME) TI = TIME
      IF (ND.EQ.0) GO TO 800
      IF (X(3).EQ.1.) WRITE (6,1020) IR,I,II,TIML
      IF (X(3).EQ.1.) GO TO 800
      IF (X(3).EQ.1.) WRITE (6,1030) TD2,TIML2
800  ND = ND+1
      GO TO (820,230,870), ND
810  NUNO(IR,I) = 4
      GO TO 730
820  TIML = 9120.
      RGI = 0.
      GO TO 230
830  RGE = 0.
      IRGE = 1000.
      TA = 0.
      GO TO (840,850,860), MFOG
840  TITL = TTA
      TIML = TIMLA
      RGI = RGIA
      MFOG = MFOG-1
      JFOG = 1
      NFOG = 0
      GO TO 230
850  TITL = TTB
      TIML = TIMLB
      RGI = RGI B
      MFOG = MFOG-1
      GO TO 230
860  TITI = TTC
      TIML = TIMLC
      MFOG = MFOG-1
      GO TO 230
870  MFOG = MFOG+1
      GO TO (880,890,900), MFOG
880  TITA = TD2
      TIMLA = R2
      RGTB = TD2
      TIMLB = 1
      NFOG = 1
      RGI B = R2
      GO TO 230
4820 SUI
4830 SUI
4840 SUI
4850 SUI
4860 SUI
4870 SUI
4880 SUI
4890 SUI
4900 SUI
4910 SUI
4920 SUI
4930 SUI
4940 SUI
4950 SUI
4960 SUI
4970 SUI
4980 SUI
4990 SUI
5000 SUI
5010 SUI
5020 SUI
5030 SUI
5040 SUI
5050 SUI
5060 SUI
5070 SUI
5080 SUI
5090 SUI
5100 SUI
5110 SUI
5120 SUI
5130 SUI
5140 SUI
5150 SUI
5160 SUI
5170 SUI
5180 SUI
5190 SUI
5200 SUI
5210 SUI
5220 SUI
5230 SUI
5240 SUI
5250 SUI
5260 SUI
5270 SUI
5280 SUI

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```

900 TTC = TD2
    TIMLC = TIML2
    RGIC = R2
    GO TO 230

C
910 FORMAT ('0',SUBEL IN AT',F15.8)
920 FORMAT ('0',SUBEL RAIDER',I3,' SURFACE OR SUBMARINE UNIT, SHIP',I3,
1 HAS NO SSM')
930 FORMAT ('0',DETECTION RANGES OF SHIP',I3,' ON RAIDER',I3,' WITH
1 RADAR',I2)
940 FORMAT ('',F9.4/(' JAMMING ENVIRONMENT.
1',F9.4/(' RADAR HORIZON... ',F9.4/('
950 FORMAT ('',F9.4/(' ACQUISITION RANGES FOR SHIP',I3,
1 STEM',I2,' FC RADAR TYPE',I3,' ON RAIDER',I3,' WITH SY
960 FORMAT ('',F9.4/(' INITIAL DETECTION OF RAIDER',I3,' BY SHIP',I3/(' SEARCH
1 H RADAR',F9.4/(' FC LOCK ON',F9.4/('
970 FORMAT ('',F9.4/(' SECOND DETECTION (BI-STATIC) ON RAIDER',I3,' BY SHIP',I3,
13/(' SEARCH RADAR DETECTION TIME',F9.4,' LAST TIME TO SHOOT',
2F9.4))
980 FORMAT ('',F9.4/(' RAIDER',I3,' FIRING SHIP',I3,' TSHOOT WAS',F9.4/(' DET
1 ECTION DELAY WAS',F9.4/(' WDE TRACK DELAY WAS',F9.4))
990 FORMAT ('',F9.4/(' DESIGNATION DELAY WAS',F9.4/(' FIRING DELAY WAS',F9.
14))
1000 FORMAT ('',F9.4/(' HORIZON SEARCH DETECTION FOR SHIP',I3,' VS. RAIDER',I3,
1)
1010 FORMAT ('',F9.4/(' SUBEL OUT AT',F15.8)
1020 FORMAT ('0',FIRST BI-STAT DET ON RAIDER',I3,' BY SHIP',I3,' WAS
1 AT',F9.4,' DET LOST AT',F9.4)
1030 FORMAT ('',F9.4/(' SECOND DET AT',F9.4,' LOST DET AT',F9.4)
    END

```

```

SUBROUTINE SUBE2 (TIME,IR)
C
C THIS SUBROUTINE COMPUTES THE LAUNCH TIME FOR ALL RED
C ASM/SSM AND DETERMINES THE POSSIBLE SAM LAUNCH TIMES FOR
C BLUE MISSILE LAUNCHERS
C
COMMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SMSU2
1AT(300,10),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NONO(190,40),ISEESU2
20,MAMBAT,KOUNT,NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASU2
3N,CHANBEL(40,3,6),NASM,JAM(4),MAX,NRTGT(90,2),NR,NNS,QSU2
4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG,RELCAD(40,4),SU2
5MARY(100),CHECK,IFIRST,NPGS,KMART(4),IFBG,RELCAD(40,4),SU2
60),AMF,HISX(100),JACK(40,7),HISA(100)
DIMENSION ITARG(40,2)
    KING = 0
    NJ = IFIX(X(17))+AMF)

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11500
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11580
11600

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SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2
SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2 SU2

GO TO 120
RT = PLIST(NT, IPQ) - PLIST((NT-1), IPQ)
IF (RT.LT.0.0005) GO TO 140
IF (SHIP(NT,6).GT.0.) GO TO 130
IF (X(5).EQ.1.) GO TO 130
MARIE = IFIX(SHIP(NT,4)+AMF)
IF (IHIT(NT).GE.MARIE) GO TO 140
CALL RCHECK(NT,IR,KQED)
IF (KQEQ.EQ.1) GO TO 140
IDP = IDP+1
ITARG(IDP,1) = FLOAT(NT)
ITARG(IDP,2) = PLIST(NT,IPQ)
CONTINUE
C
150 IF (IDP.EQ.0) GO TO 180
CALL RANDOM(ISEED,Z,1)
X(13) = X(13)+1.
C
DO 160 NT=1, IDP
IF (Z.LE.ITARG(NT,2)) GO TO 170
CONTINUE
C
NT = IDP
IOU = IFIX(ITARG(IDP,1)+AMF)
GO TO 190
IOU = IFIX(ITARG(NT,1)+AMF)
GO TO 190
CALL STOREV((TM+3.),2,IR)
IF (NASM.EQ.0) IFLASK=0
GO TO 910
C
CHECK TO SEE IF THE TARGET CHOSEN IS A DESIGNATED
NON-RADIATING PICKET
C
190 ISI = IFIX(SHIP(IOU,5)+AMF)
I2 = IFIX(X(ISI+30)+AMF)
IF (I2.EQ.0) GO TO 250
C
IF SO DETERMINE IF IT CAN BE TARGETED. IF IT CAN, TARGET
PROCEED, OTHERWISE ELIMINATE IT FROM THE TEMPORARY TARGET
LIST AND TRY AGAIN.
C
CALL RANDOM(ISEED,Z,1)
X(13) = X(13)+1.
IF (RAID(IR,9).GT.X(20)) GO TO 200
IF (Z.LE.X(22)) GO TO 240
GO TO 210
C
200 IF (Z.LE.X(21)) GO TO 240

```



```

C      FLAG FOR TWO MISSILE SALVOS FOR SSN
C      GO TO 870
C      XS = SHIP( IOU, 2)
C      ASMT(NASM, 1) = 1.
C
C      DETERMINE THE ASM/SSM FLIGHT TIME AND DETERMINE THE
C      IMPACT TIME.
C      RAID(IR, 14) = XS
C      YS = SHIP( IOU, 3)
C      RAID(IR, 15) = YS
C      XRR = RAID(IR, 3)
C      YRR = RAID(IR, 4)
C      DELTAX = ABS(XS - XRR)
C      IF (DELTAX.LT.00005) DELTAX=.00005
C      DELTAY = ABS(YS - YRR)
C      IF (DELTAY.LT.00005) DELTAY=.00005
C      DIST = Sqrt(DELTAX**2+DELTAY**2+(ALT/6000.)**2)
C      ASMT(NASM, 2) = TM+DIST/SPD
C
C      STORE AN ASM IMPACT EVENT
C
C      NU = M*100+IOU
C      CALL STOREV (ASMT(NASM, 2), 4, NU)
C      ALTN2 = (ALT/6000.)**2
C
C      ASM/SSM DETECTION AND FIRING ALGORITHM
C
C      DO 860 K=1, NS
C      NM = IFIX(SHIP(K, 6)+AMF)
C      IF (NM.GT.0) GO TO 290
C      NNO(M, K) = 7
C      GO TO 860
C      ISI = IFIX(SHIP(K, 5)+AMF)
C      RGE = 0.
C
C      GET MAX MISSILE RANGE FOR SAM SHIP
C
C      DO 340 LO=1, 4
C      MP = 3+(LO-1)*3
C
C      DO 300 LI=1, 3
C      MPI = MP+LI
C      IF (NADAR(K, MPI).GT.0) GO TO 310
C      CONTINUE
C      GO TO 340

```


SU2 2570
 SU2 2580
 SU2 2590
 SU2 2600
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 SU2 2620
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 SU2 2680
 SU2 2690
 SU2 2700
 SU2 2710
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 SU2 2930
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 SU2 2950
 SU2 2960
 SU2 2970
 SU2 2980
 SU2 2990
 SU2 3000
 SU2 3010
 SU2 3020
 SU2 3030
 SU2 3040

```

310 IF (NADAR(K,(15+LO)),EQ,0) GO TO 340
    IC = IFIX(X(15+LO-1)+AMF)
    IF (ALT.GT.X(77)) GO TO 320
    ICS = 508+(IC-1)*40
    GO TO 330
320 ICS = 501+(IC-1)*40
    SRGE = X(ICS)
    SVEL = X(ICS+1)
    IF (SRGE.LE.RGE) GO TO 340
    RGE = SRGE
    L2 = LU
    SAMVEL = SVEL
    CONTINUE
340
C
C
C
    WILL THE ASM/SSM COME WITHIN THE BLUE MISSILE ENVELOPE?
    CALL TMDASM (IR,IOU,L2,K,SPD,RGE,TM,TD,XI,YI,RIP,TIML,NASM)
    IF (TD.GE.9120.) GO TO 350
    IF (TD.LT.X(82)) GO TO 360
    NONO(M,K) = 8
    GO TO 360
350 NONO(M,K) = 9
    GO TO 860
360 IF (TD.LT.ASMT(NASM,2)) GO TO 370
    NONO(M,K) = 6
    GO TO 860
370 TFIR = TIML-RGE/SAMVEL
C
C
C
    IS TIME TO FIRE AFTER TIME OF MISSILE EXITING ENVELOPE?
    IF (TFIR.GT.TD) GO TO 380
    NONO(M,K) = 8
    GO TO 860
380 KFLAG = 0
    TA = 0.1000.
    TRGE = 0.
    JACK(K,1) = JACK(K,1)+1
    JACK(K,6) = JACK(K,6)+1
    NFOG = 0
    JFOG = 0
C
C
C
    DETERMINE CPA OF ASM TO RADAR UNIT
    CALL CPA (XU,Y,XS,YS,SHIP(K,2),SHIP(K,3),XCPA,YCPA)
    RCPS = (SHIP(K,2)-XCPA)**2+(SHIP(K,3)-YCPA)**2+ALTN2
C
  
```



```

3050 DO 460 NSR=1,3
3060 IF (NADAR(K,NSR).EQ.0) GO TO 460
3070 KFLAG = 1
3080 ID = IFIX(X(ISI+3+NSR)+AMF)
3090 IDI = (ID-1)*20
3100 IA = IFIX(X(901+IDI)+AMF)
3110
3120 BI-STATIC RADAR DETECTION MODE SWITCH
3130
3140 IF (IA.EQ.0) GO TO 930
3150
3160 MONOSTATIC SEARCH RADAR DETECTION RANGE ALGORITHM
3170
3180 SRAG = X(902+IDI)*AREA
3190 RRRH = X(81)*SQRT(X(ISI+6+NSR))
3200 HRAG = RRRH+SALT
3210 THR = X(905+IDI)
3220 TRG = AMINI(SRAG,HRAG,THR)
3230 IF (NJ.EQ.0) GO TO 390
3240 IJI = IFIX(X(907+IDI)+AMF)
3250 IF (JAM(IJI).EQ.0) GO TO 390
3260 CALL JAMM (RG,K,IR,IJI,ID,SPD,RRH,AREA,1,ICPA,RGI)
3270 IF (ICPA.EQ.0) GO TO 460
3280 IRAGJ = RGI
3290 GO TO 400
3300 RGS = RG*#2
3310 IF (RCPS.GE.RGS) GO TO 460
3320 RGI = RG
3330 RAGJ = 999.
3340 IF (X(3).EQ.0.) GO TO 410
3350 WRITE (6,1110) K,M,NSR
3360 CALL TMDASM (IR,IOU,NSR,K,SPD,RGI,TM,TI,XI,YI,RIP,TIML,NASM)
3370 IF (TA.LT.TIML) TA = TIML
3380 IF (X(10).EQ.0.) GO TO 430
3390 DELR = (RIP*X(10))/SPD
3400 GO TO 440
3410 GET DETECTION DELAYS, CHECK TIMES, GET PROBABILITY OF DE-
3420 TECTION AND DETERMINE IF DETECTION OCCURRED.
3430
3440 KEY = IFIX(X(906+IDI)+AMF)
3450 CALL REACT (I,KEY,DELR)
3460 TDET = TI+DELR
3470 IF (TRGE.LE.TDET) GO TO 450
3480 TRGE = ABS(RIP-DELR*SPD)
3490 TRGE = TDET
3500 IF (NFOG.GT.0) GO TO 960
3510 CCNTINUE
3520

```


3530 SU2
 3540 SU2
 3550 SU2
 3560 SU2
 3570 SU2
 3580 SU2
 3590 SU2
 3600 SU2
 3610 SU2
 3620 SU2
 3630 SU2
 3640 SU2
 3650 SU2
 3660 SU2
 3670 SU2
 3680 SU2
 3690 SU2
 3700 SU2
 3710 SU2
 3720 SU2
 3730 SU2
 3740 SU2
 3750 SU2
 3760 SU2
 3770 SU2
 3780 SU2
 3790 SU2
 3800 SU2
 3810 SU2
 3820 SU2
 3830 SU2
 3840 SU2
 3850 SU2
 3860 SU2
 3870 SU2
 3880 SU2
 3890 SU2
 3900 SU2
 3910 SU2
 3920 SU2
 3930 SU2
 3940 SU2
 3950 SU2
 3960 SU2
 3970 SU2
 3980 SU2
 3990 SU2
 4000 SU2

GO TO HORIZON SEARCH DETECTION MODE

IF (KFLAG.EQ.0) GO TO 740

WILL ASM/SSM ENTER SEARCH RADAR RANGE?

IF (TRGE.LT.TA) GO TO 470

IF (MFOG.GT.0) GO TO 960

NOND(M,K) = 2

IF (X(3).EQ.1.) WRITE (6,1210) TA

GO TO 860

RGFC = 0.

JACK(K,7) = JACK(K,7)+1

STATS(K,2) = STATS(K,2)+RGE

FIRE CONTROL ACQUISITION PHASE

DO 560 NB=1,4

MTY = IFIX(X(ISI+NB-1)+AMF)

IF (MTY.EQ.0) GO TO 570

IF (X(536+(MTY-1)*40).EQ.1.) GO TO 560

MTQ = NB+15

IF (NADAR(K,MTQ).EQ.0) GO TO 560

DO 550 NF=1,3

NPQ = 3+(NB-1)*3+NF

NAD = NADAR(K,NPQ)+1

GO TO (550,480,520), NAD

IAI = IFIX(X(516+NF*2+(MTY-1)*40)+AMF)

IAI = (IAI-1)*20

SRFC = X(902+IAI)*AREA

THR = X(905+IAI)

RRH = X(81)*SQRT(X(ISI+9+NB))

HRAG = X(RRH+SALT

RG = AMIN(SRFC,HRAG,THR)

IF (NJ.EQ.0) GO TO 490

IJI = IFIX(X(907+IAI)+AMF)

IF (JAM(IJI).EQ.0) GO TO 490

CALL JAMM(RG,K,IR,IJI,IA,SPD,RRH,AREA,1,ICPA,RGF)

IF (ICPA.EQ.0) GO TO 550

RGFCJ = RGI

GO TO 500

RGS = RG*#2

IF (RCPS.GE.RGS) GO TO 550

RGE = RG

RFCJ = 999.

IF (X(3).EQ.0.) GO TO 510

SU2 4010
 SU2 4020
 SU2 4030
 SU2 4040
 SU2 4050
 SU2 4060
 SU2 4070
 SU2 4080
 SU2 4090
 SU2 4100
 SU2 4110
 SU2 4120
 SU2 4130
 SU2 4140
 SU2 4150
 SU2 4160
 SU2 4170
 SU2 4180
 SU2 4190
 SU2 4200
 SU2 4210
 SU2 4220
 SU2 4230
 SU2 4240
 SU2 4250
 SU2 4260
 SU2 4270
 SU2 4280
 SU2 4290
 SU2 4300
 SU2 4310
 SU2 4320
 SU2 4330
 SU2 4340
 SU2 4350
 SU2 4360
 SU2 4370
 SU2 4380
 SU2 4390
 SU2 4400
 SU2 4410
 SU2 4420
 SU2 4430
 SU2 4440
 SU2 4450
 SU2 4460
 SU2 4470
 SU2 4480

```

510 WRITE (6,1130) K,M,NB,NF
    WRITE (6,1120) SRFC,RFCJ,HRAG
    IF (RGFC.GE.RGF) GO TO 550
    RGFC = RGF
    IFC = NB
    IFA = NF
    GO TO 550
520 MTZ = (MTY-1)*40
    IFM (ALT.GT.X(77)) GO TO 530
    RGM = X(508+MTZ)
    SVEL = X(509+MTZ)
    GO TO 540
530 RGM = X(501+MTZ)
    SVEL = X(502+MTZ)
540 RGF = RGM*(1+SPD/SVEL)
    IF (RGFC.GE.RGF) GO TO 560
    IFC = NB
    RGFC = RGF
    IFA = 0
    GO TO 560
550 CONTINUE
560 CONTINUE
570 CALL TMDASM (IR,IOU,IFC,K,SPD,RGFC,IM,TFR,XI,YI,RIP,TIMF,NASM)
    IF (X(3).EQ.0.) GO TO 590
    IF (JFOG.EQ.1) GO TO 580
    WRITE (6,1140) TRGE,TFR
    GO TO 590
580 WRITE (6,1150) TRGE,TFR
590 PROB = X(151+15)
    CALL RANDOM (ISEED,Z,1)
    X(13) = X(13)+1
    IF (PROB.GT.Z) GO TO 600
    NCON(M,K) =
    GO TO 860
    DESIGNATION, EVALUATION, AND ACQUISITION DELAYS.
600 IF (TA.LT.TFR) GO TO 940
    KEY = IFIX(X(151+16))+AMF)
    CALL REACT (2,KEY,TWDS)
    KEY = IFIX(X(151+17))+AMF)
    CALL REACT (3,KEY,TDES)
    MTZ = IFIX(X(151+18))+AMF)
    IF (IFA.EQ.0) GO TO 610
    IA = IFIX(X(1516+IFA*2+MTZ))+AMF)

```


SUZ 4490
 SUZ 4510
 SUZ 4520
 SUZ 4530
 SUZ 4540
 SUZ 4560
 SUZ 4570
 SUZ 4580
 SUZ 4590
 SUZ 4600
 SUZ 4610
 SUZ 4620
 SUZ 4630
 SUZ 4640
 SUZ 4650
 SUZ 4660
 SUZ 4670
 SUZ 4680
 SUZ 4690
 SUZ 4700
 SUZ 4710
 SUZ 4720
 SUZ 4730
 SUZ 4740
 SUZ 4750
 SUZ 4760
 SUZ 4770
 SUZ 4780
 SUZ 4790
 SUZ 4800
 SUZ 4810
 SUZ 4820
 SUZ 4830
 SUZ 4840
 SUZ 4850
 SUZ 4860
 SUZ 4870
 SUZ 4880
 SUZ 4890
 SUZ 4900
 SUZ 4910
 SUZ 4920
 SUZ 4930
 SUZ 4940
 SUZ 4950
 SUZ 4960

```

KEY = IFIX(X(906+(IA-1)*20)+AMF)
CALL REACT(4,KEY,TAC)
TSR = TRGE+TWDS+TDES+TAC
GO TO 620
610  TSR = TRGE+TWDS+TDES
620  IF (ALT.GT.X(77)) GO TO 630
    SVEL = X(509+MTZ)
GO TO 640
630  SVEL = X(502+MTZ)
640  TLS = TIMF-RGFC/SVEL
    IF (TSR.LT.TLS) GO TO 650
    IF (MFOG.GT.0) GO TO 960
NONC(M,K) = 5
GO TO 860
  
```

C
 C
 FIRE EVENT STORAGE FOR A REGULAR SHOT

```

650  KEY = IFIX(X(ISI+18)+AMF)
CALL REACT(5,KEY,TFIRE)
IF (TRGE.GT.TFR) GO TO 660
TSHOOT = TFR+TFIRE
GO TO 670
660  TSHOOT = TSR+TFIRE
670  IF (X(57).EQ.0.) GO TO 680
    WRITE(6,1230) TSHOOT,DELR,TWDS
680  IF (TSHOOT.LT.TLS) GO TO 690
    IF (MFOG.GT.0) GO TO 960
NONC(M,K) = 5
GO TO 860
  
```

C
 C
 DO 720 MS=1,4
 MJL = 15+MS
 IF (NADAR(K,MJL).EQ.0) GO TO 720
 ID = IFIX(X(ISI+MS-1)+AMF)
 IF (X(536+(ID-1)*40).EQ.1.) GO TO 720
 MP = 3+(MS-1)*3

C
 DO 710 MT=1,3
 MPI = MP+MT
 LARRY = NADAR(K,MPI)+1
 GO TO (710,700,730,710), LARRY
 K53 = M*10000+K*1000+MS*100+MT*10
 CALL STOREV (TSHOOT,3,K53)

C
 C
 700 CONTINUE
 710 CONTINUE
 720 CONTINUE
 C


```

C      GO TO 860
C      FIRE EVENT STORAGE FOR A NON DEDICATED SHOT
C
C      730  KS3 = M*100000+K*1000+MS*100+MT*10+7
C          CALL STOREV (TSHOOT,3,KS3)
C          GO TO 720
C      740  RGFC = 0.
C
C          HORIZON SEARCH DETECTION ALGORITHM
C
C          DO 790 NB=1,4
C          IF (X(ISI+NB-1).EQ.0.) GO TO 790
C          ICH = (NB-1)*3+3
C
C          DO 780 NF=1,3
C          NFG = ICH+NF
C          IF (NADAR(K,NFG).NE.3) GO TO 780
C          IFCR = IFIX(X(ISI+NB-1)+AMF)
C          IICL = IFIX(X(516+(IFCR-1)*40+2*NF)+AMF)
C          IICI = (ICL-1)*20
C          RRFC = X(902+ICI)*AREA
C          THR = X(905+ICI)
C          RRRH = X(ISI+10+NF)
C          HORZ = X(81)*SQRT(HT)
C          HGRZ = AMIN1(RRFC,HORZ,THR)
C          IF (NJ.EQ.0) GO TO 750
C          IF (IJ1.EQ.0) GO TO 750
C          CALL JAMM (RG,K,IR,IJI,ICL,SPD,RRH,AREA,1,ICPA,RGF)
C          IFCJ = ICPA.EQ.0) GO TO 780
C          GO TO 760
C      750  RGS = RG*#2
C          IF (RCPS.GE.RGS) GO TO 780
C          RFCJ = RG
C          RFCJ = 999.EQ.0.) GO TO 770
C          IF (X(57).EQ.0.) GO TO 770
C          WRITE (6,1160) K,M
C      770  WRITE (6,1120) RRFC,RFCJ,HORZ
C          WRF (RGF,LE,RGFC) GO TO 780
C          IF (RGF.LE.RGFC) GO TO 780
C          RGF = RGF
C          RGC = NB
C          IFCJ = NB
C          CONTINUE
C      780
C

```



```

790 CONTINUE
C      MTZ = IFIX(X(ISI-1+IFC)+AMF)
      MTZ = (MTZ-1)*40
      IA = IFIX(X(516+IFA*2+MTZ)+AMF)
C
C      HORIZON SEARCH DECISION AND FIRE DELAYS
      KEY = IFIX(X(908+(IA-1)*20)+AMF)
      CALL REACT(6,KEY,TAC)
      KEY = IFIX(X(ISI+18)+AMF)
      CALL REACT(5,KEY,TFIRE)
      KEY = IFIX(X(ISI+19)+AMF)
      CALL REACT(7,KEY,THSCAN)
      CALL TMDASM(IR,IOU,IFC,K,SPD,RGFC,TM,TIFA,XI,YI,RIP,TIML,NASM)
      TSHOOT = TIFA+TAC+AMAX1(TFIRE,THSCAN)
      IF (TSHOOT.GT.X(82)) GO TO 800
      IF (TSHOOT.GT.X(82)) GO TO 800
      JACK(K,2) = STAK(K,2)+RIP
      IF (ALT.GT.X(77)) GO TO 810
      SVEL = X(508+MTZ)
      GO TO 820
      800 NDNQ(M,K) = 4
      GO TO 860
      810 SVEL = X(502+MTZ)
      820 TLS = TIML-RGFC/SVEL
      IF (TSHOOT.LE.TLS) GO TO 830
      NDNQ(M,K) = 5
      GO TO 860
C
C      HORIZON SEARCH FIRE
      830 DU 850 MS=1,4
      IPQ = 15+MS
      IF (NADAR(K,IPQ).EQ.0) GO TO 850
      ID = IFIX(X(ISI+MS-1)+AMF)
      IF (X(536+(ID-1)*40).EQ.1.) GO TO 850
      MP = 3+(MS-1)*3
C
      DO 840 MT=1,3
      MPI = MP+MT
      IF (NADAR(K,MPI).NE.3) GO TO 840
      KS3 = M*10000+K*1000+MS*100+MT*10
      CALL STOKEV(TSHOOT,3,KS3)
      CCNTINUE
      840 CONTINUE
C
      850 CONTINUE
C

```



```

C      860 CONTINUE
      IF (IFLAG.EQ.1) GO TO 1060
      IF (KING.EQ.1) IFLAG=1
      CONTINUE
C
C      870
      CHECK TO SEE IF THE RAIDER HAS ANOTHER TYPE OF MISSILE
      IF (NTOI.EQ.0) GO TO 900
      IF (NEXT.EQ.1) GO TO 880
      IF (RAID(IR,16).GT.TM) GO TO 890
      NMIS = MISLFT(IR,2)
      NOW = 2
      KATHY = 1
      GO TO 60
      880 IF (RAID(IR,16).GT.TM) GO TO 890
      NMIS = MISLFT(IR,1)
      NOW = 1
      KATHY = 1
      GO TO 60
      890 IF (RAID(IR,16).GT.X(82)) GO TO 900
      IF THE RAIDER IS OUTSIDE THE LAUNCH RANGE FOR THE TYPE
      TWO MISSILES, STORE A MISSILE (ASM/SSM) LAUNCH EVENT
      CALL STOREV (RAID(IR,16),2,IR)
      IF FLAG SET PRINT THE NONO TABLE
      900 IF (X(58).EQ.0.) GO TO 910
      WRITE (6,1190)
      NMIS = 90+NASM
      WRITE (6,1200) (MFOG,(NONO(MFOG,NFOG),NFOG=1,40),MFOG=1,NR)
      910 IF (X(55).EQ.0.) GO TO 920
      CALL GETIMX (IET)
      T = 000026*IET
      WRITE (6,1170) T
      RETURN
      THE EI-STATIC DETECTION ALGORITHM
C
C      930 CALL BIDET (K,NSR,ALT,IR,SPD,SIGMA,ND,PI,TIML,RGI,TD2,TIML2,R2,1)
      GO TO (950,420,1000), ND
      940 NONO(M,K) = 4
      GO TO 860
      950 TI = 9120.
      TIML = 0.

```



```

980 990 1000 1010 1020 1030 1040
TA = 0 (970,980,990), MFOG
GO TO TTA
T I IML = R G I A
M F O G = M F O G - 1
J F O G = 1
N F O G = 0
GO TO 420
T I IML = R G I B
M F O G = M F O G - 1
GO TO 420
T I I = T T C
R G I = R G I C
T I M L C = M F O G - 1
GO TO 420
M F O G = M F O G + 1
GO TO (1010,1020,1030), MFOG
T I A = T D 2
T I M L A = T I M L 2
R G I A = R 2
GO TO 420
T I M L B = T I M L 2
N F O G = 1
R G I B = R 2
GO TO 420
T T C = T D 2
T I M L C = R 2
GO TO 420
R G I C = R 2
GO TO 420
I F (I F L A S K . E Q . 1) I F L A S K = 0
M I S L F T ( I R , 1 ) + M I S L F T ( I R , 2 )
N F L A G = 1
J D = I F ( X ( 2 2 0 1 + ( I R - 1 ) * 6 ) + A M F )
K I N G = I F ( X ( 1 8 0 8 + ( I D - 1 ) * 2 0 ) + A M F )
I F ( K I N G . E Q . 1) I F L A G = 1
C A L L R A N D O M ( I S E E D , Z , 1 )
X ( 1 3 ) = X ( 1 3 ) + 1
X ( 8 6 )
GO TO 40

```



```

COMMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SMSUB
IAT(300,10),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NONO(190,40),ISESUS
2D,MAMBAT,KOUNT,NADAR(40,19),RXATA(5),LDVER,ITEMS,PLIST(40,6),REAS,QSUS
3N,CHANELL(40,4,3,6),NASM,JAM(4),IMAX,NRTGI(90),MISLFT(90,2),NR,NS,8
4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELGAD(40,4),SUS
5MARY(100),CHECK,IFIRST,NPGS,KMART(+),NSAM,TGTAV(190),IHIT(4SUS
60),AMF,HISX(100),JACK(40,7),HISA(100)SUS
C
MFOG = 0
NCL = 0
REASON = 0
IF (X(55).EQ.0.) GO TO 20
CALL GETIMX (K)
TIM = K#0.000026
WRITE (6,610) TIM
C
          DETERMINE THE TARGET NUMBER, FIRING SHIP,BATTERY,DIRECTOR,
          AND CHANNEL NUMBER FOR THE PROPOSED MISSILE FIRING.
20  IU = IU+2
    M = IU*1.0D-5
    KP = M*10000
    ID = IU-KP
    K = ID*1.0D-3
    KP = K*1000
    JP = ID-KP
    NMS = JP*0.0100
    ID = JM*100
    ID = JP-KP
    NNB = ID*0.10
    KP = NB*10
    NNC = ID-KP
    NNC = NC-2
    IU = IU-2
          IF THE FIRING SHIP HAS BEEN SUNK,EXIT
CC
CC
IF (SHIP(K,6).NE.0.) GO TO 30
REASON = 1.
GO TO 560
C
          IF THE FIRING SHIP IS OUT OF MISSILES, EXIT
CC
CC
30  IF (IBAT(K,NMS).NE.0) GO TO 40
    REASON = 4.
    GO TO 560
C
          IF THE TARGET HAS ALREADY BEEN SUNK OR SHOT DOWN, EXIT
CC
CC

```



```

C      IF THE RAIDER WAS AN AIRCRAFT CARRYING ASMS AND ALL ITS
C      ASMS HAVE BEEN LAUNCHED, AND THE FLAG IS SET, EXIT
C
40  IF (M.GT.90) GO TO 60
50  IF (RAID(M,13).NE.0.) GO TO 70
    GO TO 560
60  JULIA = M-90
    IF (ASMT(JULIA,1).NE.1.) GO TO 50
C
C      GET THE MAXIMUM MISSILE RANGE FOR THIS BATTERY AND CHECK
C      TO SEE IF THERE ARE ANY TARGETS MORE THREATENING WHICH
C      IT IS CAPABLE OF HANDLING
C
70  ID = IFIX(SHIP(K,5)+AMF)
    ID = IFIX(X(ID+NMS-1)+AMF)
    KING = (ID-1)*40
    RGE = AMAX1(X(501+KING),X(508+KING))
    IF (M.GT.90) GO TO 80
    CALL LOCTIM (M,TIME,5,XP,YP)
    CALL CPA (XP,YP,RAID(M,5),RAID(M,6),SHIP(K,2),SHIP(K,3),RJL,EBTJR)
    GO TO 90
80  LML = IFIX(ASMT(JULIA,4)+AMF)
    CALL ASMTIM (M,TIME,XP,YP)
    CALL CPA (XP,YP,SHIP(LML,2),SHIP(LML,3),SHIP(K,2),SHIP(K,3),RJL,EB
1TJR)
90  TT = (RJL-SHIP(K,2))*2+(EBTJR-SHIP(K,3))*2
    IF (TT.LE.RGE**2) GO TO 100
    REASON = 13.
    GO TO 560
100 TT = X(532+KING)
    CALL PRIOR (M,K,NMS,NB,RGE,NC,TIME,M1,NCL,XP,YP)
C
C      IS NEW TARGET THE SAME AS THE OLD, OR HAS NEW BEEN DESTROYED?
C
    IF (M1.EQ.M) GO TO 120
    IF (M1.GT.90) GO TO 110
    IF (RAID(M1,13).EQ.0.) GO TO 50
    GO TO 120
110 JULIA = M1-90
    IF (ASMT(JULIA,1).NE.1.) GO TO 50
C
C      IF THERE IS COORDINATION,CHECK TO SEE IF THE TARGET IS
C      AVAILABLE
C
120 IF (X(4).EQ.0.) GO TO 140
    KP = IFIX(SHIP(K,5)+AMF)
    IF (X(KP+14).EQ.0.) GO TO 140

```

```

SUS 540
SUS 550
SUS 560
SUS 570
SUS 580
SUS 590
SUS 600
SUS 610
SUS 620
SUS 630
SUS 640
SUS 650
SUS 660
SUS 670
SUS 680
SUS 690
SUS 700
SUS 710
SUS 720
SUS 730
SUS 740
SUS 750
SUS 760
SUS 770
SUS 780
SUS 790
SUS 800
SUS 810
SUS 820
SUS 830
SUS 840
SUS 850
SUS 860
SUS 870
SUS 880
SUS 890
SUS 900
SUS 910
SUS 920
SUS 930
SUS 940
SUS 950
SUS 960
SUS 970
SUS 980
SUS 990
SUS 1000
SUS 1010

```



```

IF (TIME.GT.TGTAV(MI)) GO TO 140
REASON = 2
T = TGTAV(MI)+1.0E-3
130 KP = MI*100000+K*1000+NMS*100+NB*10+NC1
CALL STOREV (T,3,KP)
GO TO 560
140 IF (NONO(MI,K).EQ.0) GO TO 150
REASON = 8.
GO TO 560

C C C C C C C C C C
      FLAG ICOT SET TO 1 IF A) CHANNEL PREVIOUSLY ASSIGNED AND
      THAT CHANNEL IS BUSY, B) NO CHANNEL PREVIOUSLY ASSIGNED AND
      ALL CHANNELS ARE BUSY, EARLIEST AVAILABLE ASSIGNED, AND THE
      MISSILE ONLY REQUIRES THE DIRECTOR FOR THE FINAL PHASE
      OF THE INTERCEPT. SET TO 0 IF THE MISSILE REQUIRES NO
      DIRECTOR, OR IF THE CHANNEL ASSIGNED IS FREE.
150 NCH = IFIX(X(515+KING+NB*2)+AMF)
      IF (NC1.EQ.7) GO TO 250
      IF (NC1.EQ.0) GO TO 160
      IF (CHANNEL(K,NMS,NB,NC1).EQ.0.) GO TO 250
      GO TO 180

C
160 DO 170 I=1,NCH
      IF (CHANNEL(K,NMS,NB,I).EQ.0.) GO TO 240
170 CONTINUE

C
180 TA = 5000.
      KP = 0
      I = NSAM
190 KA = IFIX(SMAT(I,2)+AMF)
      IF (KA.NE.K) GO TO 220
      KA = IFIX(SAMASM(I,2)*1.0E-1+AMF)
      T = FLOAT(KA)
      KA = IFIX(SAMASM(I,2)-T*10.+AMF)
      IF (KA.NE.NMS) GO TO 220
      KA = IFIX(SAMASM(I,3)*1.0E-1+AMF)
      IF (KA.NE.NB) GO TO 220

C
      DO 200 J=1,NCH
      KA = J+3
      TIM = SMAT(I,KA)
      IF (TA.LE.TIM) GO TO 200
      JAPL = J
      TA = TIM
200 CONTINUE

C

```


SUB 1500
 SUB 1510
 SUB 1520
 SUB 1530
 SUB 1540
 SUB 1550
 SUB 1560
 SUB 1570
 SUB 1580
 SUB 1590
 SUB 1600
 SUB 1610
 SUB 1620
 SUB 1630
 SUB 1640
 SUB 1650
 SUB 1660
 SUB 1670
 SUB 1680
 SUB 1690
 SUB 1700
 SUB 1710
 SUB 1720
 SUB 1730
 SUB 1740
 SUB 1750
 SUB 1760
 SUB 1770
 SUB 1780
 SUB 1790
 SUB 1800
 SUB 1810
 SUB 1820
 SUB 1830
 SUB 1840
 SUB 1850
 SUB 1860
 SUB 1870
 SUB 1880
 SUB 1890
 SUB 1900
 SUB 1910
 SUB 1920
 SUB 1930
 SUB 1940
 SUB 1950
 SUB 1960
 SUB 1970

```

NC1 = JAPL
IF (TT.GT.0.) GO TO 260
TA = TA+1.OE-3
KP = 3+(NMS-1)*3+NB
IF (NADAR(K,KP).EQ.3) GO TO 210
REASON = 5.
GO TO 130
REASON = 12.
GO TO 130
210 GO TO 130
I = I-1
IF (I.NE.0) GO TO 190
220 IF (I.NE.0) GO TO 190
230 WRITE (6,620) K,NMS,NB
STOP
240 NC1 = I
250 TA = TIME
ICOT = 0
GO TO 270
260 ICOT = I
CHECK TO SEE IF OWN SHIP IS ENGAGING THE TARGET WITH ANOTHER
SYSTEM
270 DO 280 I=1,300
IF (SAMASM(I,I).EQ.0.) GO TO 300
LML = IFIX(SAMASM(I,I)+AMF)
IF (LML.NE.MI) GO TO 280
LML = IFIX(SAMASM(I,2)*1.OE-1+AMF)
IF (LML.NE.K) GO TO 280
IF (SAMASM(I,6).GT.TIME) GO TO 290
280 CONTINUE
GO TO 300
REASON = 6.
290 GO TO 560
300 IF (MI.LE.90) GO TO 320
CHECK TO SEE IF ASM WILL IMPACT BEFORE LAUNCH OF SAM.
CC
310 IF (ASMT(JULIA,2).GE.TA) GO TO 320
REASON = 10.
GO TO 560
CHECK TO SEE IF LAUNCHER IS LOADED
CC
320 IF (RELOAD(K,NMS).LE.TIME) GO TO 340
REASON = 9.
IF (MI.LE.90) GO TO 330
IF (RELOAD(K,NMS).GE.ASMT(JULIA,2)) GO TO 310

```


1980
 1990
 2000
 2010
 2020
 2030
 2040
 2050
 2060
 2070
 2080
 2090
 2100
 2110
 2120
 2130
 2140
 2150
 2160
 2170
 2180
 2190
 2200
 2210
 2220
 2230
 2240
 2250
 2260
 2270
 2280
 2290
 2300
 2310
 2320
 2330
 2340
 2350
 2360
 2370
 2380
 2390
 2400
 2410
 2420
 2430
 2440
 2450

```

330 T = RELGAD(K,NMS)
340 GO TO 130
340 IF (ICOT.EQ.0) GO TO 380
I = NSAM
C IF SAM/SSM CHANNELS BUSY STORE A SHOOT EVENT WHEN THE CHANNEL
C WILL BE FREE
C
350 LML = IFIX(SAMASM(I,2)*1.0E-1+AMF)
IF (LML.NE.K) GO TO 360
T = FLOAT(LML)
KP = IFIX(SAMASM(I,2)-T*10.+AMF)
IF (KP.NE.NMS) GO TO 360
LML = IFIX(SAMASM(I,3)*1.0E-1+AMF)
IF (LML.NE.NB) GO TO 360
T = FLOAT(LML)
KP = IFIX(SAMASM(I,3)-T*10.+AMF)
IF (KP.EQ.NC1) GO TO 370
I = I-1
IF (I.NE.0) GO TO 350
GO TO 230
370 T = SAMASM(I,6)+1.0E-3
REASON = 7.
GO TO 130
C
C CHECK TO SEE IF, IN FACT THIS MISSILE CAN INTERCEPT
C A TARGET WITH ITS FLIGHT CHARACTERISTICS
C
380 CALL TIMMY (M1,K,NMS,XP,YP,PROB,FT,KP,TIME)
C IF IND RETURNS FROM TIMMY WITH A VALUE OF 1, THE INTERCEPT
C IS POSSIBLE
C
390 IF (KP) 390,410,420
REASON = 14.
400 T = TIME+0.1
GO TO 130
410 REASON = 13.
GO TO 560
420 IF (KP.EQ.1) GO TO 430
REASON = 15.
GO TO 400
430 IF (TT.EQ.0.) GO TO 500
IF (NSAM.EQ.0) GO TO 500
C IF THE SYSTEM REQUIRES THE DIRECTOR ONLY PART TIME,
C CHECK TO SEE IF THE DIRECTOR WILL BE AVAILABLE WHEN NEEDED
C

```


SUB 2460
 SUB 2470
 SUB 2480
 SUB 2490
 SUB 2500
 SUB 2510
 SUB 2520
 SUB 2530
 SUB 2540
 SUB 2550
 SUB 2560
 SUB 2570
 SUB 2580
 SUB 2590
 SUB 2600
 SUB 2610
 SUB 2620
 SUB 2630
 SUB 2640
 SUB 2650
 SUB 2660
 SUB 2670
 SUB 2680
 SUB 2690
 SUB 2700
 SUB 2710
 SUB 2720
 SUB 2730
 SUB 2740
 SUB 2750
 SUB 2760
 SUB 2770
 SUB 2780
 SUB 2790
 SUB 2800
 SUB 2810
 SUB 2820
 SUB 2830
 SUB 2840
 SUB 2850
 SUB 2860
 SUB 2870
 SUB 2880
 SUB 2890
 SUB 2900
 SUB 2910
 SUB 2920
 SUB 2930

```

KIM = K*100+NMS*10+NB
TIG = TIME+FT-IT
TIME = 9000.
TFT = 9000.
I = NSAM
IF (I.EQ.0) GO TO 490
IF (I.EQ.1) GO TO 490
IF (I.EQ.2) GO TO 490
IF (I.EQ.3) GO TO 490
IF (I.EQ.4) GO TO 490
GO TO 440
NC2 = NCI+3
IPQ = NCH+3
C
DO 470 ID=4,IPQ
IF (ID.EQ.NC2) GO TO 470
IF (SMAT(I,ID).LT.ITG) GO TO 460
IT = SMAT(I,ID)-IT
IF (IT.GT.ITL) GO TO 460
GO TO 480
TCF(ID-3) = SMAT(I,ID)
460 CONTINUE
C
GO TO 490
IF (TFT.LT.SMAT(I,ID)) GO TO 460
MFOG = I
TFT = SMAT(I,ID)
GO TO 460
IF (MFOG.EQ.0) GO TO 500
REASON = I
T = TFT-FT+IT+1.0E-3
GO TO 130
C
IF OK, FILL IN THE SAMASM AND SAM TABLES, LOG THE
CHANNEL BUSY, STORE THE INTERCEPT EVENT
C
500 MFOG = IFIX(X(524+KING)+AMF)
NSAM = NSAM+1
IF (NSAM.GT.300) GO TO 600
I = NSAM
SAMASM(I,1) = FLOAT(M1)
SAMASM(I,2) = PROB
SAMASM(I,3) = FLOAT(K*10+NMS)
SAMASM(I,4) = FLOAT(NB*10+NC1)
SAMASM(I,5) = TIME+FT
SAMASM(I,6) = SAMASM(I,6)+5.I
CALL STOREV (SAMASM(I,6),5,I)
IBAT(K,NMS) = IBAT(K,NMS)-MFOG
SMAT(I,10) = FLOAT(MFOG)

```


660 FORMAT (' NUMBER OF SALVOS FIRED EXCEEDS 300, PROGRAM TERMINATING',SU3 3420
 1)END SU3 3430
 SU3 3440

```

SUBROUTINE SUBE4 (IU)
  THIS SUBROUTINE EVALUATES RED ASM/SSM FLIGHT PERFORMANCE
  AND DETERMINES IF THE RED MISSILE HIT THE BLUE TARGET
  COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMSU4
  IAT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NONO(190,40), ISEESU4
  2D,MAMBAL,KOUNT,NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASCSU4
  3NR,CHANNEL(40,4,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFLT(90,2),NR,NS,QSU4
  4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELDAD(40,4),SU4
  5MARY(100),CHECK,IFIRST,NPGS,KMART(4),NSAM,TGTAV(190),TCF(6),IHI(+SU4
  6),AMF,HISX(100),JACK(40,7),HISA(100)
  IQ = X(55)
  IF (IQ.EQ.0) GO TO 110
  CALL GETIMX (ID)
  PB = ID*2.6E-5
  WRITE (6,170) PB
  DETERMINE THE ASM/SSM NUMBER AND TARGET SHIP NUMBER
  ID = (IU/10)*10
  IF (ID.EQ.IU) IU = IU-1
  NAS = IFIX(FLOAT(IU)*1.0E-2+AMF)
  KP = NAS*100
  K = IU-KP
  NAM = NAS-90
  IU = IU+1
  IF (ID.EQ.IU) K = K+1
  IF THE ASM/SSM HAS BEEN SHOT DOWN OR THE SHOT INVALIDATED
  BY A BOMBER KILL, EXIT
  IF (ASMT(NAM,1).EQ.2..OR.ASMT(NAM,1).EQ.5.) GO TO 140
  ID = IFIX(ASMT(NAM,6)+AMF)
  PB = X(2005+(ID-1)*10)
  CALL RANDOM (ISEED,Z,1)
  X(13) = X(13)+1.
  DETERMINE INFLIGHT PERFORMANCE
  IF (Z.LE.PB) GO TO 120
  ASMT(NAM,1) = 3.
  GO TO 140
  
```


SUS 260
 SUS 270
 SUS 280
 SUS 290
 SUS 300
 SUS 310
 SUS 320
 SUS 330
 SUS 340
 SUS 350
 SUS 360
 SUS 370
 SUS 380
 SUS 390
 SUS 400
 SUS 410
 SUS 420
 SUS 430
 SUS 440
 SUS 450
 SUS 460
 SUS 470
 SUS 480
 SUS 490
 SUS 500
 SUS 510
 SUS 520
 SUS 530
 SUS 540
 SUS 550
 SUS 560
 SUS 570
 SUS 580
 SUS 590
 SUS 600
 SUS 610
 SUS 620
 SUS 630
 SUS 640
 SUS 650
 SUS 660
 SUS 670
 SUS 680
 SUS 690
 SUS 700
 SUS 710
 SUS 720
 SUS 730

```

NB = IFIX((SAMASM(M,3)*1.0E-1)+AMF)
ID = IFIX(SHIP(K,5)+AMF)
NC = IFIX(SAMASM(M,3)+AMF)-NB*10
IF (NC.EQ.7) GO TO 30

C C C
IF THE MISSILE USES A DIRECTOR, DETERMINE THE APPROPRIATE
REASSIGNMENT DELAYS

KEY = IFIX(X(ID+18)+AMF)
CALL REACT (KEY,5,TF)
IQ = IFIX(X(ID+NMS-1)+AMF)
IP = IFIX(X(516+(IQ-1)*40+NB*2)+AMF)
KEY = IFIX(X(906+(IP-1)*20)+AMF)
CALL REACT (KEY,4,TA)

C C C
INCREMENT THE FLEET AND SHIP COUNTERS IF APPROPRIATE

30 IF (IGAGE(NT).NE.0) GO TO 50
   IGAGE(NT) = 1
   IF (NT.GT.90) GO TO 40
   ISBG(K) = ISBG(K)+1
   IFBG = IFBG+1
   GO TO 50
40 ISAG(K) = ISAG(K)+1
   IFAG = IFAG+1

C C C
DETERMINE IF THE TARGET IS STILL THERE.

50 IF (NT.GT.90) GO TO 60
   IF (RAID(NT,13).GT.0.) GO TO 80
   GO TO 70
60 IF (ASMT(NA,1).EQ.2.) GO TO 70
   IF (ASMT(NA,1).NE.1.) GO TO 100
   GO TO 80
70 SAMASM(M,5) = -1.00
   IF (NC.EQ.7) GO TO 190
   GO TO 170
80 IQ = IFIX(X(ID+NMS-1)+AMF)
   PB = X(530+(IQ-1)*40)
   N = IFIX(X(524+(IQ-1)*40)+AMF)

C C C
DETERMINE KILL-NO KILL

PROB = PB*(1-(1-SAMASM(M,7))**N)
CALL RANDOM (ISEED,Z,1)
X(13) = X(13)+1
IF (Z.LE.PROB) GO TO 110
IF (NC.EQ.7) GO TO 90

```



```

90 CHANEL(K,NMS,NB,NC)=0.
   KP = NT*100000+K*1000+NMS*100+NB*10+NC
   C
   C
   C STORE A CHANNEL FREE EVENT
   C
   C CALL STCREV (SAMASM(M,6),3,KP)
   C SAMASM(M,5) = 0.
   C GO TO 220
100 SAMASM(M,5) = 0.
   C IF (NC.EQ.7) GO TO 190
   C GO TO 170
110 JACK(K,3) = JACK(K,3)+1
   C IF (NT.GT.90) GO TO 150
   C RAID(NT,13) = RAID(NT,13)-1.0001
   C IF (RAID(NT,13).GT.0.) GO TO 160
   C RAID(NT,13) = 0.0
   C
   C IF A RAIDER HAS BEEN SHOT DOWN OR SJNK, AND IT WAS A JAMMER,
   C ADJUST THE JAM TABLE
   C
   C NDU = IFIX(RAID(NT,1)+AMF)
   C IF (X(NDU+9).GT.0.) JAM(1)=JAM(1)-1
   C IF (X(NDU+10).GT.0.) JAM(2)=JAM(2)-1
   C IF (X(NDU+11).GT.0.) JAM(3)=JAM(3)-1
   C IF (X(NDU+12).GT.0.) JAM(4)=JAM(4)-1
   C RAID(NT,17) = SAMASM(M,6)
   C NTOT = MISLFT(NT,1)+MISLFT(NT,2)
   C
   C IF THE RAIDER HAS MISSILES LEFT ON BOARD- INDICATE "LOST
   C WHEN A/C SHOT DOWN OR SHIP SUNK"
   C
   C IF (NTOT.EQ.0) GO TO 130
   C MISLFT(NT,1) = 0
   C MISLFT(NT,2) = 0
   C
   C DO 120 I=1,NTOT
   C NASM = NASM+1
   C ASMT(NASM,1) = 5.
   C ASMT(NASM,2) = 0.
   C ASMT(NASM,4) = 0.
   C ASMT(NASM,6) = 0.
   C ASMT(NASM,7) = 0.
   C ASMT(NASM,8) = 0.
   C ASMT(NASM,5) = SAMASM(M,6)
   C ASMT(NASM,3) = FLOAT(NT)
   C CONTINUE
   C
120 ID = NASM-NTOT
   C
130 ID = NASM-NTOT

```

```

740
750
760
770
780
790
800
810
820
830
840
850
860
870
880
890
900
910
920
930
940
950
960
970
980
990
1000
1010
1020
1030
1040
1050
1060
1070
1080
1090
1100
1110
1120
1130
1140
1150
1160
1170
1180
1190
1200
1210
1220

```


SUS 1230
 SUS 1240
 SUS 1250
 SUS 1260
 SUS 1280
 SUS 1290
 SUS 1300
 SUS 1310
 SUS 1320
 SUS 1330
 SUS 1340
 SUS 1350
 SUS 1370
 SUS 1380
 SUS 1400
 SUS 1410
 SUS 1420
 SUS 1430
 SUS 1440
 SUS 1450
 SUS 1460
 SUS 1470
 SUS 1480
 SUS 1490
 SUS 1500
 SUS 1510
 SUS 1520
 SUS 1530
 SUS 1540
 SUS 1550
 SUS 1560
 SUS 1580
 SUS 1590
 SUS 1600
 SUS 1610
 SUS 1620
 SUS 1630
 SUS 1640
 SUS 1650
 SUS 1660
 SUS 1670
 SUS 1680
 SUS 1690

IF (RAID(NT,12).EQ.0.) GO TO 160
 CHECK ASM LAUNCH TIME OF SHOT DOWN RAIDER OR SSM LAUNCH
 TIME OF SURFACE RAIDER- IF AFTER TARGET KILL TIME- INDICATE
 NO LAUNCH.

DO 140 I=1, ID
 IQ = IFIX(ASMT(I,3)+AMF)
 IF (NT.NE.IQ) GO TO 140
 IF (ASMT(I,5).LT.SAMASM(M,6)) GO TO 140
 ASMT(I,1) = 5.
 ASMT(I,2) = 0.
 ASMT(I,5) = 0.
 ASMT(I,4) = 0.
 ASMT(I,7) = 0.
 ASMT(I,8) = 0.
 C CONTINUE

140 C

GO TO 160
 ASMT(NA,1) = 2.
 SAMASM(M,5) = FLOAT(N)
 TK = X(533+(IQ-I)*40)
 IF (NC.EQ.7) GO TO 190
 SAMASM(M,6) = SAMASM(M,6)+TK+TA+TF
 JFK = NC+3
 SMAT(M,JFK) = SAMASM(M,6)
 GO TO 180
 SAMASM(M,6) = SAMASM(M,6)+TA+TF
 JFK = NC+3
 SMAT(M,JFK) = SAMASM(M,6)
 KP = SAMASM(M,2)*100.+SAMASM(M,3)
 CALL STOREV (SAMASM(M,6),6,KP)
 IF (X(58).EQ.0.) SAMASGO TO 200
 WRITE(6,240) M, SAMASM(M,5)
 WRITE(6,250) M, GO TO 210
 WRITE(6,250) NT,K,NMS,M,SAMASM(M,6)
 IF (X(55).EQ.0.) GO TO 220
 CALL GETIMX(ID)
 PB = ID*2.6E-5
 WRITE(6,260) PB
 RETURN

220 C

FORMAT (' SUBES IN AT',F15.8)
 FORMAT ('0',,FOR SHOT',I4,,' RESULTS',F4.0)
 FORMAT ('0',,EV 5 TGT NO.',I4,,' FS',I3,,' LAUNCHER',I2,,' SAMS',I4,
 ' TIME',F8.3)
 FORMAT (' SUBES OUT AT',F15.8)
 END


```

SUBROUTINE SUBE6 (M)
C
C THIS SUBROUTINE RELEASES A FIRE CONTROL CHANNEL
C FOR FURTHER USE AFTER AN ENGAGEMENT AND THE APPROPRIATE
C TIME DELAYS.
COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMS
1AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NONO(190,40), ISEES
2D,MAMBAT,KOUNT,NADAK(40,19), RXATA(5), LOVER, ITEMS, PLIST(40,6), REASCS
3N,CHANNEL(40,4,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFT(90,2),NR,NS,Q
4R(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG,RELOAD(40,4),SUB
5MARY(100),CHECKK,IFIRST,NPGS,KMART(4),NSAM,TGTAV(190),ICF(6),IHIT(4
60),AMF,HISX(100),JACK(40,7),HISA(100)
C
IF (X(55).EQ.0.) GO TO 110
CALL GETIMX(I)
T = I#2.6E-5
WRITE (6,130) T
110 M = M+2
K = M*1.0E-3
NMS = (M-K*1000)*1.0E-2
I = M-K*1000-NMS*100
NB = I*1.0E-1
NC = I-NB*10
CHANNEL(K,NMS,NB,NC)=0.
IF (X(55).EQ.0.) GO TO 120
CALL GETIMX(I)
T = I#2.6E-5
WRITE (6,140) T
120 RETURN
C
130 FORMAT (: SUBE6 IN AT : ,F14.8)
140 FORMAT (: SUBE6 OUT AT : ,F15.8)
END
C
SUBROUTINE TIMMY (M,K,NMS,XP,YP,PROB,FT,IND,TIME)
TIM
TIM
TIM
TIM
COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMT
1AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NONO(190,40), ISEES
2D,MAMBAT,KOUNT,NADAK(40,19), RXATA(5), LOVER, ITEMS, PLIST(40,6), REAS
TIM
TIM
TIM
TIM
C THIS SUBROUTINE COMPUTES THE PREDICTED INTERCEPT POINT AND
C DETERMINES WHETHER OR NOT IT LIES WITHIN THE INTERCEPT
C CONTOUR.
C
C
C

```



```

IF (KP.EQ.3412.OR.KP.EQ.4312.OR.KP.EQ.3421.OR.KP.EQ.4321) GO TO 60
IF (KP.EQ.2341.OR.KP.EQ.2431.OR.KP.EQ.1342.OR.KP.EQ.1432) GO TO 80
IF (KP.EQ.1234.OR.KP.EQ.1243.OR.KP.EQ.2134.OR.KP.EQ.2143) GO TO 11
10 IF (KP.EQ.1324.OR.KP.EQ.2413) GO TO 60
IF (KP.EQ.3241.OR.KP.EQ.4132) GO TO 100

```

CC

IF THE SHIP HAS NONE, EXIT.

REASON = 2.

```

GO TO 480
FZL = RXATA(1)
FZR = RXATA(4)
FZL1 = RXATA(3)
FZR1 = RXATA(2)

```

60

KP = 2

```

GO TO 120
FZL = RXATA(2)
FZR = RXATA(1)

```

70

KP = 1

```

GO TO 120
FZL = RXATA(4)
FZR = RXATA(3)

```

80

KP = 1

```

GO TO 120
FZL = RXATA(3)
FZR = RXATA(2)

```

90

KP = 1

```

GO TO 120
FZL = RXATA(4)
FZR = RXATA(3)
FZL1 = RXATA(2)
FZR1 = RXATA(1)

```

100

KP = 2

```

GO TO 120
FZL = RXATA(1)
FZR = RXATA(4)

```

110

KP = 1

COLLECT TARGET ALTITUDE AND MAXIMUM SAM ALTITUDE. GET MISSILE PARAMETERS UNLESS TARGET TOO HIGH, IN WHICH CASE, EXIT.

CC

```

120 KPX = 7
IF (X(KL+35).EQ.1.) KPX=0
IF (M.GT.90) GO TO 130
ALT = KAID(M,9)
GO TO 140

```

```

580 TTTTMM
590 TTTTMM
600 TTTTMM
610 TTTTMM
620 TTTTMM
630 TTTTMM
640 TTTTMM
650 TTTTMM
660 TTTTMM
670 TTTTMM
680 TTTTMM
690 TTTTMM
700 TTTTMM
710 TTTTMM
720 TTTTMM
730 TTTTMM
740 TTTTMM
750 TTTTMM
760 TTTTMM
770 TTTTMM
780 TTTTMM
790 TTTTMM
800 TTTTMM
810 TTTTMM
820 TTTTMM
830 TTTTMM
840 TTTTMM
850 TTTTMM
860 TTTTMM
870 TTTTMM
880 TTTTMM
890 TTTTMM
900 TTTTMM
910 TTTTMM
920 TTTTMM
930 TTTTMM
940 TTTTMM
950 TTTTMM
960 TTTTMM
970 TTTTMM
980 TTTTMM
990 TTTTMM
1000 TTTTMM
1010 TTTTMM
1020 TTTTMM
1030 TTTTMM
1040 TTTTMM
1050 TTTTMM

```



```

130 ID = IFIX(ASMT(JULJA,6)+AMF)
140 ALT = X(2002+(ID-1)*10)
      IF (ALT.GT.X(77)) KPX=0
      IF (ALT.LE.X(KL+15)) GO TO 150
      REASON = 11.
      GO TO 480
150 KPX = KL+KPX
      KMAX = X(KPX)
      SSPD = X(KPX+1)
      A = X(KPX+2)
      B = X(KPX+3)
      EX = X(KPX+4)
      SLOPE = X(KPX+5)
      SEEK = X(KPX+6)
      RMIN = X(KL+14)

```

C C C DETERMINE IF THE TARGET WILL ENTER THIS SYSTEM'S ENVELOPE

```

IF (M.LE.90) GO TO 160
IR = IFIX(ASMT(JULIA,3)+AMF)
VEL = RAID(IR,14)
PS = RAID(IR,15)
RAID(IR,14) = XT
RAID(IR,15) = YT
PT = RAID(IR,2)
RAID(IR,2) = XP
RAID(IR,3) = YP
RAID(IR,4) = YP
GO TO 170
RAID(M,14) = XT
RAID(M,15) = YT
CALL LOCTIM (M,TIME,5,XI,YI)
KVEL = IFIX(X(2201+(M-1)*6)+AMF)
IR = X(1814+(KR-1)*20)

```

```

160
170 CALL TMDASM (IR,0,NMS,K,VEL,RMAX,TIME,TX,XI,YI,RIP,TXL,M)
      IF (M.LE.90) GO TO 180
      RAID(IR,14) = PQ
      RAID(IR,15) = PS
      CALL LOCTIM (IR,PT,5,PS,PQ)

```

C C C IF TARGET BEYOND RANGE AND OUTBOUND,EXIT.

```

180 IF (TX.NE.9120.) GO TO 190
      REASON = 7.
      GO TO 480

```

C


```

C      IF GSINE GREATER THAN ONE, INTERCEPT IS IMPOSSIBLE
C      IF (ABS(GSINE).LE.1.) GO TO 280
      REASON = 10.
      GO TO 480
250    IF (M.LE.90) GO TO 260
      DELTAX = ASMT(JULIA,7)-SHIP(K,2)
      DELTAY = ASMT(JULIA,8)-SHIP(K,3)
      GO TO 240
260    CALL LOCTIM (M,0.,1,XW,YW)
      DELTAX = XW-SHIP(K,2)
      DELTAY = YW-SHIP(K,3)
      GO TO 240
270    IF (PHI.LT.0.) PHI = PHI+2.*PI
280    GAMMA = ARSIN(GSINE)
      BETA = PI-GAMMA-ALPHA
      DELTA = PI-BETA
C
C      IF (ABS(DELTAX).LT.5.0E-5) DELTAX=0.0
      IF (ABS(DELTAY).LT.5.0E-5) DELTAY=0.0
      DLT = SQRT(DELTAX**2+DELTAY**2)
      IF (X(59).EQ.0.) GO TO 290
      WRITE (6,530)
      WRITE (6,540)
      WRITE (6,550) M,K,ALPHA,BETA,GAMMA,XP,YP,GSINE,DLT
290    P4 = PI/4.
      IF (DELTA.LE.P4) GO TO 300
      PK = X(KL+36)
      GO TO 310
300    PK = X(KL+28)
C
C      IF TARGET NOT ASM TARGETED ON FIRING SHIP, COMPUTE FLIGHT
      TIME
C
C      FT = DLT*SIN(ALPHA)/(SSPD*SIN(BETA))
      IF (M.LE.90) GO TO 320
      KPX = FIX(SHIP(K,5)+AMF)
      IF (X(KPX+29).EQ.0.) GO TO 320
      TKIL = TIME+FT
      IF (TKIL.LT.ASMT(JULIA,2)) GO TO 320
      REASON = 3.
      GO TO 480
320    TKIL = TIME+FT
      GET INTERCEPT POSIT
C
C      IF (M.GT.90) GO TO 330

```


IF (ID.EQ.123.OR.ID.EQ.231.OR.ID.EQ.312) GO TO 360

CAN MISSILE ENGAGE

410 IF (ABS(DELTA X).LT.5.0E-5) DELTAX=0.
IF (ABS(DELTA Y).LT.5.0E-5) DELTAY=0.

DIS = SQRT(DELTA X**2+DELTA Y**2)

IF (DIS.GE.RMIN) GO TO 420

REASON = 4.

IND = -1

GO TO 480

PHI1 = CS-3.*PI/2.

IF (PHI1.LT.0.) PHI1=PHI1+2.*PI

XIS = XI-SHIP(K,2)

YIS = YI-SHIP(K,3)

XIP = ABS(XIS*COS(PHI1))+YIS*SIN(PHI1))

YIP = ABS(YIS*COS(PHI1))-XIS*SIN(PHI1)

Z = (XIP/A)**EX+(ABS(YIP)/B)**EX

IF (Z.LE.1.) GO TO 430

REASON = 5.

IND = -1

GO TO 480

Z = YIP-SLOPE*XIP

IF (Z.GE.SEEK) GO TO 440

REASON = 6.

GO TO 480

IF (X(76).EQ.0.) GO TO 460

PIZ = X(76)**2

DO 450 I=1,NS

IF (I.EQ.K) GO TO 450

DELTA X = ABS(SHIP(I,2))-XI)

DELTA Y = ABS(SHIP(I,3))-YI)

IF (DELTA X.LT.5.0E-5) DELTAX=0.0

IF (DELTA Y.LT.5.0E-5) DELTAY=0.0

DIS = DELTAX**2+DELTAY**2.

IF (DIS.GE.PIZ) GO TO 450

IND = 2

REASON = 9.

GO TO 480

C CONTINUE

IF THE TARGET IS AN ASM WHOS TARGET IS THE FIRING SHIP,
OR THE TARGET IS A SURFACE/SUB SURFACE UNIT, PROCEED,
OTHERWISE ADD IN THE TARGET ALTITUDE TO MISSILE FLIGHT TIME

460 IF (M.LE.90) GO TO 470

JOAN = IFIX(ASMT(JULIA,4)+AMF)

2980
2990
3000
3010
3020
3030
3040
3050
3060
3070
3080
3090
3100
3110
3120
3130
3140
3150
3160
3170
3180
3190
3200
3210
3220
3230
3240
3250
3260
3270
3280
3290
3300
3310
3320
3330
3340
3350
3360
3370
3380
3390
3400
3410
3420
3430
3440
3450


```

IF (JOAN.EQ.K) GO TO 470
RUTH = ALI/6000.
IF (RUTH.LT.AMF) GO TO 470
FT = SQRT((DIS+RUTH**2)/SSPD
470  PMD = X(KL+30)
      PROB = PK*PM
      IF (X(9).EQ.0.) GO TO 490
WRITE (6,570) M,K
480  WRITE (6,570) SHIP(K,2),SHIP(K,3),XI,YI,KP,FZL,FZL,FZL1,FZRI,PHI
      IF (X(9).EQ.0.) GO TO 490
WRITE (6,580) M,K,IND,REASON
490  IF (X(55).EQ.0.) GO TO 500
      CALL GETIMX(KP)
      XT = KP*2.6E-5
      WRITE (6,590) XT
500  RETURN
      (TIMMY IN AT',F15.8)
510  FORMAT ('0',TARGET',I4',DATA',I4')
520  FORMAT ('0',CROSSING TARGET SHIP',I4)
530  FORMAT ('0',TAR,XP,YP,SAM FLIGHT LAUNCH',I3)
540  1GLE BEM FLIGHT PATH LOS,4,F15.4,F17.4,F13.2,F9.2,F8.4,F9.2)
      2DS SAM TGT FLIGHT PATH DATA:6,7X,Y-INT,2X,# ZONES,3
      3SHIP, I3, TARGET COURSE',F5.2)
550  FORMAT ('0',INTERCEPT DATE:6,7X,Y-INT,2X, BEARING',/(F11.1,
560  FORMAT ('0',X-FT 1,5X:2,4X,I4,2(3X,F6.3),10X,F6.3)
570  1X,2,2(5X,I4),1X,I4,4X,I3, IND IS',I3, REASON IS',F3.0)
      27.2,2(5X,I4),1X,I4,4X,I3, IND IS',I3, REASON IS',F3.0)
580  FORMAT ('0',TIMMY OUT AT',F15.8)
590  END

```

```

TIM 3460
TIM 3470
TIM 3480
TIM 3490
TIM 3500
TIM 3510
TIM 3520
TIM 3530
TIM 3540
TIM 3550
TIM 3560
TIM 3570
TIM 3580
TIM 3590
TIM 3600
TIM 3610
TIM 3620
TIM 3630
TIM 3640
TIM 3650
TIM 3660
TIM 3670
TIM 3680
TIM 3690
TIM 3700
TIM 3710
TIM 3720
TIM 3730
TIM 3740
TIM 3750
TIM 3760
TIM 3770
TIM 3780

```

```

SUBROUTINE JAMM (RG,IR,IJ,IR,IJ,ID,VEL,RRH,AREA,IBM,ICPA,RGI)
THIS SUBROUTINE DETERMINES THE RANGE AT WHICH A TARGET CAN
BE DETECTED IN A MULTIPLE STAND-OFF JAMMING ENVIRONMENT
RG-----MINIMUM RANGE OF CLEAR AND HORIZON (INPUT)
IR-----SHIP NUMBER OF TARGET (INPUT)
IJ-----KAIDER NUMBER OF RADAR (INPUT)
IJ-----FREQUENCY BAND OF RADAR (INPUT)
ID-----VELOCITY CLASS NUMBER IN NM/MIN (INPUT)
VEL-----RADAR'S HORIZON (INPUT)
RRH-----RADAR'S HORIZON (INPUT)
AREA-----FOURTH ROOT OF RAIF TARGET IS AN AIRCRAFT OR MISSILE (INPUT)
IBM-----FLAG INDICATING IF TARGET IS A BOMBER. IF TARGET IS A
      EQUAL TO 0 IF TARGET IS A BOMBER.

```

```

JAM 10
JAM 20
JAM 30
JAM 40
JAM 50
JAM 60
JAM 70
JAM 80
JAM 90
JAM 100
JAM 110
JAM 120
JAM 130

```

CCCCCCCCCCCC


```

MISSILE SET TO 1 (INPUT)
FLAG INDICATING IF TARGET'S CPA LESS THAN DETECTION
RANGE. EQUAL TO 0 IF CPA IS BEYOND RANGE (OUTPUT)
RGI-----DETECTION RANGE (OUTPUT)
JAM 140
JAM 150
JAM 160
JAM 170
JAM 180
JAM 190
JAM 200
JAM 210
JAM 220
JAM 230
JAM 240
JAM 250
JAM 260
JAM 270
JAM 280
JAM 290
JAM 300
JAM 310
JAM 320
JAM 330
JAM 340
JAM 350
JAM 360
JAM 370
JAM 380
JAM 390
JAM 400
JAM 410
JAM 420
JAM 430
JAM 440
JAM 450
JAM 460
JAM 470
JAM 480
JAM 490
JAM 500
JAM 510
JAM 520
JAM 530
JAM 540
JAM 550
JAM 560
JAM 570
JAM 580
JAM 590
JAM 600
JAM 610

ICPA-----
RANGE. EQUAL TO 0 IF CPA IS BEYOND RANGE (OUTPUT)
RGI-----DETECTION RANGE (OUTPUT)

COMMON X(2744), ASMT(100,8), SAMASM(300,7), KAID(90,17), SHIP(40,6), SMJAM
1AT(300,10), IVENTS(1000,2), SSTATS(40,2), IBAT(40,4), NONO(190,40), ISEESJAM
2D, MAMBAT, KOUNT, NADAR(40,19), RXATA(5), LOVER, ITEMS, PLIST(40,6), REASQJAM
3NT, CHANNEL(40,4,3,6), NASM, JAM(4), TMAX, NRTGT(90), MISLFT(90,2), NR, NS, QJAM
4RT(50), IFLASK, IGAGE(190), ISAG(40), IFAG, ISBG(40), IFBGR, RELOAD(40,4), JAM
5MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), TCF(6), IHIT(4
60), AMF, HISX(100), JACK(40,7), HISA(100)
REAL #4JJTBR, LJBW, GO TO 20
IF (X(55), EQ, 0) GO TO 20
ICALL GETIMX (IET)
T=IET*.0000020
WRITE (6,290) T
ICPA = 1
20

SET SITE VALUES
XR = SHIP(1,2)
YR = SHIP(1,3)

SET TRACK VALUES
IF (IBM, EQ, 0) GO TO 30
XI = ASMT(NASM,7)
YI = ASMT(NASM,8)
ITS = IFIX(ASMT(NASM,4)+AMF)
XO = SHIP(ITS,2)
YO = SHIP(ITS,3)
MIC = IFIX(ASMT(NASM,6)+AMF)
ZIMC = X(2002+(MIC-1)*10)/6000.
GO TO 40
XI = RAID(IR,3)
YI = RAID(IR,4)
XO = RAID(IR,14)
YO = RAID(IR,15)
ZIMC = RAID(IR,9)/6000.
CALL CPA (XI, YI, XO, YO, XR, YR, XC, YC)
RCPS = RG*2
RG = RG*2
40

DETERMINE IF CPA IS WITHIN RANGE

```


JAM 620
 JAM 630
 JAM 640
 JAM 650
 JAM 660
 JAM 670
 JAM 680
 JAM 690
 JAM 700
 JAM 710
 JAM 720
 JAM 730
 JAM 740
 JAM 750
 JAM 760
 JAM 770
 JAM 780
 JAM 790
 JAM 800
 JAM 810
 JAM 820
 JAM 830
 JAM 840
 JAM 850
 JAM 860
 JAM 870
 JAM 880
 JAM 890
 JAM 900
 JAM 910
 JAM 920
 JAM 930
 JAM 940
 JAM 950
 JAM 960
 JAM 970
 JAM 980
 JAM 990
 JAM 1000
 JAM 1010
 JAM 1020
 JAM 1030
 JAM 1040
 JAM 1050
 JAM 1060
 JAM 1070
 JAM 1080
 JAM 1090

```

IF (RCPS.GE.RGS) GO TO 250
DELX = ABS(X0-X1)-0.1
DELY = ABS(Y0-Y1)-0.1
IF (DELX.LT.0.0.AND.DELY.LT.0.0) GO TO 90
TIMI = (ABS(YC-Y1))/VEL+TIMC
50 GO TO 100
60 IF (DELY) 70,80,80
70 TIMI = (ABS(XC-X1))/VEL+TIMC
80 GO TO 100
VD = SQRT(((X0-X1)**2+(Y0-Y1)**2)
VX = VEL*(X0-X1)/VD
VY = VEL*(Y0-Y1)/VD
TIMX = (XC-X1)/VX
TIMY = (YC-Y1)/VY
TIMI = (TIMX+TIMY)/2.+TIMC
90 TIMI = 3.0

CC C
CC C
      DETERMINE BEARING FROM RADAR TO TARGET IN RADIANS
100 YRT = YC-YR
    XRT = XC-XR
    IF (YRT.NE.0.0.OR.XRT.NE.0.0) GO TO 110
    YRT = Y1-YR
    XRT = X1-XR
    TBRG = ATAN2(YRT,XRT)
110 IF (TBRG.LT.0.) TBRG=TBRG+6.2831853

CC C
      GET HALF RADAR BEAM WIDTH IN RADIANS
    HRBW = X(911+(ID-1)*20)
    SUMJP = 0.0
    RCOF = X(904+(ID-1)*20)

CC C
      DETERMINE JAMMING LEVEL AT THE RADAR IN DIRECTION OF TARGET
    DO 240 N=1,NR
    IF (TIMI.GT. RAID(N,17)) GO TO 240
    RCOFF = RCOF
    IRC = IFIX(X(2201+(N-1)*6)+AMF)
    IIR = (IRC-1)*20

CC C
      FIND JAMMING POWER OF RAIDER ON RADAR BAND
    PJ = X(1809+IIR+IJ)
    IF (PJ.LE.0.0) GO TO 240
    CALL LOCTIM (N,TIMI,1,XJ,YJ)
  
```


JAM 1109
 JAM 1110
 JAM 11120
 JAM 11130
 JAM 11140
 JAM 11150
 JAM 11160
 JAM 11170
 JAM 11180
 JAM 11190
 JAM 1200
 JAM 1210
 JAM 1220
 JAM 1230
 JAM 1240
 JAM 1250
 JAM 1260
 JAM 1270
 JAM 1280
 JAM 1290
 JAM 1300
 JAM 1310
 JAM 1320
 JAM 1330
 JAM 1340
 JAM 1350
 JAM 1360
 JAM 1370
 JAM 1380
 JAM 1390
 JAM 1400
 JAM 1410
 JAM 1420
 JAM 1430
 JAM 1440
 JAM 1450
 JAM 1460
 JAM 1470
 JAM 1480
 JAM 1490
 JAM 1500
 JAM 1510
 JAM 1520
 JAM 1530
 JAM 1540
 JAM 1550
 JAM 1560
 JAM 1570

```

CC C      DETERMINE IF JAMMER IS ABOVE RADAR HORIZON
CC C      RJHS = (RAID(N,10)+RRH)**2
CC C      RRJS = (XR-XJ)**2+(YR-YJ)**2
CC C      IF (RRJS.GT.RJHS) GO TO 240
CC C      DETERMINE COORDINATES OF JAMMER TARGET
CC C      JS = IFIX(X(2206+(N-1)*6)+AMF)
CC C      IF (JS.EQ.0) GO TO 240
CC C      IF (JS.GT.40) GO TO 120
CC C      YJTT = SHIP(JS,2)
CC C      GO TO 130
120 XJTT = 0.0
130 YJTT = 0.0
130 YJK = YR-YJ
130 XJR = XR-XJ
130 IF (YJR.NE.0.0.OR.XJR.NE.0.0) GO TO 140
CC C      CALL LOCTIM (N,0.0,1,XJJ,YJJ)
CC C      YJR = YR-YJJ
CC C      XJR = XR-XJJ
CC C      GET BEARING FROM JAMMER TO RADAR AND FROM RADAR TO JAMMER
140 JRBRG = ATAN2(YJR,XJR)
CC C      IF (JRBRG.LT.0.0) JRBRG=JRBRG+6.2831853
CC C      RJBRG = JRBRG-3.1415926
CC C      IF (RJBRG.LT.0.0) RJBRG=RJBRG+6.2831853
CC C      FIND BEARING FROM JAMMER TO JAMMER'S TARGET
CC C      YJJT = YJT-YJ
CC C      XJJT = XJT-XJ
CC C      IF (YJJT.NE.0.0.OR.XJJT.NE.0.0) GO TO 150
CC C      CALL LOCTIM (N,0.0,1,XJJ,YJJ)
CC C      YJJT = YJT-YJJ
CC C      XJJT = XJT-XJJ
150 JTTBR = ATAN2(YJJT,XJJT)
CC C      IF (JTTBR.LT.0.0) JTTBR=JTTBR+6.2831853
CC C      GET JAMMER SIDE-LOBE COEFFICIENT AND HALF-BEAM WIDTH
CC C      COFF = X(1818+IIR)
CC C      HJBW = X(1817+IIR)
CC C      LJBW = JTTBR+HJBW
CC C      RJBW = JTTBR-HJBW

```



```

1580 JAM
1590 JAM
1600 JAM
1610 JAM
1620 JAM
1630 JAM
1640 JAM
1650 JAM
1660 JAM
1670 JAM
1680 JAM
1690 JAM
1700 JAM
1710 JAM
1720 JAM
1730 JAM
1740 JAM
1750 JAM
1760 JAM
1770 JAM
1780 JAM
1790 JAM
1800 JAM
1810 JAM
1820 JAM
1830 JAM
1840 JAM
1850 JAM
1860 JAM
1870 JAM
1880 JAM
1890 JAM
1900 JAM
1910 JAM
1920 JAM
1930 JAM
1940 JAM
1950 JAM
1960 JAM
1970 JAM
1980 JAM
1990 JAM
2000 JAM
2010 JAM
2020 JAM
2030 JAM
2040 JAM

```

DETERMINE IF RADAR IS IN MAIN BEAM OF JAMMER
IF (LJBW.GT.6.2831853) GO TO 160
IF (RJBW.LT.0.0) GO TO 170
IF (LJBW.GT.JRBRG.AND.RJBW.LT.JRBRG) COFF=1.0
GO TO 190
LJBW = LJBW-6.2831853
GO TO 180
RJBW = RJBW+6.2831853
180 IF (LJBW.GT.JRBRG.OR.RJBW.LT.JRBRG) COFF=1.0
DETERMINE IF JAMMER IS IN MAIN BEAM OF RADAR
190 LTBWG = TBRG+HRBW
RTBRG = TBRG-HRBW
IF (LTBRG.GT.6.2831853) GO TO 200
IF (RTBRG.LT.0.0) GO TO 210
IF (LTBRG.GT.RJBRG.AND.RTBRG.LT.RJBRG) RCOFF=1.0
GO TO 230
LTBRG = LTBRG-6.2831853
GO TO 220
RTBRG = RTBRG+6.2831853
220 IF (LTBRG.GT.RJBRG.OR.RTBRG.LT.RJBRG) RCOFF=1.0
230 XCOF = CDEF*RCOFF
RRJS = (RRJS+(RAID(N,9)/6000.))*2
SUMJP = SUMJP+(XCOF*PJ/RRJS)
240 CONTINUE
C
IF (SUMJP.LE.0.0) GO TO 260
RGI = AREA*SQRT(X(903+(ID-1)*20))/SUMJP**.25
RGI = AMIN1(RG,RGI)
IF (RGI#2.LE.RCPS) GO TO 250
GO TO 270
ICPA = 0
RGI = 0.0
GO TO 270
RGI = RG
270 IF (X(55).EQ.0.) GO TO 280
CALL GETIMX(IET)
IET = IET#.0000026
WRITE (6,300) T
RETURN
280
C
290 FORMAT (I, JAMM IN AT',F15.8)
300 FORMAT (I, JAMM OUT AT',F15.8)
END


```

SUBROUTINE BIDE (N,NSR,ALT,IR,VEL,SIGMA,ND,TD,TL,RR,TD2,TL2,R2,IBM)
1M)
THIS SUBROUTINE DETERMINES WHEN A TARGET IS DETECTED BY A
BISTATIC RADAR SYSTEM IN EITHER A CLEAR OR A JAMMING SITUATION
N-----RADAR RECEIVER NUMBER (INPUT)
NSR-----RADAR RECEIVER NUMBER (INPUT)
ALT-----TARGET ALTITUDE IN FEET (INPUT)
IR-----RAIDER NUMBER OF TARGET (INPUT)
SIGMA-----TARGET CROSS SECTION IN METERS SQUARED (INPUT)
ND-----NUMBER OF DETECTION ZONES. 2--TWO ZONES (OUTPUT)
TD-----TIME OF FIRST DETECTION (OUTPUT)
TL-----TIME CONTACT LOST IN FIRST DETECTION ZONE (OUTPUT)
RR-----RANGE FROM RECEIVER TO TARGET AT TIME OF DETECTION
TD2-----TIME OF INITIAL DETECTION IN SECOND ZONE. USED ONLY
IF ND=2 (OUTPUT)
IF ND=2, TIME CONTACT LOST IN SECOND ZONE (OUTPUT)
R2-----IF ND=2, RANGE AT WHICH TARGET FIRST DETECTED IN
SECOND DETECTION ZONE (OUTPUT)
IBM-----FLAG INDICATING IF TARGET IS AN AIRCRAFT OR MISSILE.
COMMON X(2744),ASMT(100,8),SABMASM(100,17),SHIP(40,6),SMBID
1A(300,10),IVEVTS(1000,2),STRTX(40,2),IBAT(40,4),NANO(190,40),ISEEBID
2D,MAMBAL,KUNT,NADAR(40,19),SATS(40,5),LUVTR(90,2),REASOBI
3N,CHANNEL(40,4,3,6),NASM,JASG(190,4),ITEMS,PLIST(40,6),REASOBI
4RT(50),IFLASK,IGAGE(190),IFAG(90),MISLFT(90,2),NR,NS,
5MARY(100),CHECK,IFIRST,NPGS,KMART(4),IFBG,RELCAD(40,4),
6O),AMF,HISX(100),JACK(40,7),HISA(100)
REAL #4JTBRLJBM,JRBRG,LTBRG
DIMENSION XCOF(5),COF(5),TIME(4),T(4)
REAL #8VVD,VX,VY,A,B,CC,EE,FEI,A2,CC,EE,XRAD,A1,CHAS
REAL #8CHAR,RRAD,COF,TIMEI,A2,CC,EE,XRAD,A1,CHAS
IF (X(55).EQ.0.) GO TO 20
CALL GETIMX(IET)
PIGS = IET*.000026
WRITE (6,530) PIGS

SET SITE VALUES
20 XR = SHIP(N,2)
YR = SHIP(N,3)
L = IFIX(SHIP(N,5)+AMF)

BISTATIC RECEIVER HEIGHT IN FEET
ZR = X(L+6+NSR)

```

CCCCCCCCCCCCCCCCCCCC

CC

CC


```
ZRN = ZR/6000.
LL = IFIX(X(L+3+NSR)+AMF)
LLJ = (LL-1)*20
CHAS = DBLE(X(902+LLJ))
CHAR = DBLE(SIGMA)*CHAS**4
IT = IFIX(X(917+LLJ)+AMF)
YX = SHIP(IT,2)
YX = SHIP(IT,3)
```

C C BISTATIC TRANSMITTER HEIGHT IN FEET

```
ZX = X(918+LLJ)
ZYN = ZX/6000.
```

C C SET TRACK VALUES

```
X1 = RAID(IR,3)
Y1 = RAID(IR,4)
X0 = RAID(IR,14)
Y0 = RAID(IR,15)
Z1 = ALTI/6000.0
Z12 = (ALTI/6000.0)**2
V = VEL
TLMC = RAID(IR,2)
IFLAG = 0
JFLAG = 0
```

C C CHECK FOR TARGET CPA AT RECEIVER OR TRANSMITTER LOCATION

```
DELY = ABS(XO-XR)-0.01
DELY = ABS(YO-YR)-0.01
IF (DELY.LT.0.0.AND.DELY.LT.0.0) GO TO 70
DELY = ABS(XO-XX)-0.01
DELY = ABS(YO-YX)-0.01
IF (DELY.LT.0.0.AND.DELY.LT.0.0) GO TO 80
```

C C DETERMINE IF NO MOTION IN X AND Y DIRECTIONS

```
DELY = ABS(Y1-Y0)-0.1
DELY = ABS(X1-X0)-0.1
IF (DELY.LT.0.0.AND.DELY.LT.0.0) GO TO 40
```

C C COMPUTE CPA TO RECEIVER AND TRANSMITTER

```
IF (DELY) 30,50,50
30 XRC = XR
YRC = Y1
XXC = XX
```

```

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1000

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```

40 YXC = Y1
   GO TO 100
   IFLAG = 1
60 IF (DELX) 60,90,90
   XRC = YR
   XRC = XR
   GO TO 100
70 XRC = YO
   CALL CPA (X1,Y1,XO,YO,XX,XY,XXC,XYC)
80 XRC = XO
   CALL CPA (X1,Y1,XO,YO,XR,YR,XRC,YRC)
90 Q = (Y1-YO)/(X1-XO)
   XRC = (YR-YO+XR/Q+Q*XO)/(Q+1/Q)
   XXC = (YX-YO+XX/Q+Q*XO)/(Q+1/Q)
   YXC = YX-(XXC-XX)/Q

C    DETERMINE TIME OF DETECTION
C    COMPUTE RADAR HORIZON FOR TRANS AND RECEIVER
C    100 HORRS = (X(81)**2)*((SQRT(ALT))+SQRT(ZR))**2
      IF (IFLAG.EQ.1) GO TO 200
      CPRS = (XR-XRC)**2+(YR-YRC)**2+(ZRN-Z1)**2
      CPXS = (XX-XXC)**2+(YX-YXC)**2+(ZXN-Z1)**2

C    IF CPA TO RCVR OR TRANS BEYOND RESPECTIVE RADAR HORIZON NO DET
C    IF (CPRS.GE.HORRS.OR.CPXS.GE.HORXS) GO TO 220
      VD = DBLE(SQRT((X1-XO)**2+(Y1-YO)**2))
      VY = V*(XO-Y1)/VD
      VA = VX**2+VY**2
      A2 = A**2
      B = -2*(VX*(XRC-X1))+VY*(YRC-Y1)
      C = CPXS+(XRC-X1)**2+(YRC-Y1)**2
      D = -2*(VX*(XXC-X1))+VY*(YXC-Y1)
      E = CPXS+(XXC-X1)**2+(YXC-Y1)**2

C    DETERMINE TIME TARGET ABOVE BI-STATIC RADAR HORIZON(T10,T20)

```

```

D    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I
B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B    B
I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I    I
1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1    1
960  970  980  990  1000  1010  1020  1030  1040  1050  1060  1070  1080  1090  1100  1110  1120  1130  1140  1150  1160  1170  1180  1190  1200

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```

1440 A1 = 2*A
1450 CC = C-HOPRS
1460 CRRAD = DSQRT(B**2-4*A*CC)
1470 TR1 = ((-B+RRAD)/A)
1480 TR2 = ((-B-RRAD)/A)
1490 EE = E-HORXS
1500 XRAD = DSQRT(D**2-4*A*EE)
1510 TX1 = ((-D+XRAD)/A)
1520
1530
1540
1550
1560
1570
1580
1590
1600
1610
1620
1630
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1690
1700
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1730
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1800
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1890
1900
1910

```

C C T10 IS TIME FIRST ABOVE BI-STATIC RADAR HORIZON, T20 TIME DOWN
C C
C C T10 = AMAXI(TR1, TX1)
C C T20 = AMINI(TR2, TX2)
C C T10 = T10+TIMC
C C T20 = T20+TIMC
C C
C C DETERMINE IF TRANS/RCVR RADAR HORIZONS OVERLAP ALONG TRACK AND
C C AFTER START OF GAME AND BEFORE END OF GAME
C C
C C IF (T10.GE. T20.OR. T20.LE.0.0.OR. T10.GE.X(82)) GO TO 220
C C XCOF(5) = 0.1D01
C C XCOF(4) = (B+D)/A
C C XCOF(3) = ((C+E)/A)+(B*D/A2)
C C XCOF(2) = ((B+E)+(C*D))/A2
C C XCOF(1) = (C*E-CHAR)/A2
110 CALL DTIMD (XCOF, COF, 4, TIME, TIMEI, IER)
C C IF (IER.NE.0) GO TO 220
C C
C C CHECK FOR REAL ROOTS, IE, TIMEI=0 IF ROOT IS REAL
C C
C C IF (TIMEI(1).NE.0.0D0.AND.TIMEI(2).NE.0.0D0.AND.TIMEI(3).NE.0.0D0.
1 AND.TIMEI(4).NE.0.0D0) GO TO 220
KRR = 1
C C
C C DO 120 NNN=1,4
C C IF (TIMEI(NNN).NE.0.0D0) GO TO 120
C C T(KRR) = TIME(NNN)+TIMC
C C KRR = KRR+1
120 CONTINUE
C C
C C CHECK FOR TWO OVALS OF CASSINI; IF TWO COMPUTE 2ND DET FIRST
C C
C C IF (KRR.EQ.5) GO TO 160
C C T1 = T(1)
C C T2 = T(2)
C C GO TO 140
130 T1 = T(1)

ID 2880
 BID 2890
 BID 2900
 BID 2910
 BID 2920
 BID 2930
 BID 2940
 BID 2950
 BID 2960
 BID 2970
 BID 2980
 BID 2990
 BID 3000
 BID 3010
 BID 3020
 BID 3030
 BID 3040
 BID 3050
 BID 3060
 BID 3070
 BID 3080
 BID 3090
 BID 3100
 BID 3110
 BID 3120
 BID 3130
 BID 3140
 BID 3150
 BID 3160
 BID 3170
 BID 3180
 BID 3190
 BID 3200
 BID 3210
 BID 3220
 BID 3230
 BID 3240
 BID 3250
 BID 3260
 BID 3270
 BID 3280
 BID 3290
 BID 3300
 BID 3310
 BID 3320
 BID 3330
 BID 3340
 BID 3350

```

CC
RJHS = (RAID(L,10)+RRH)**2
RRJS = (XR-XJ)**2+(YR-YJ)**2
IF (RRJS.GT.RJHS) GO TO 390

    DETERMINE COORDINATES OF JAMMER TARGET

    JS = IFIX(X(2206+(L-1)*6)+AMF)
    IF (JS.EQ.0) GO TO 390
    IF (JS.GT.40) GO TO 270
    XJT = SHIP(JS,2)
    YJT = SHIP(JS,3)
    GO TO 280
270 XJT = 0.0
    YJT = 0.0
280 YJR = YR-YJ
    XJR = XR-XJ
    IF (YJR.NE.0.0.OR.XJR.NE.0.0) GO TO 290
    CALL LOCTIM (L,0.0,1,XJJ,YJJ)
    YJR = YR-YJJ
    XJR = XR-XJJ

    GET BEARING FROM JAMMER TO RADAR AND FROM RADAR TO JAMMER

290 JRBRG = ATAN2(YJR,XJR)
    IF (JRBRG.LT.0.0) JRBRG=JRBRG+6.2831853
    RJBRG = JRBRG-3.1415926
    IF (RJBRG.LT.0.0) RJBRG=RJBRG+6.2831853

    FIND BEARING FROM JAMMER TO JAMMER'S TARGET

    YJJT = YJT-YJ
    XJJT = XJT-XJ
    IF (YJJT.NE.0.0.OR.XJJT.NE.0.0) GO TO 300
    CALL LOCTIM (L,0.0,1,XJJ,YJJ)
    YJJT = YJT-YJJ
    XJJT = XJT-XJJ
300 JJTBR = ATAN2(YJJT,XJJT)
    IF (JJTBR.LT.0.0) JJTBR=JJTBR+6.2831853

    GET JAMMER SIDE-LOBE COEFFICIENT AND HALF-BEAM WIDTH

    HJBW = X(IIR+16)
    COFF = X(IIR+17)
    LJBW = JJTBR+HJBW
    RJBW = JJTBR-HJBW

    DETERMINE IF RADAR IS IN MAIN BEAM OF JAMMER

CC
  
```



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3360 ID
3370 ID
3380 ID
3390 ID
3400 ID
3410 ID
3420 ID
3430 ID
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3460 ID
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3480 ID
3490 ID
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3760 ID
3770 ID
3780 ID
3790 ID
3800 ID
3810 ID
3820 ID
3830 ID

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IF (LJBW.GT.6.2831853) GO TO 310
IF (RJBW.LT.0.0) GO TO 320
IF (LJBW.GT.JRBRG.AND.RJBW.LT.JRBRG) COFF=1.0
GO TO 340
LJBW = LJBW-6.2831853
GO TO 330
RJBW = RJBW+6.2831853
330 IF (LJBW.GT.JRBRG.OR.RJBW.LT.JRBRG) COFF=1.0

C C C
DETERMINE IF JAMMER IS IN MAIN BEAM OF RADAR

340 LTBRG = TBRG+HRBW
RTBRG = TBRG-HRBW
IF (LTBRG.GT.6.2831853) GO TO 350
IF (RTBRG.LT.0.0) GO TO 360
IF (LTBRG.GT.RJBRG.AND.RTBRG.LT.RJBRG) RCOFF=1.0
GU TO 380
LTBRG = LTBRG-6.2831853
GO TO 370
RTBRG = RTBRG+6.2831853
360 IF (LTBRG.GT.RJBRG.OR.RTBRG.LT.RJBRG) RCOFF=1.0
370 XCOFF = DBLE(COFF*RCOFF)
380 KRJS = (RRJS+(RAID(L,9)/6000.))*2
SUMJP = SUMJP+XCOFF*DBLE(PJ/RRJS)
390 CONTINUE

C
IF (SUMJP.LE.0.0D0) GO TO 400
CHAR = DBLE(X(903+LLJ)**2)*SIGMA/SUMJP
JFLAG = 1
IF (IFLAG.EQ.1) GO TO 210
GO TO 110
IF (ND.EQ.1) GO TO 410
R2 = DSQRT((X1+VX*(TD2-TIMC)-XR)**2+(Y1+VY*(TD2-TIMC)-YR)**2+(Z1-ZR
1R2)**2)
IF (R2.GT.X(905+LLJ)) GO TO 420
RR = DSQRT((X1+VX*(TD-TIMC)-XR)**2+(Y1+VY*(TD-TIMC)-YR)**2+(Z1-ZR
1R)**2)
IF (RR.GT.X(905+LLJ)) GO TO 460
GO TO 510
R2 = X(905+LLJ)
IF (IBM.EQ.0) GO TO 430
ILL = IFIX(ASMT(NASM,4)+AMF)
ILL = NASM+90
CALL TMDASM (IR,IL,NSR,N,VEL,R2,TIMC,TD2,XI,YI,RIP,TLL,ILL)
GO TO 440
CALL TMDASM (IR,0,NSR,N,VEL,R2,TIMC,TD2,XI,YI,RIP,TLL,IR)
440 IF (TD2.LT.TL2) GO TO 450
ND = 1


```

C C C IF (XCOF(N+1)) 20,50,20
C C C IF (N) 30,30,70
C C C SET ERROR CODE TO 1
C C C IER = 1
C C C RETURN
C C C SET ERROR CODE TO 4
C C C IER = 4
C C C GO TO 40
C C C SET ERROR CODE TO 2
C C C IER = 2
C C C GO TO 40
C C C IF (N-36) 80,80,60
C C C NX = N
C C C NXX = N+1
C C C N2 = 1
C C C KJ1 = N+1
C C C DO 90 L=1,KJ1
C C C MT = KJ1-L+1
C C C COF(MT) = XCOF(L)
C C C SET INITIAL VALUES
C C C X0 = .00500101
C C C Y0 = 0.01000101
C C C ZERO INITIAL VALUE COUNTER
C C C IN = 0
C C C X = X0
C C C INCREMENT INITIAL VALUES AND COUNTER
C C C X0 = -10.0*X0
C C C Y0 = -10.0*Y0
C C C SET X AND Y TO CURRENT VALUE
C C C X = X0
C C C Y = Y0
C C C IN = IN+1

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DTM 180
DTM 190
DTM 210
DTM 220
DTM 230
DTM 240
DTM 250
DTM 260
DTM 270
DTM 280
DTM 290
DTM 300
DTM 310
DTM 320
DTM 330
DTM 340
DTM 350
DTM 360
DTM 370
DTM 380
DTM 390
DTM 400
DTM 410
DTM 420
DTM 430
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DTM 630
DTM 640
DTM 650

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DTM 660
 DTM 670
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 DTM 1040
 DTM 1050
 DTM 1060
 DTM 1070
 DTM 1080
 DTM 1090
 DTM 1100
 DTM 1110
 DTM 1120
 DTM 1130

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120 GO TO 130
    IFIT = 1
    XPR = X
    YPR = Y
C
C EVALUATE POLYNOMIAL AND DERIVATIVES
130 ICT = 0
140 UX = 0.0
    UY = 0.0
    V = 0.0
    YT = 0.0
    XT = 1.0
    U = COF(N+1)
    IF (U) 150,280,150
C
150 DO 160 I=1,N
    L = N-I+1
    XT2 = X*XT-Y*YT
    YT2 = X*YT+Y*XI
    U = U+COF(L)*XT2
    V = V+COF(L)*YT2
    FI = I
    UX = UX+FI*XT*COF(L)
    UY = UY-FI*YT*COF(L)
    XT = XT2
    YT = YT2
C
160 SUMSQ = UX*UX+UY*UY
    IF (SUMSQ) 170,240,170
    DX = (V*UY-U*UX)/SUMSQ
    DY = X+DX
    Y = Y+DY
    IF (DABS(DY)+DABS(DX)-1.0E-05) 220,180,180
C
C STEP ITERATION COUNTER
180 ICT = ICT+1
190 IF (ICT-500) 140,190,190
200 IF (IFIT) 220,200,220
    IF (IN-5) 110,210,210
C
C SET ERROR CODE TO 3
210 IER = 3
    GO TO 40
C

```



```

220 DO 230 L=1,NXX
    MT = KJ1-L+1
    TEMP = XCOF(MT)
    XCOF(MT) = COF(L)
    COF(L) = TEMP
C
230 ITEMP = N
    NX = NX
    NX = ITEMP
    IF (IFIT) 260,120,260
    IF (IFIT) 250,110,250
240 X = XPR
250 Y = YPR
260 IFIT = 0
    IF (DABS(Y/X)-1.0E-04) 290,270,270
270 ALPHA = X+X
    SUMSQ = X*X+Y*Y
    N = N-2
    GO TO 300
280 X = 0.0
    NX = NX-1
    NXX = NXX-1
290 Y = 0.0
    SUMSQ = 0.0
    ALPHA = X
    N = N-1
    COF(2) = COF(2)+ALPHA*COF(1)
C
300 DO 310 L=2,N
    COF(L+1) = COF(L)+ALPHA*COF(L)-SUMSQ*COF(L-1)
C
310 ROOT1(N2) = Y
    ROOTR(N2) = X
    N2 = N2+1
    IF (SUMSQ) 330,340,330
330 Y = -Y
    SUMSQ = 0.0
    GO TO 320
340 IF (N) 40,40,100
    END
C
SUBROUTINE CPA (XI,YI,XC,YO,XP,YP,XC,YP,XC,YP)
XI---BOMBER OR ASM START POSITION
YI---"
XC---BOMBER END OF GAME POSIT,
YO---ASM TARGET SHIP POSIT
XP---REFERENCE POINT, IE FIRING SHIP
C
CPA 10
CPA 20
CPA 30
CPA 40
CPA 50
CPA 60

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DIM 1140
DIM 1150
DIM 1160
DIM 1170
DIM 1180
DIM 1190
DIM 1200
DIM 1210
DIM 1220
DIM 1230
DIM 1240
DIM 1250
DIM 1260
DIM 1270
DIM 1280
DIM 1290
DIM 1300
DIM 1310
DIM 1320
DIM 1330
DIM 1340
DIM 1350
DIM 1360
DIM 1370
DIM 1380
DIM 1390
DIM 1400
DIM 1410
DIM 1420
DIM 1430
DIM 1440
DIM 1450
DIM 1460
DIM 1470
DIM 1480
DIM 1490
DIM 1500
DIM 1510
DIM 1520
DIM 1530

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SUBROUTINE REACT (ICL,ITP,DELAY)
THIS SUBROUTINE COMPUTES THE REACTION TIME DELAY FOR
DETECTION, ACQUISITION, FIRING, ETC., WHERE
ICL-----CLASS OF THE REACTION TIME DISTRIBUTION,
IE. WDE, FIRE, DETECT, ETC.
ITP-----TYPE OF DISTRIBUTION, UP TO FIVE PER CLASS
DELAY-----OUTPUT
CCOMGN X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMRE
1AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NOND(190,40), ISEERE
20, MAMBAT, KOUNT, NADAR(40,19), RXATA(5), LGVER, ITEMS, PLIST(40,6), REASOR
1120
3N, CHANNEL(40,4,3,6), NASM, JAM(4), TMAX, NRTGT(90,2), NR, NS, QR
1130
4RT(50), IFLASK, IGAGE(190), ISAG(40), IFAG, ISBG, RELOAD(40,4), REA
1140
5MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), TCF(6), IHIT(4
1150
60), AMF, HISX(100), JACK(40,7), HISA(100)
REAA
CALL RANDOM(ISEED,Z,1)
REAA
X(13) = X(13)+1.
REAA
INT = Z*10
REAA
IF (INT.EQ.0) GO TO 120
REAA
IF (ITP-1) *10+INT
REAA
RANGE = X(ID+1)-X(ID)
REAA
CALL RANDOM(ISEED,Z,1)
REAA
X(13) = X(13)+1.
REAA
DELAY = X(ID)+Z*RANGE
REAA
RETURN = X(ID+1)
REAA
RANGE = X(ID+1)
REAA
CALL RANDOM(ISEED,Z,1)
REAA
X(13) = X(13)+1.
REAA
DELAY = RANGE*Z
REAA
GO TO 110
REAA
END
110
120

```

```

SUBROUTINE PRIOR (M,K,NMS,NB,RGE,NC,TIME,MM,MC,XM,YM)
THIS SUBROUTINE DETERMINES IF THERE IS A MORE THREATENING
TARGET TO BE ENGAGED AT THIS TIME BY THIS SHIP, THIS SYSTEM
AND THIS DIRECTOR. PRESENT LOGIC CONSIDERS THE CLOSEST
UNENGAGED TARGET THE MOST THREATENING.
CCOMGN X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMPRI
1AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NOND(190,40), ISEEPRI
20, MAMBAT, KOUNT, NADAR(40,19), RXATA(5), LGVER, ITEMS, PLIST(40,6), REASOPRI
3N, CHANNEL(40,4,3,6), NASM, JAM(4), TMAX, NRTGT(90,2), NR, NS, QPRI
110

```


4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELOAD(40,4),PRI
 5MARY(100),CHECK,IFIRST,NPSS,KMART(4),NSAM,TGTAV(190),TCF(6),IHI(4)
 60),AMF,HISX(100),JACK(40,7),HISA(100)

110 IQ = X(EQ.0) GO TO 110
 IF (IQ.EQ.0) GO TO 110
 CALL GETIMX (MV) -5
 DELTAX = MV*2.6E-5
 WRI (M.GT.90) GO TO 120
 IF (M.GT.90) GO TO 120
 CALL LOC TIM (M,TIME,3,XP,YP)
 GO TO 130
 CALL ASMTIM (M,TIME,XP,YP)
 DELTAX = ABS(SHIP(K,2)-XP)
 DELTAY = ABS(SHIP(K,3)-YP)
 120 DEF (DELTAX.LI.5.0E-5) DELTAX=5.0E-5
 130 DEF (DELTAY.LI.5.0E-5) DELTAY=5.0E-5
 IF (DELTAY**2+DELTAX**2)
 RGI = SQRT(DELTAX**2+DELTAY**2)
 CHECK = RGE/RGI
 MM = MC
 MC = NC
 XM = XP
 YM = YP

GET ANOTHER CANDIDATE IF THERE IS ONE

140 CALL TARGET (TIME,MT,MORE)
 IF (MORE.EQ.0) GO TO 170
 IU = MT-300000000+2
 MV = IU*1.00-5
 KP = MV*100000
 ID = IU-KP
 KP = IU*1.0D-3 GO TO 140
 IF (KP.NE.K) GO TO 140
 KT = KP*1000
 JP = ID-KT
 MSO = JP*1.0E-2 GO TO 140
 IF (MSO.NE.NMS) GO TO 140
 KP = NMS*100
 ID = JP-KP
 NBO = ID*1.0E-1 GO TO 140
 IF (NBO.NE.NB) GO TO 140
 KP = NB*10
 NCO = ID-KP-2
 IF (MV.GT.90) GO TO 150
 CALL LOC TIM (MV,TIME,3,XP,YP)
 GO TO 160
 150 CALL ASMTIM (MV,TIME,XP,YP)


```

160 DELTAX = ABS(SHIP(K,2)-XP)
    DELTAY = ABS(SHIP(K,3)-YP)
    IF (DELTAX.LI.5.0E-5) DELTAX=5.0E-5
    IF (DELTAY.LI.5.0E-5) DELTAY=5.0E-5
    RGI = SQRT(DELTAX**2+DELTAY**2)
        COMPARE THREAT VALUES
    CHERRY = RGE/RGI
    IF (CHECK.GE.CHERRY) GO TO 140
    CHECK = CHERRY
    MM = MV
    MC = NCO
    XM = XP
    YM = YP
    IUNYT = MT
    GO TO 140
170 IF (MM.EQ.M) GO TO 180
    CALL REMOVE (IUNYT)
    IUNYT = M*10000+K*1000+NMS*100+NB*10+NC
    CALL STOREV (TIME,3,IUNYT)
    IF (X(9).EQ.0.) GO TO 190
180 NSB = K*100+NMS*10+NB
    WRITE (6,220) M,MM,NSB,NC,MC
190 IF (IQ.EQ.0) GO
    CALL GETIMX (MV)
    DELTAY = MV*2.6E-5
    WRITE
    RETURN
200 RETURN (' PRIOR IN AT',F15.8)
210 FORMAT ('0', ' PRIOR DEBUG DATA
220 122X, ' BATTERY NUMBER', I5/(22X, ' INPUT CHANNEL', I2, '
    212))
230 FORMAT (' PRIOR OUT AT',F15.8)
    END

```

CC

```

SUBROUTINE RCHECK (IT,IR,K)
IT.....TARGET NUMBER
IR.....RAIDER NUMBER
K.....FLAG FOR GO/NOGO ON TARGET ASSIGNMENT
THIS SUBROUTINE EVALUATES THE PROSPECTIVE TARGET TO
SEE IF THE RAIDER CAN IN FACT "SEE" THE TARGET.
COMMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SMRECK
IAT(300,10),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NONO(190,40),ISEE

```

CCCCC


```

2D, MAMBAT, KOUNT, NADAR(40,19), RXATA(5), LDVER, ITEMS, PLIST(40,6), REASORRECK
3N, CHANNEL(40,4,3,6), NNASM, JAM(4), TMAX, NRTGT(90), MISLFT(90,2), NR, NS, QRECK
4RT(50), IFLASK, IGAGE(190), ISAG(40), IFAG, ISBG(40), IFBG, RELQAD(40,4), RECK
5MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), TCF(6), IHIT(4 RECK
60), AMF, HISX(100), JACK(40,7), HISA(100) RECK
      IC = X(55) RECK
      IF (IQ.EQ.0) GO TO 20 RECK
      CALL GETIMX (IET) RECK
      TM = .000026*IET RECK
      WRITE (6,70) TM RECK
      GET THE DISTANCE FROM THE RED RAIDER TO THE BLUE SHIP RECK
20 XS = RAID(IR,3) RECK
      YS = RAID(IR,4) RECK
      XT = SHIP(IT,2) RECK
      YT = SHIP(IT,3) RECK
      DELX = ABS(XS-XT) RECK
      IF (DELY.LT.00005) DELX=.00005 RECK
      DELY = ABS(YS-YT) RECK
      IF (DELY.LT.00005) DELY=.00005 RECK
      DIS = DELX**2+DELY**2 RECK
      DID = IFIX(X(1201)+(IT-1)*4)+AMF) RECK
      IC = IC+6 RECK
      IB = IC+6 RECK
      IF IB = 15. RECK
      SET THE TARGET SHIP HEIGHT TO A NOMINAL VALUE OF 15 FEET AND THEN PROCEED TO DETERMINE THE HEIGHT OF HIS HIGHEST RADAR, IF HE HAS ONE. RECK
      DO 30 M=IC, IB RECK
      IF (HT.LT.X(M)) HT = X(M) RECK
30 CONTINUE RECK
      DETERMINE THE MUTUAL RADAR HORIZON BETWEEN THE ATTACKER AND THE TARGET. GET THE MAX RANGE FOR THE ATTACKER'S RADAR. IF THE COMBINED RADAR HORIZONS ARE LESS THAN THE ACTUAL DISTANCE, OR THE ACTUAL DISTANCE IS GREATER THAN THE RADAR'S CAPABILITY, SET THE FLAG TO NO GO AND EXIT. OTHERWISE SET THE FLAG TO OK AND EXIT. RECK
      HTR = X(81)*SQRT(HT) RECK
      RTR = RAID(IR,10) RECK
      RADAR = RTR+HTR RECK
      RADAR2 = RADAR**2 RECK
      IF (RADAR2.LT.DIS) GO TO 40 RECK
      IC = IFIX(X(2201)+(IR-1)*6)+AMF) RECK

```



```

RECK 600
RECK 610
RECK 620
RECK 630
RECK 640
RECK 650
RECK 660
RECK 670
RECK 680
RECK 690
RECK 700
RECK 710
RECK 720
RECK 730
RECK 740
RECK 750

```

```

IB = IFIX(X(1807+(IC-1)*20)+AMF)
RR = X(905+(IB-1)*20)
RR2 = RR**2
IF (DIS.GT.RR2) GO TO 40
GO TO 50
K = 1
40 IF (IQ.EQ.0) GO TO 60
50 CALL GETIMX (IET)
TM = .000026*IET
WRITE (6,80) TM
RETURN
60
70 FORMAT (1) RCHECK IN AT',F15.8)
80 FORMAT (1) RCHECK OUT AT',F15.8)
END

```

C

```

SUBROUTINE TMDASM (IRAID,ITS,ISAMBT,NFS,VEL,SRG,TML,TIME,XI,YI,RI,
1,TIML,M)

```

THIS SUBROUTINE COMPUTES THE TIME OF ENTERING AND LEAVING A GIVEN ENGAGEMENT CIRCLE

```

IRAID-----RAID LAUNCHING THE ASM
ITS-----TARGET SHIP
ISAMBT-----SAM BATTERY NUMBER
NFS-----NUMBER OF THE SAM FIRING SHIP
VEL-----ASM VELOCITY (SPEED IN NM/MIN)
SRG-----MAXIMUM SAM RANGE FOR THIS ALTITUDE AND TYPE
TML-----TIME OF ASM LAUNCH
TIME----- (OUTPUT) MAX RANGE SAM INTERCEPT
XI----- (OUTPUT) X POSIT MAX INTERCEPT RANGE
YI----- (OUTPUT) Y POSIT MAX INTERCEPT RANGE
RIP----- (OUTPUT) DISTANCE TO INTERCEPT OR
DETECTION
TIML----- (OUTPUT) TIME OF OUT OF RANGE
M-----AIRBORNE TARGET NUMBER
COMMON X(2744),ASMT(100,8),SAMASMT(300,7),RAID(90,17),SHIP(40,6),SMITMD
1AT(300,10),IVEN,NADAR(40,2),STATS(40,2),IBAT(40,4),NOND(190,40),ISEETMD
2D,MAMBAL(40,4),3,6),NASM,JAN(4),TMAX,NR,TGT(90),MISLFT(90,2),NR,NS,QTMD
4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG,RELOAD(40,4),ITMD
5MARY(100),CHECK,IFIRST,NPGS,KMART(100)
60),AMF,HISX(100),JACK(40,7),HISA(100)
IQ = X(55)

```

CCCCCCCCCCCCCCCCCCCC

TMD 310
TMD 320
TMD 330
TMD 340
TMD 350
TMD 360
TMD 370
TMD 380
TMD 390
TMD 400
TMD 410
TMD 420
TMD 430
TMD 440
TMD 450
TMD 460
TMD 470
TMD 480
TMD 490
TMD 500
TMD 510
TMD 520
TMD 530
TMD 540
TMD 550
TMD 560
TMD 570
TMD 580
TMD 590
TMD 600
TMD 610
TMD 620
TMD 630
TMD 640
TMD 650
TMD 660
TMD 670
TMD 680
TMD 690
TMD 700
TMD 710
TMD 720
TMD 730
TMD 740
TMD 750
TMD 760
TMD 770
TMD 780

```

IF (VEL.EQ.0.) VEL = .0001
IF (IQ.EQ.0.) GO TO 20
CALL GETIMX (IET)
TIMES = IET*.000026
WRITE (6,270) TIMES
20 KFLAG = 0
IF KFLAG = 0
CC
CC
      DETERMINE THE PRESENT RANGE
DEX = ABS(SHIP(NFS,2))-RAID(IRAIID,3)
DEY = SHIP(NFS,3)-RAID(IRAIID,4)
IF (ABS(DEY).LT.0.00005) DEY=.00005
IF (DEX.LT.*2+DEY**2
DIP = DEY**2+DEY**2
DIP = SQRT(DIP)
IF (RIP.GT.SRG) GO TO 30
XI = RAID(IRAIID,3)
YI = RAID(IRAIID,4)
TIME = TML
IFLAG = 1
IF (VEL.LT..005) GO TO 260
GO TO 40
30 IF (VEL.LT..005) GO TO 200
CC
CC
      SOLVE THE LINEAR EQUATION FOR THE TARGET
DELTAX = RAID(IRAIID,14)-RAID(IRAIID,3)
DELTAY = RAID(IRAIID,15)-RAID(IRAIID,4)
IF (ABS(DELTAX).LT.5.0E-2) GO TO 50
SLM = DELTAY/DELTAX
GO TO 60
50 B = -2*SHIP(NFS,3)
C = (RAID(IRAIID,3))-SHIP(NFS,2)**2+SHIP(NFS,3)**2-SRG**2
IF (TEST.LE.0.) GO TO 200
TOAST = SQRT(TEST)
X1 = XI
X2 = XI
Y1 = (-B+TOAST)/2.
Y2 = (-B-TOAST)/2.
KFLAG = 1
GO TO 80
60 XI = RAID(IRAIID,15)-SLM*RAID(IRAIID,14)
X2 = RAID(NFS,2)
Y1 = SHIP(NFS,3)
Y2 = SHIP(NFS,3)
C
```


C C SOLVE THE JOINT QUADRATIC EQUATION

```

A = SLM**2+1.(BI-YS)-XS)
B = 2.*(SLM*(BI-YS)**2-SRG**2)
C = XS**2+2-4.*A*C
TEST (TEST) 200,200,70
IF ROOT = SQRT(TEST)
70  X1 = (-B+ROOT)/(2.*A)
    X2 = (-B-ROOT)/(2.*A)
    Y1 = SLM*X1+B1
    Y2 = SLM*X2+B1
80  DELX = ABS(X1-RAID(IRCID,3))
    DELY = ABS(Y1-RAID(IRCID,4))
    IF (DELY.LT.00005) DELX=.00005
    IF (DELX.LT.00005) DELY=.00005
    D1 = SQRT(DELY**2+DELX**2)
    IF (DELX = ABS(X2-RAID(IRCID,3)))
    DELX = ABS(Y2-RAID(IRCID,4))
    DELY = ABS(X1-RAID(IRCID,3))
    IF (DELY.LT.00005) DELX=.00005
    IF (DELX.LT.00005) DELY=.00005
    D2 = SQRT(DELY**2+DELX**2)
    IF (IFLAG.EQ.1) GO TO 120
    IF (KFLAG.EQ.1) GO TO 160
    DIF = ABS(DELTA)
    IF (D2.LT.D1) GO TO 100
    DIF = ABS(DELTA)
90  IF (DIF.LT.DIC) GO TO 200

```

C C DETERMINE THE INTERSECTION TIMES

```

XI = X1
YI = Y1
TIME = TML+D1/VEL
TIML = TML+D2/VEL
GO TO 220
100 DIF = ABS(RAID(IRCID,14)-X2)
    IF (DIF.LT.DIC) GO TO 200
110 XI = X2
    YI = Y2
    TIME = TML+D2/VEL
    TIML = TML+D1/VEL
    GO TO 220
120 IF (KELTAG.EQ.1) GO TO 180
    IF (DELTA.LT.0.) GO TO 150
    IF (X1.LT.X2) GO TO 140
130 TIME = TML+D1/VEL
    GO TO 220

```

TMD 790
TMD 800
TMD 810
TMD 820
TMD 830
TMD 840
TMD 850
TMD 860
TMD 870
TMD 880
TMD 890
TMD 900
TMD 910
TMD 920
TMD 930
TMD 940
TMD 950
TMD 960
TMD 970
TMD 980
TMD 990
TMD 1000
TMD 1010
TMD 1020
TMD 1030
TMD 1040
TMD 1050
TMD 1060
TMD 1070
TMD 1080
TMD 1090
TMD 1100
TMD 1110
TMD 1120
TMD 1130
TMD 1140
TMD 1150
TMD 1160
TMD 1170
TMD 1180
TMD 1190
TMD 1200
TMD 1210
TMD 1220
TMD 1230
TMD 1240
TMD 1250
TMD 1260


```

140 TIML = TML+D2/VEL
150 GO TO 220
160 IF (X1.LT.X2) GO TO 130
170 DIF = ABS (DELTA Y)
180 IF (D2.LT.D1) GO TO 170
190 DIC = ABS (RAID (IRAID,15)-Y1)
200 DIC TO 90
210 DIC = ABS (RAID (IRAID,15)-Y2)
220 GO TO 110
230 IF (DELTA Y.LT.0.) GO TO 190
240 IF (Y1.LT.Y2) GO TO 140
250 IF (Y1.LT.Y2) GO TO 130
260 GO TO 140
270 TIME = 9120.
280 XI = 9999.
290 YI = 9999.
300 RIP = 0.
310 IF (X(57).EQ.0.) GO TO 240
320 IF (ITS.EQ.0) GO TO 210
330 WRITE (6,280) IRAID,ITS,ISAMBT,NFS,M
340 GO TO 240
350 WRITE (6,310) M,NFS
360 GO TO 240
370 IF (X(57).EQ.0.) GO TO 240
380 IF (ITS.EQ.0) GO TO 230
390 WRITE (6,290) M,NFS,ITS,SRG,TIME,TIML
400 GO TO 240
410 WRITE (6,320) M,NFS,ISAMBT,SRG,TIME,TIML
420 IF (IQ.EQ.0) GO TO 250
430 CALL GETIMX (IET)
440 TIMES = .000026*IET
450 WRITE (6,300) TIMES
460 RETURN
470 TIML = X(82)
480 GO TO 220
490 FORMAT (' NO ENGAGEMENT POSSIBLE, RAID ',F15.8)
500 1 BATTERY ',I2,' MISSILE SHIP',I3,' ASM',I3)
510 1 FORMAT ('0',, ENGAGEMENT DATA, ASM',I4,' AND SHIP',I3,'/(', TARGET
520 2 SHIP DETEC RANGE GAIN CONTACT LOOSE CONTACT',I6,9X,F10.3,6X
530 2,F7.3,9X,F7.3))
540 300 FORMAT ('0',, TMDASM OUT AT ',F15.8)
550 310 FORMAT ('0',, NO ENGAGEMENT POSSIBLE BETWEEN BOMBER',I3,' AND SHIP',I3)
560 320 FORMAT ('0',, ENGAGEMENT DATA, BOMBER',I3,' AND SHIP',I3,'/(',BATTIM

```

```

TMD 1270
TMD 1280
TMD 1290
TMD 1300
TMD 1310
TMD 1320
TMD 1330
TMD 1340
TMD 1350
TMD 1360
TMD 1370
TMD 1380
TMD 1390
TMD 1400
TMD 1410
TMD 1420
TMD 1430
TMD 1440
TMD 1450
TMD 1460
TMD 1470
TMD 1480
TMD 1490
TMD 1500
TMD 1510
TMD 1520
TMD 1530
TMD 1540
TMD 1550
TMD 1560
TMD 1570
TMD 1580
TMD 1590
TMD 1600
TMD 1610
TMD 1620
TMD 1630
TMD 1640
TMD 1650
TMD 1660
TMD 1670
TMD 1680
TMD 1690
TMD 1700
TMD 1710
TMD 1720
TMD 1730
TMD 1740

```

C

10 TBM
 20 TBM
 30 TBM
 40 TBM
 50 TBM
 60 TBM
 70 TBM
 80 TBM
 90 TBM
 100 TBM
 110 TBM
 120 TBM
 130 TBM
 140 TBM
 150 TBM
 160 TBM
 170 TBM
 180 TBM
 190 TBM
 200 TBM
 210 TBM
 220 TBM
 230 TBM
 240 TBM
 250 TBM
 260 TBM
 270 TBM
 280 TBM
 290 TBM
 300 TBM
 310 TBM
 320 TBM
 330 TBM
 340 TBM
 350 TBM
 360 TBM
 370 TBM
 380 TBM
 390 TBM
 400 TBM
 410 TBM
 420 TBM
 430 TBM

```

SUBROUTINE TMDBOMB ( IR,RGE,T)
  COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMETBM
  1 AT(300,10), IVENTS(1000,2), STATS(40,2), IBAT(40,4), NONO(190,40), ISEETBM
  2 D,MANBA(1,KOUNT,NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASOUTBM
  3 N,CHANEL(40,4,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFLT(90,2),NR,NS,QTBM
  4 RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELOAD(40,4),IHIT(4
  5 MARY(100),CHECK,IFIRST,NPGS,KMART(4),NSAM,TGTAV(190),TCF(6),TBM
  60),AMF,HISX(100),JACK(40,7),HISA(100)

  COMPUTES THE TIME THE RAIDER WILL REACH A GIVEN RANGE FROM
  FORCE CENTER.
  IR.....BOMBER NUMBER
  RGE.....GIVEN RANGE IN MILES
  T.....(OUTPUT) TIME OF ATTAINING THE RANGE. IF PRESENT
           GAME TIME. PUTS BOMBER INSIDE GIVEN RANGE, PRESENT
           GAME TIME IS RETURNED.

  IQ = X(55)
  IF (IQ.EQ.0) GO TO 20
  CALL GETIMX (IET)
  TM = .000026*IET
  WRITE (6,110) TM

  COMPUTE PRESENT RAIDER RANGE FROM FORCE CENTER

  20 DIP = RAID(IR,3)**2+RAID(IR,4)**2
     RIP = SQRT(DIP)
     IF (RIP.GT.RGE) GO TO 30
     T = RAID(IR,2)
     GO TO 80

  30 DELTAX = RAID(IR,5)-RAID(IR,3)
     IP = IFIX(X(2201)+(IR-1)*6)+AMF)
     VEL = X(1814+(IP-1)*20)
     DELTAY = RAID(IR,6)-RAID(IR,4)

     SOLVE THE LINEAR EQUATION FOR RAIDER TRACK AND THE
     QUADRATIC FOR INPUT RANGE SIMULTANEOUSLY

     IF (ABS(DELTAX).LT.5.0E-2) GO TO 40
     SLM = DELTAY/DELTAX
     GO TO 50
     40 IF (ABS(RAID(IR,3)).GE.RGE.OR.DELTAY*RAID(IR,4).GT.0.) GO TO 100
        IF (VEL.EQ.0.) GO TO 100

```

C
 C
 C
 C


```

T = RAID(IR,2)+(ABS(RAID(IR,4))-SQRT(RGE**2-RAID(IR,3)**2))/VEL
IF (T.GT.X(82).OR.T.LT.RAID(IR,2)) GO TO 100
GO TO 80
50 BA = RAID(IR,6)-SLM*RAID(IR,5)
A = SLM**2+1.
C = 2.*SLM*BA
TEST = B**2-4.*A*C
IF (TEST) 100,100,60
60 X1 = (-B+ROOT)/(2.*A)
X2 = (-B-ROOT)/(2.*A)
Y1 = SLM*X1+BA
Y2 = SLM*X2+BA
DELX = ABS(X1-RAID(IR,3))
IF (DELX.LT..00005) DELX=.00005
DELY = ABS(Y1-RAID(IR,4))
IF (DELY.LT..00005) DELY=.00005
D1 = DELX**2+DELY**2
DELY = ABS(X2-RAID(IR,3))
IF (DELX.LT..00005) DELX=.00005
DELY = ABS(Y2-RAID(IR,4))
IF (DELY.LT..00005) DELY=.00005
D2 = DELX**2+DELY**2
IF (VEL.EQ.0.) GO TO 100
DIF = ABS(RAID(IR,5)-RAID(IR,3))
IF (D2.LT.D1) GO TO 70
DIF = ABS(RAID(IR,5)-X1)
IF (DIF.LT.DIC) GO TO 100
C COMPUTE TIME RAIDER IS WITHIN GIVEN RANGE
C
DIX = SQRT(D1)
T = RAID(IR,2)+DIX/VEL
GO TO 80
70 DIC = ABS(RAID(IR,5)-X2)
IF (DIF.LT.DIC) GO TO 100
DIX = SQRT(D2)
T = RAID(IR,2)+DIX/VEL
80 IF (IQ.EQ.0) GO TO 90
CALL GETIMX (IET)
TM = IET*.000026
WRITE (6,120) TM
90 RETURN
100 T = 9120.
GO TO 80
C 110 FORMAT (' TMDBOM IN AT',F15.8)

```

```

TBM 440
TBM 450
TBM 460
TBM 470
TBM 480
TBM 490
TBM 500
TBM 510
TBM 520
TBM 530
TBM 540
TBM 550
TBM 560
TBM 570
TBM 580
TBM 590
TBM 600
TBM 610
TBM 620
TBM 630
TBM 640
TBM 650
TBM 660
TBM 670
TBM 680
TBM 690
TBM 700
TBM 710
TBM 720
TBM 730
TBM 740
TBM 750
TBM 760
TBM 770
TBM 780
TBM 790
TBM 800
TBM 810
TBM 820
TBM 830
TBM 840
TBM 850
TBM 860
TBM 870
TBM 880
TBM 890
TBM 900
TBM 910

```


120 FORMAT (' TMD80M OUT AT',F15.8)
 END

SUBROUTINE ZLNKA (A,KEY,N)

THIS SUBROUTINE CAN BE FOUND IN THE NPGS SUBROUTINE
 LIBRARY UNDER THE NAME SHSORT

THE SUBROUTINE REORDERS THE INPJT ARRAY "A" FROM SMALLEST
 TO LARGEST, AND SIMULTANEOUSLY REORDERS THE INTEGER
 ARRAY "KEY" TO THE SAME ORDER AS "A".

DIMENSION A(N), KEY(N)

M1 = 1
 M1 = M1*2
 20 IF (M1.LE.N) GO TO 20
 M1 = M1/2 - 1
 MM = MAX0(M1/2,1)
 GO TO 40
 30 MM = MM/2
 IF (MM.LE.0) GO TO 70
 40 K = N-MM

DO 60 J=1,K
 II = J+MM
 IM = J+MM
 IF (A(IM).GE.A(II)) GO TO 60
 50 TEMP = A(II)
 A(II) = A(IM)
 A(IM) = TEMP
 KEY(IM) = KEY(II)
 KEY(II) = IM
 IF (II.GT.0) GO TO 50
 60 CONTINUE

GO TO 30
 RETURN
 END

SUBROUTINE TJSORT (A,N)

ID: M1-NPG-SHSORT (F-IV)

A - ARRAY OF NUMBERS TO BE SORTED. THIS ARRAY IS SORTED

TBM 920
 TBM 930

ZLKA 10
 ZLKA 20
 ZLKA 30
 ZLKA 40
 ZLKA 50
 ZLKA 60
 ZLKA 70
 ZLKA 80
 ZLKA 90
 ZLKA 100
 ZLKA 110
 ZLKA 120
 ZLKA 130
 ZLKA 140
 ZLKA 150
 ZLKA 160
 ZLKA 170
 ZLKA 180
 ZLKA 190
 ZLKA 200
 ZLKA 210
 ZLKA 220
 ZLKA 230
 ZLKA 240
 ZLKA 250
 ZLKA 260
 ZLKA 270
 ZLKA 280
 ZLKA 290
 ZLKA 300
 ZLKA 310
 ZLKA 320
 ZLKA 330
 ZLKA 340
 ZLKA 350
 ZLKA 360
 ZLKA 370

TJS 10
 TJS 20
 TJS 30
 TJS 40
 TJS 50

(RE-ORDERED) BY A SHELL SORT.
NUMBER OF MEMBERS IN ARRAY "A".

```

C C C
N -
DIMENSION A(N)
20 M1 = M1*2
   IF (M1.LE.N) GO TO 20
   M1 = M1/2-1
   MM = MAXO(M1/2,1)
   GO TO 40
30 MM = MM/2
   IF (MM.LE.0) GO TO 70
40 K = N-MM
   DO 60 J=1,K
   I = J+MM
   IF (A(I).GE.A(I+1)) GO TO 60
   TEMP = A(I)
   A(I+1) = A(I)
   A(I) = TEMP
   I = I-MM
   IF (I.GT.0) GO TO 50
60 CONTINUE
   GO TO 30
70 RETURN
   END
C

```

SUBROUTINE LOCTIM (K,T,IND,XP,YP)

THIS SUBROUTINE COMPUTES THE PRESENT, FUTURE OR PAST BOMBER POSITION. THE INPUTS ARE:

- K-----BOMBER NUMBER
- T-----THE TIME OF INTEREST
- IND-----AN INDICATOR: DO YOU WANT THIS INFORMATION STORED IN THE RAID ARRAY?
- XP-----{OUTPUT} POSITION AT TIME T.
- YP-----{OUTPUT} POSITION AT TIME T.

```

COMMON X(2744), ASMT(100,8), SAMASM(300,7), RAID(90,17), SHIP(40,6), SMLCC
1AT(300,10), IVENTS(100,2), STATS(40,2), IBAR(40,4), NCOND(190,40), ISEELCC
2D,MAMBAT,KOUNT,NADAR(40,19), RXATA(5), LOVER, ITEMS, PLIST(40,6), REASOLCC
3N, CHANEL(40,4,3,6), NASM, JAM(4), TMAX, NRTGT(90), MISLFT(90,2), NK, NS, QLCC
4RT(50), IFLASK, IGAGE(190), ISAG(40), IFAG, ISBG(40), IEBG, WELLOAD(40,4), LCC
5MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), TCF(6), THIT(4), LCC
60), AMF, HISX(100), JACK(40,7), HISA(100)
C C C C C C C C C C

```



```

190 IQ = X(EQ, 0) GO TO 20
200 IF (IQ.EQ.0) (IET)
210 CALL GETIMX (IET)
220 TIMES = IET*.000026
230 WRITE (6, 70) TIMES
240 IF X(1) = 1 THEN WRITE (K, 1) + AMF
250 IF (ID + 1) = 1 THEN WRITE (K, 2)
260 PTIME = (T - PTIME) * VEL
270 DL = RAID(K, 4)
280 YZ = RAID(K, 3)
290 XZ = RAID(K, 3)
300 DELTAX = XZ - RAID(K, 5)
310 IF (ABS(DELTAX)) .LT. .00005 DELTAX = 0.0
320 DELTAY = YZ - RAID(K, 6)
330 IF (ABS(DELTAY)) .LT. .00005 DELTAY = 0.0
340 D = SQRT(DELTAX**2 + DELTAY**2)
350 IF (D.EQ.0.) GO TO 60
360 DT = DL/D
370 XP = XZ - DELTAX*DT
380 YP = YZ - DELTAY*DT
390 IF (IND.NE.5) GO TO 40
400 RAID(K, 4) = YP
410 RAID(K, 3) = XP
420 RAID(K, 2) = T
430 IF (IQ.EQ.0) GO TO 50
440 CALL GETIMX (IET)
450 TIMES = IET*.000026
460 WRITE (6, 80) TIMES
470 RETURN
480 XP = XZ
490 YP = YZ
500 GO TO 30
510
520
530
540
550

```

```

C 70 FORMAT (' LOCTIM IN AT', F15.8)
80 FORMAT (' LOCTIM OUT AT', F15.8)
END

```

```

SUBROUTINE ASMTIM (M, T, XP, YP)
COMMON X(2744), ASMT(100, 8), SAMASM(300, 7), RAID(90, 17), SHIP(40, 6), SMASM
1AT(300, 10), IVENTS(1000, 2), STATS(40, 2), IBAT(40, 4), NONO(190, 4), ISEAS
2D, MAMBA, T, KOUNT, NADAR(40, 19), RXATA(5), LQVER, ITEMS, PLIST(40, 6), REAS
3N, CHANEL(40, 4, 3, 6), NASM, JAM(4), TMAX, NRTGT(90, 2), NR, NS, QASM
4RT(50), IFLASK, IGAGE(190), ISAG(40, 1), IFAG, ISBG(40), IFBG, RELQAD(40, 4),
5MARY(100), CHECK, IFIRST, NPGS, KMART(4), NSAM, TGTAV(190), ICF(6), IHT(4),
60), AMF, HISX(100), JACK(40, 7), HISA(100)
C
C
C

```


HISTG0120
 HISTG0130
 HISTG0140
 HISTG0150
 HISTG0160
 HISTG0170
 HISTG0180
 HISTG0190
 HISTG0200
 HISTG0210
 HISTG0220
 HISTG0230
 HISTG0240
 HISTG0250
 HISTG0260
 HISTG0270
 HISTG0280
 HISTG0290
 HISTG0300
 HISTG0310
 HISTG0320
 HISTG0330
 HISTG0340
 HISTG0350
 HISTG0360
 HISTG0370
 HISTG0380
 HISTG0390
 HISTG0400
 HISTG0410
 HISTG0420
 HISTG0430
 HISTG0440
 HISTG0450
 HISTG0460
 HISTG0470
 HISTG0480
 HISTG0490
 HISTG0500
 HISTG0510
 HISTG0520
 HISTG0530
 HISTG0540
 HISTG0550
 HISTG0560
 HISTG0570
 HISTG0580
 HISTG0590

CALLING SEQUENCES

- CALL HISTG(X, N, NBAR)
- CALL HISTF(X, N, NBAR)
- CALL NOSTAT
- CALL FIX(SCALE)
- CALL NOFIX

ARGUMENTS

- X A SINGLE DIMENSIONAL ARRAY OF DATA (REAL*4) TO BE ANALYZED. SORTED IN ASCENDING ORDER ON OUTPUT FROM HISTF/HISTG.
- N THE NUMBER OF DATA POINTS TO BE CONSIDERED. MUST BE GREATER THAN 9.
- NBAR THE NUMBER OF BARS IN THE HISTOGRAM. MUST BE BETWEEN 15 AND 32. IF NBAR IS SUPPLIED AS ZERO, THE NUMBER OF BARS IN THE HISTOGRAM WILL BE AUTOMATICALLY DETERMINED BASED ON THE NUMBER OF DATA POINTS.
- SCALE A VECTOR (REAL*4) OF TWO VALUES USED TO OPTIONALLY FIX THE SCALE FOR THE HISTOGRAM. SCALE(1) IS THE LOWER VALUE AND SCALE(2) THE UPPER.

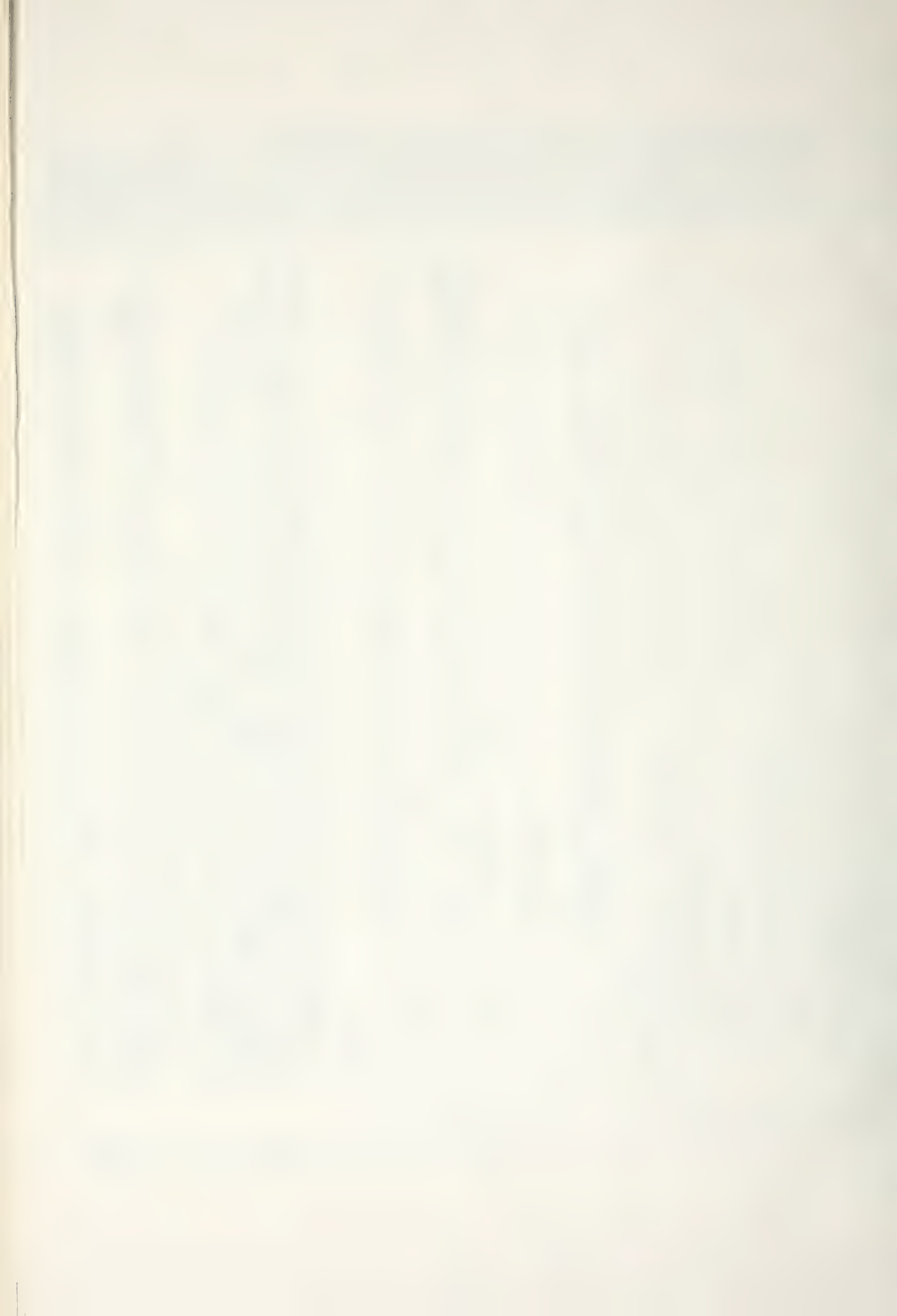
USAGE

THE CALLING SEQUENCE USING THE ENTRY POINT HISTG WILL PRODUCE A SINGLE PAGE OF OUTPUT WITH THE HISTOGRAM AND THE COMPUTED STATISTICS (BUT SEE ERROR CONDITIONS BELOW). USING THE ALTERNATE ENTRY POINT HISTF WILL PRODUCE TWO PAGES OF OUTPUT: THE FIRST WILL BE IDENTICAL TO THE PAGE FOR HISTG WHILE THE SECOND WILL SHOW THE EMPIRICAL DENSITY FUNCTION PLOTTED OVER THE BASIC HISTOGRAM. THE CALCULATION AND PRINT OUT OF STATISTICS MAY BE SUPPRESSED BY CALLING NOSTAT.

HISTG/HISTF CALLS ON SUBROUTINE PXSORT TO PERFORM AN IN-PLACE SORT OF THE INPUT DATA SO THAT IT WILL BE IN INCREASING ORDER UPON RETURN FROM THE SUBROUTINE. THE VALUES OF THE DATA POINTS ARE UNCHANGED.

THE HISTOGRAM SCALE MAY BE FIXED BY CALLING THE ALTERNATE ENTRY POINT FIX; THE SCALE REMAINS SET AT THESE LIMITS UNLESS

CC



HSTG0600
 HSTG0610
 HSTG0620
 HSTG0630
 HSTG0640
 HSTG0650
 HSTG0660
 HSTG0670
 HSTG0680
 HSTG0690
 HSTG0700
 HSTG0710
 HSTG0720
 HSTG0730
 HSTG0740
 HSTG0750
 HSTG0760
 HSTG0770
 HSTG0780
 HSTG0790
 HSTG0800
 HSTG0810
 HSTG0820
 HSTG0830
 HSTG0840
 HSTG0850
 HSTG0860
 HSTG0870
 HSTG0880
 HSTG0890
 HSTG0900
 HSTG0910
 HSTG0920
 HSTG0930
 HSTG0940
 HSTG0950
 HSTG0960
 HSTG0970
 HSTG0980
 HSTG0990
 HSTG1000
 HSTG1010
 HSTG1020
 HSTG1030
 HSTG1040
 HSTG1050
 HSTG1060
 HSTG1070

IT IS RESET BY ANOTHER CALL TO FIX OR ALLOWED TO FLOAT (THE DEFAULT) BY CALLING NOFIX. WHEN THE SCALE IS FIXED, POINTS FALLING OUTSIDE THE INTERVAL ARE DISPLAYED IN THE END BARS OF THE HISTOGRAM.

THE FOLLOWING BASIC STATISTICS ARE ALSO COMPUTED AND PRINTED OUT, IF NOSTAT IS NOT CALLED:

- MEAN, MEDIAN, TRIMEAN, MIDMEAN
- GEOMETRIC AND HARMONIC MEANS (POSITIVE SAMPLES ONLY)
- VARIANCE, STANDARD DEVIATION, COEFFICIENT OF VARIATION, RANGE AND MIDSPREAD
- THIRD AND FOURTH CENTRAL MOMENTS, COEFFICIENTS OF SKEWNESS AND KURTOSIS
- MAXIMUM, MINIMUM AND 5 QUANTILES

IN ADDITION, THE MEAN IS DISPLAYED ON THE HISTOGRAM BY A VERTICAL COLUMN OF "M"'S AND THE QUANTILES BY COLUMNS OF DOTS.

INTERPRETING THE OUTPUT

THE DEFINITIONS OF THE BASIC STATISTICS COMPUTED BY HISTG/HISIF ARE LISTED BELOW. PAGE NUMBER REFERENCES ARE TO THE CRC STANDARD MATH TABLES, 19TH EDITION (1971).

- MEAN AVERAGE OF THE SAMPLE (P 554).
- MEDIAN MID-VALUE OF THE SAMPLE, IF THERE ARE AN ODD NUMBER OF SAMPLE POINTS, OR THE AVERAGE OF THE TWO MIDDLE VALUES FOR AN EVEN NUMBER OF POINTS (P 555).
- TRIMEAN $0.25 * (Q_1 + 2Q_2 + Q_3)$, WHERE THE Q_i ARE THE QUANTILES.
- MIDMEAN THE AVERAGE OF ALL SAMPLE VALUES LYING BETWEEN THE UPPER AND LOWER QUANTILES.
- MIDRANGE AVERAGE OF THE MAXIMUM AND MINIMUM.
- GEOMETRIC MEAN (P 554).
- HARMONIC MEAN (P 555).
- VARIANCE (P 557). UNBIASED ESTIMATORS FOR VARIANCE AND STANDARD DEVIATION ARE USED.
- STANDARD DEVIATION (P 557).

CC

COEFFICIENT OF VARIATION = STANDARD DEVIATION / MEAN
 WHEN THE MEAN IS LESS THAN 10. ** -30, THE COEFFICIENT
 OF VARIATION IS SET TO ZERO.

MEAN (P 556). THE AVERAGE OF THE SUM OF THE ABSOLUTE
 DEVIATION DIFFERENCES BETWEEN THE SAMPLE VALUES AND THE
 MEDIAN

RANGE MAXIMUM - MINIMUM (P 557).

MIDSPREAD $Q_3 - Q_1$, ALSO CALLED INTERQUARTILE DISTANCE.

M3 THIRD CENTRAL MOMENT. UNBIASED ESTIMATOR IS USED.

M4 FOURTH CENTRAL MOMENT. UNBIASED ESTIMATOR IS USED.

COEFFICIENT OF SKEWNESS $M3 / (STD DEV) ** 3$

COEFFICIENT OF KURTOSIS $(M4 / (STD DEV) ** 4) - 3$

BETA1 BIASED ESTIMATE OF THIRD CENTRAL MOMENT. CAN BE USED
 IN TESTING FOR NORMALITY.

BETA2 BIASED ESTIMATE OF FOURTH CENTRAL MOMENT.

MAXIMUM LARGEST SAMPLE VALUE.

MINIMUM SMALLEST SAMPLE VALUE.

QUANTILES THE ALPHA-QUANTILE, $X(\text{ALPHA})$, IS THE SOLUTION TO
 THE EQUATION

$$F_N(Z) = \sum_{I=1}^N W(X_I - Z) / B(N)$$
 PROBABILITY $(X \leq X(\text{ALPHA})) = \text{ALPHA}$.

THE EMPIRICAL DENSITY FUNCTION IS PLOTTED WHEN THE ENTRY POINT
 HISTF IS USED. THE EMPIRICAL DENSITY FUNCTION GIVES ESSENTIALLY
 A "MORE EXACT" PICTURE OF THE DATA THAN DOES THE HISTOGRAM
 ALONE. IT IS DEFINED BY THE RELATION

$$F_N(Z) = \frac{1}{N} \sum_{I=1}^N W(X_I - Z) / B(N)$$

WHERE N IS THE NUMBER OF DATA POINTS, $B(N)$ IS A BANDWIDTH
 FUNCTION,

HS TGI 080
 HS TGI 090
 HS TGI 100
 HS TGI 110
 HS TGI 120
 HS TGI 130
 HS TGI 140
 HS TGI 150
 HS TGI 160
 HS TGI 170
 HS TGI 180
 HS TGI 190
 HS TGI 200
 HS TGI 210
 HS TGI 220
 HS TGI 230
 HS TGI 240
 HS TGI 250
 HS TGI 260
 HS TGI 270
 HS TGI 280
 HS TGI 290
 HS TGI 300
 HS TGI 310
 HS TGI 320
 HS TGI 330
 HS TGI 340
 HS TGI 350
 HS TGI 360
 HS TGI 370
 HS TGI 380
 HS TGI 390
 HS TGI 400
 HS TGI 410
 HS TGI 420
 HS TGI 430
 HS TGI 440
 HS TGI 450
 HS TGI 460
 HS TGI 470
 HS TGI 480
 HS TGI 490
 HS TGI 500
 HS TGI 510
 HS TGI 520
 HS TGI 530
 HS TGI 540
 HS TGI 550

HSTG1560
 HSTG1570
 HSTG1580
 HSTG1590
 HSTG1600
 HSTG1610
 HSTG1620
 HSTG1630
 HSTG1640
 HSTG1650
 HSTG1660
 HSTG1670
 HSTG1680
 HSTG1690
 HSTG1700
 HSTG1710
 HSTG1720
 HSTG1730
 HSTG1740
 HSTG1750
 HSTG1760
 HSTG1770
 HSTG1780
 HSTG1790
 HSTG1800
 HSTG1810
 HSTG1820
 HSTG1830
 HSTG1840
 HSTG1850
 HSTG1860
 HSTG1870
 HSTG1880
 HSTG1890
 HSTG1900
 HSTG1910
 HSTG1920
 HSTG1930
 HSTG1940
 HSTG1950
 HSTG1960
 HSTG1970
 HSTG1980
 HSTG1990
 HSTG2000
 HSTG2010
 HSTG2020
 HSTG2030

$B(N) = \text{RANGE} / \text{SQRT}(N)$,
 AND W IS A WEIGHT FUNCTION,
 $W(Z) = 0$ IF $|Z| > 1$
 $W(Z) = 1 - |Z|$ OTHERWISE.

F (Z) IS COMPUTED FOR VALUES OF Z BETWEEN THE MAXIMUM AND THE
 MINIMUM OF THE SAMPLE AND PLOTTED ON TOP OF THE HISTOGRAM
 USING THE SYMBOL "F". THE RELATIVE FREQUENCY MARKS ON THE
 LEFT OF THE OUTPUT REFER TO THE HISTOGRAM AND NOT TO THE
 DENSITY FUNCTION.

SUBROUTINES REQUIRED

SUBROUTINE PXSORT IS USED TO ORDER THE SAMPLE. PXSORT HAS
 BEEN COMPILED AND ADDED TO MPSSLIB UNDER OS.

TIMING AND CORE REQUIREMENTS

HISTG/HISTF REQUIRE 15,984 DECIMAL BYTES OF CORE. WITH ALL
 THE IBM BUILT-IN FUNCTIONS (IBCOM, SORT, ALOG, ETC.) AND
 SUBROUTINE PXSORT, THE TOTAL REQUIREMENT IS ABOUT 38,500 BYTES.

THE FOLLOWING APPROXIMATE TIME REQUIREMENTS FOR AN IBM/360-67
 WERE OBSERVED:

SAMPLE SIZE (N)	HISTG	HISTF
1000	2.17 SEC	3.97 SEC
500	1.73 SEC	3.40 SEC
200	1.49 SEC	3.04 SEC
100.	1.42 SEC	2.91 SEC

ERROR CONDITIONS

SAMPLE SIZE MUST BE AT LEAST 10; IF NOT, AN ERROR MESSAGE IS
 PRINTED AND NO OUTPUT IS PRODUCED.

THERE MUST BE SOME DIFFERENCES IN THE DATA; IF ALL VALUES OF
 X ARE THE SAME, AN ERROR MESSAGE IS PRINTED.

PROGRAMMER : D.W. ROBINSON

ADAPTED FROM A PREVIOUS VERSION CALLED 'HIST'
 PROVIDED BY IBM AND MODIFIED AT NPS BY

CCCCCCCC

S.D. RANEY 11/72.

DATE : DEC 73
REVISION 1: APR 74

ADDED ADDITIONAL STATISTICS AND CALLED
NEW SORT ROUTINE. PUT IN NOSTAT, FIX AND
NOFIX SECTIONS.

```

SUBROUTINE HISTG (X, N, NBAR)
INTEGER F, ARRAY, BLK, BMARK, PROB, RVERT
REAL MIDMN, MIDSPD, MNDEV, MORNG
LOGICAL*1 PLOT, EM, DOT, VERT, CROSS, BLANK, NUM, FMT, FUNC, EFF
LOGICAL*1 STAT, FX
REAL*8 SUM, SUM2, SUM3, SUM4, SUMH
DIMENSION X(N), XLABEL(33), F(32), PROB(50), NUM(4), FMT(24)
EQUIVALENCE (PLOT(1,1), ARRAY(1))
DATA BLK/, MARK/****/, BMARK/****+/, NOMARK/'---+',
DATA RVERT/,/, FUNC/.TRUE./, STAT/.TRUE./, FX/.FALSE./
DATA NOUT/6/, EM/M', DOT/'', VERT/|', CROSS/'+', BLANK/' '
DATA EFF/0.1/, FMT/4H3210/, FMT/24H(1XF6.2,15(3XF5.2),F6.2)/
THIS STATEMENT WILL PRODUCE A SIZE WARNING:--
DATA NUM/4H3210/, FMT/24H(1XF6.2,15(3XF5.2),F6.2)/

SET FLAG SO EMPIRICAL D.F. IS NOT PLOTTED
FUNC = .FALSE.

ENTRY POINT FOR DENSITY FUNCTION PLOT ROUTINE
ENTRY HISTG (X, N, NBAR)

TEST N
AN = N
IF(N .GE. 10) GO TO 10
WRITE(NOUT,5) N
5 FORMAT('1***HISTG SAMPLE SIZE TOO SMALL:',I11)
FUNC = .TRUE.
RETURN

10 SORT THE SAMPLE
CALL PXSORT(X, 1, N)

GET FREQUENCY INTERVALS FOR BARS AND COUNT NO VALUES IN EACH
SEE WHETHER TO USE AUTO NBARS DETERMINATION
NBARS = NBAR

```

HSTG2040
HSTG2050
HSTG2060
HSTG2070
HSTG2080
HSTG2090
HSTG2100
HSTG2110
HSTG2120
HSTG2130
HSTG2140
HSTG2150
HSTG2160
HSTG2170
HSTG2180
HSTG2190
HSTG2200
HSTG2210
HSTG2220
HSTG2230
HSTG2240
HSTG2250
HSTG2260
HSTG2270
HSTG2280
HSTG2290
HSTG2300
HSTG2310
HSTG2320
HSTG2330
HSTG2340
HSTG2350
HSTG2360
HSTG2370
HSTG2380
HSTG2390
HSTG2400
HSTG2410
HSTG2420
HSTG2430
HSTG2440
HSTG2450
HSTG2460
HSTG2470
HSTG2480
HSTG2490
HSTG2500
HSTG2510


```

IF ( (NBAR .GE. 15) .AND. (NBAR .LE. 32) ) GO TO 20
NBARS = 15
IF(N .GE. 80) NBARS = MINO(32, N/5)
20 MAX = NBARS * 4
   NBPI = NBARS + 1
   NBMI = NBARS - 1
   LIM E = MINO(NBPI, 32)
   RANGE = X(N) - X(1)
   IF(RANGE .GT. 0.0) GO TO 40
   RANGE OF SAMPLE IS .LE. 0; PRINT ERROR MESSAGE
   WRITE(NOUT,30) X(1)
30 FORMAT(.1**HISTG SAMPLE IS CONSTANT. SAMPLE VALUES ARE',1PE16.6)
   GO TO 450
C
40 IF(FX) GO TO 50
   XMIN = X(1)
   HSCALE = RANGE
   DELTA = HSCALE / FLOAT(NBARS)
50 K = 1
   LABEL(1) = XMIN
   DO 80 J=1,NBARS
   F(J) = 0
   TOP = XMIN + J * DELTA
   LABEL(J+1) = TOP
   IF(K .GT. N) GO TO 80
   DO 60 I=K,N
   IF(X(I) .GT. TOP) GO TO 70
   F(J) = F(J) + 1
60 CONTINUE
   I = N + 1
70 K = I
80 CONTINUE
   LE = N) F(NBARS) = F(NBARS) + N - K + 1
   SCALE = FREQUENCIES
90 FMAX = F(1)
   DO 100 I=2,NBARS
   FMAX = AMAX1(FMAX, FLOAT(F(I)))
100 CONTINUE
C
   BLANK PRINT ARRAY
   DO 110 I=1,1600
   ARRAY(I) = BLK
110 CONTINUE
C
   PLOT THE BARS
   LIM = 1536
   FSCALE = 49. / FMAX
   DO 140 I=1,NBARS

```

HSTG22520
 HSTG22530
 HSTG22540
 HSTG22550
 HSTG22560
 HSTG22570
 HSTG22580
 HSTG22590
 HSTG22600
 HSTG22610
 HSTG22620
 HSTG22630
 HSTG22640
 HSTG22650
 HSTG22660
 HSTG22670
 HSTG22680
 HSTG22690
 HSTG22700
 HSTG22710
 HSTG22720
 HSTG22730
 HSTG22740
 HSTG22750
 HSTG22760
 HSTG22770
 HSTG22780
 HSTG22790
 HSTG22800
 HSTG22810
 HSTG22820
 HSTG22830
 HSTG22840
 HSTG22850
 HSTG22860
 HSTG22870
 HSTG22880
 HSTG22890
 HSTG22900
 HSTG22910
 HSTG22920
 HSTG22930
 HSTG22940
 HSTG22950
 HSTG22960
 HSTG22970
 HSTG22980

TG2990
 HSTG3000
 HSTG3010
 HSTG3020
 HSTG3030
 HSTG3040
 HSTG3050
 HSTG3060
 HSTG3070
 HSTG3080
 HSTG3090
 HSTG3100
 HSTG3110
 HSTG3120
 HSTG3130
 HSTG3140
 HSTG3150
 HSTG3160
 HSTG3170
 HSTG3180
 HSTG3190
 HSTG3200
 HSTG3210
 HSTG3220
 HSTG3230
 HSTG3240
 HSTG3250
 HSTG3260
 HSTG3270
 HSTG3280
 HSTG3290
 HSTG3300
 HSTG3310
 HSTG3320
 HSTG3330
 HSTG3340
 HSTG3350
 HSTG3360
 HSTG3370
 HSTG3380
 HSTG3390
 HSTG3400
 HSTG3410
 HSTG3420
 HSTG3430
 HSTG3440
 HSTG3450

```

LIM = LIM + 1
ARRAY(LIM+32) = BMARK
LINE = 50.5 - FSCALE * F(I)
IF (LINE .GE. 50) GO TO 130
LINE = LINE * 32 + I - 32
DO I=20 J = LINE, LIM, 32
  ARRAY(J) = MARK
CONTINUE
GO TO 140
120 IF(F(I) .EQ. 0) ARRAY(LIM+32) = NOMARK
130 CONTINUE
C
C
FIND PROBABILITY MARKERS
PROBMX = FMAX / AN
DO I=1,50
  PROB(I) = 0
CONTINUE
INCR = 5
IF(PROBMX .LT. .20) INCR = 2
IF(PROBMX .LT. .10) INCR = 1
J = INCR
150 J = J / 100.0
IF ( Q .GE. PROBMX) GO TO 170
LINE = (1. - Q / PROBMX) * 49. + 1.5
PROB(LINE) = J
J = J + INCR
GO TO 160
160
C
C
FIND THE MEAN
SUM = 0.0
DO I=1,N
  SUM = SUM + X(I)
CONTINUE
XMEAN = SUM/AN
170
C
C
FIND THE QUANTILE ESTIMATES
IQ1 = N / 4
IQ2 = N / 2
IQ3 = N - IQ1
M2M = 1 - MOD(N,2)
M12 = 1 - MOD(N,4)/2
M12 = 1 + M1
XQ1 = (M1 * X(IQ1) + X(IQ1 + 1)) / M12
XQ2 = (M2M * X(IQ2) + X(IQ2+1)) / (1 + M2M)
XQ3 = (M1 * X(IQ3+1) + X(IQ3)) / M12
XQ10 = X(N/10)
XQ90 = X(9*N/10)
C

```


TG33470
 HSTG33480
 HSTG33490
 HSTG33500
 HSTG33510
 HSTG33520
 HSTG33530
 HSTG33540
 HSTG33550
 HSTG33560
 HSTG33570
 HSTG33580
 HSTG33590
 HSTG33600
 HSTG33610
 HSTG33620
 HSTG33630
 HSTG33640
 HSTG33650
 HSTG33660
 HSTG33670
 HSTG33680
 HSTG33690
 HSTG33700
 HSTG33710
 HSTG33720
 HSTG33730
 HSTG33740
 HSTG33750
 HSTG33760
 HSTG33770
 HSTG33780
 HSTG33790
 HSTG33800
 HSTG33810
 HSTG33820
 HSTG33830
 HSTG33840
 HSTG33850
 HSTG33860
 HSTG33870
 HSTG33880
 HSTG33890
 HSTG33900
 HSTG33910
 HSTG33920
 HSTG33930
 HSTG33940

```

C   PLOT THE MEAN AND THE QUANTILES
R   (MAX-2.0) / HSCALE
I   (XQ1 - XMIN) * R + 1.5
I   (XQ2 - XMIN) * R + 1.5
I   (XQ3 - XMIN) * R + 1.5
C   (XMEAN - XMIN) * R + 1.5
C   MEAN AND QUANTILES PLOT ON GRAPH
C   INSURE = MEAN AND QUANTILES PLOT ON GRAPH
C   IF (MEAN .LT. 1) MEAN = 1
C   IF (IQ1 .LT. 1) IQ1 = 1
C   IF (IQ2 .LT. 1) IQ2 = 1
C   IF (IQ3 .LT. 1) IQ3 = 1
C   IF (IQ1 .GT. MAX) IQ1 = MAX
C   IF (IQ2 .GT. MAX) IQ2 = MAX
C   IF (IQ3 .GT. MAX) IQ3 = MAX
179 DO I=1,50
    PLOT(IQ1,I) = DOT
    PLOT(IQ2,I) = DOT
    PLOT(IQ3,I) = DOT
    PLOT(MEAN,I) = EM
    PLOT(MAX,I) = VERT
C   CONTINUE
C   BYPASS STATISTIC COMPUTATION, IF DESIRED
C   IF (.NOT. STAT) GO TO 198
C   COMPUTE MEAN AND MOMENT ESTIMATES
MDRNG = 0.5 * (X(1) + X(N))
SUM = 0.000
SUM2 = 0.000
SUM3 = 0.000
SUM4 = 0.000
DO I=1,N
  SUM = SUM + ABS(X(I) - XQ2)
  SUM2 = SUM2 + DEV * DEV
  SUM3 = SUM3 + DEV ** 3
  SUM4 = SUM4 + DEV ** 4
C   CONTINUE
VAR = SUM2 / (AN - 1.0)
STDV = SQRT(VAR)
MDEV = SUM / AN
XSUM3 = SNGL(SUM3) * AN / (AN-1.) * (AN-2.)
XSUM4 = XSUM3 / STDV ** 3
BETA1 = SUM3 / AN
XSUM4 = SUM4 * ((AN-2.) * AN + 3.) / ((AN-1.) * (AN-3.))
XSUM4 = XSUM4 - (VAR * VAR) ** 3.
CKUM4 = XSUM4 / AN
BETA2 = SUM4 / AN
  
```


HSTG3950
HSTG3960
HSTG3970
HSTG3980
HSTG3990
HSTG4000
HSTG4010
HSTG4020
HSTG4030
HSTG4040
HSTG4050
HSTG4060
HSTG4070
HSTG4080
HSTG4090
HSTG4100
HSTG4110
HSTG4120
HSTG4130
HSTG4140
HSTG4150
HSTG4160
HSTG4170
HSTG4180
HSTG4190
HSTG4200
HSTG4210
HSTG4220
HSTG4230
HSTG4240
HSTG4250
HSTG4260
HSTG4270
HSTG4280
HSTG4290
HSTG4300
HSTG4310
HSTG4320
HSTG4330
HSTG4340
HSTG4350
HSTG4360
HSTG4370
HSTG4380
HSTG4390
HSTG4400
HSTG4410
HSTG4420

```

C      CVAR = 0.0
      IF (ABS(XMEAN) .GT. 1.E-30) CVAR = STDV / ABS(XMEAN)
      MIDSPD = XQ3 - XQ1
      TRIMN = 0.25 * (XQ1 + XQ2 + XQ3)
      SUM = XQ1 + XQ3
      IQ1 = N/4 + 2
      IQ3 = N - IQ1 + 1
      DO 92 I=IQ1,IQ3
      SUM = SUM + X(I)
      CONTINUE
92     MIDMN = SUM/(IQ3 - IQ1 + 3)
      C
      GET GEOMETRIC AND HARMONIC MEANS, FOR POSITIVE RANDOM VARIABLES
      IF(X(1) .LE. 0.0) GO TO 198
      SUM = 0.0D0
      SUMH = 0.0D0
      DO 195 I=1,N
      SUM = SUM + ALOG(X(I))
      SUMH = SUMH + 1./X(I)
      CONTINUE
195     GEOM = SUM / AN
      GEOM = EXP(GEOM)
      HARM = AN / SUMH
      C
      WRITE THE FREQUENCIES
      WRITE(NOUT,200) N, (F(I), I=1,NBARS)
200    FORMAT('I',5X,'FREQUENCIES',36X,'SAMPLE SIZE =',I5//4X32I4)
      C
      DRAW THE TOP OF THE GRAPH
      WRITE(NOUT,210) BLK, CROSS, (NOMARK,I=1,NBARS)
      WRITE(NOUT,210) BLK, VERT, (BLK,I=1,NBMI), RVERT
210    FORMAT(A4,A1,32A4)
      C
      PLOT THE GRAPH PART
      DO 240 I=1,50
      IF (PROB(I) .EQ. 0) WRITE(NOUT,220) (PLOT(J,I), J=1,MAX)
      FORMAT(4X,'I',128A1)
      IF ( (PROB(I) .GT. 0) .AND.
          * (PROB(I) .LT. 10)) .AND.
225     (PROB(I) .LT. 10)) WRITE(NOUT,225) PROB(I), (PLOT(J,I), J=1,MAX)
          * (PROB(I) .GT. 11,9) .AND.
230     (PROB(I) .GT. 11,9) WRITE(NOUT,230) PROB(I), (PLOT(J,I), J=1,MAX)
          * (PROB(I) .GT. 12,12) .AND.
240     (PROB(I) .GT. 12,128A1)
          * (PROB(I) .GT. 12,128A1)
      CONTINUE
      C
      WRITE OUT THE SCALE ALONG THE BOTTOM
      WRITE(NOUT,250) (RVERT, I=1,NBPI,2)
250    FORMAT(1X,16(A4,4X),A4)

```



```

XS = AMAX1 (ABS(X(1)), ABS(X(N)))
IF ( (XS .LT. .001) .OR. (XS .GE. 1000.) ) GO TO 260
J = ALOG10(XS) + 2.0
IF (J .LE. 0) J = 1
FMT(7) = NUM(J)
FMT(17) = NUM(J)
FMT(23) = NUM(J)
WRITE(NOUT,FMT) (XLABEL(I), I=1,NBPI, 2)
GO TO 290
260 WRITE(NOUT,270) (XLABEL(I), I=1, LIM E, 4)
270 FORMAT(1X,1PE9.2,2X,1,7(3XE9.2,3X,1,1),7X,1)
280 WRITE(NOUT,280) (XLABEL(I), I=3, LIM E, 4)
280 FORMAT(8X,1PE9.2, 7(7X, E9.2))
C
290 IF (FX) WRITE(NOUT,295) XMIN, XMAX
295 FORMAT(//, SCALE FIXED FROM,1PE14.6, TO, E14.6)
C
C BYPASS STATISTICS, IF REQUESTED
IF(.NOT. STAT) GO TO 330
WRITE OUT THE STATISTICS
WRITE(NOUT,300) XMEAN, VAR, XSUM3, X(1), XQ2, STDV, XSUM4, XQ10,
TRIMM, CVAR, SKEW, XQ1, MIDMN, MNDEV, CKURT, XQ2,
MORNG, RANGE, BETA1, XQ3
**
300 FORMAT(///, OCEVTRAL TENDENCY, //
4X, DISTRIBUION: /
, OMEAN, 5X, 1PE14.6, 4X, VARIANCE, E14.6, 4X, M3, 6X, E14.6, 4X,
, MEDIAN, E14.6, 4X, M4, 6X, E14.6,
, TRIMMEAN, E14.6, 4X, COEF VAR, E14.6 /
, 4X, .10 QUANTILE, E14.6, 4X, (HINGE), E14.6 /
, 4X, .25 QUANTILE, E14.6, 4X, MEAN DEV, E14.6, 4X, KURTOSIS,
, MIDMEAN, E14.6, 4X, .50 QUANTILE (MEDIAN), E14.6 /
, MIDRANGE, E14.6, 4X, RANGE, E14.6, 4X, BETA1,
, E14.6, 4X, .75 QUANTILE (HINGE), E14.6)
**
C IF(X(1) .GT. 0.0) WRITE(NOUT,310) GEOM, MIDSPD, BETA2, XQ90,
HARM, X(N)
310 FORMAT( , GEOM MEAN, 1PE14.6, 4X, MIDSPREAD, E14.6, 4X, BETA2,
, E14.6, 4X, .90 QUANTILE, 9X, E14.6 /
, HARM MEAN, E14.6, 57X, MAXIMUM, 14X, E14.6 // )
**
C IF(X(1) .LE. 0.0) WRITE(NOUT,320) MIDSPD, BETA2, XQ90, X(N)
320 FORMAT(28X, MIDSPREAD, 1PE14.6, 4X, BETA2
, .90 QUANTILE, 9X, E14.6 /
, 81X, MAXIMUM, 14X, E14.6 // )
**
C 330 CONTINUE

```


HSTG4910
HSTG4920
HSTG4930
HSTG4940
HSTG4950
HSTG4960
HSTG4970
HSTG4980
HSTG4990
HSTG5000
HSTG5010
HSTG5020
HSTG5030
HSTG5040
HSTG5050
HSTG5060
HSTG5070
HSTG5080
HSTG5090
HSTG5100
HSTG5110
HSTG5120
HSTG5130
HSTG5140
HSTG5150
HSTG5160
HSTG5170
HSTG5180
HSTG5190
HSTG5200
HSTG5210
HSTG5220
HSTG5230
HSTG5240
HSTG5250
HSTG5260
HSTG5270
HSTG5280
HSTG5290
HSTG5300
HSTG5310
HSTG5320
HSTG5330
HSTG5340
HSTG5350
HSTG5360
HSTG5370
HSTG5380

```

IF(.NOT. FUNC) GO TO 450
FUNC = .FALSE.
C
C-----
C  FIND AND PLOT FN (EMPIRICAL DENSITY FUNCTION)
BANDWIDTH = SQRT(AN) / RANGE
BN = BN / AN
C-----
C  EMPIRICAL DENSITY FUNCTION CALCULATION
LOW = 1
FMAX = -10.0
XINC = HSCALE / MAX
MAXM1 = MAX - 1
DO 430 I=1,MAXM1
U = XMIN + I * XINC
FN(I) = 0.0
DO 410 J=LOW,N
TRY = (U - X(J)) * BN
IF(TRY .GT. 1.0) GO TO 400
IF(TRY .LT. -1.0) GO TO 420
WEIGHT = FN(I) + 1.0 - ABS(TRY)
FN(I) = FN(I)
GO TO 410
400 LOW = J
410 CONTINUE
420 FN(I) = FN(I) * XN
430 FMAX = AMAX1(FMAX, FN(I))
C-----
C  PLOT THE DENSITY FUNCTION
DO 440 I=1,MAXM1
LINE = 50.5 - 49.0 * FN(I) / FMAX
PLOT(I, LINE) = EFF
CONTINUE
C-----
C  PRINT THE REVISED HISTOGRAM
GO TO 198
C
C  RESET FUNCTION FLAG AND QUIT
FUNC = .TRUE.
RETURN
C
C  ENTRY NOSTAT
C
C  ENTRY POINT TO SET STATISTIC FLAG TO SUPPRESS
CALCULATION AND PRINTOUT OF STATISTICS
STAT = .FALSE.
RETURN
C
C  ENTRY FIX(SCALE)

```


HSTG5390
HSTG5400
HSTG5410
HSTG5420
HSTG5430
HSTG5440
HSTG5450
HSTG5460
HSTG5470
HSTG5480
HSTG5490
HSTG5500
HSTG5510
HSTG5520

```

C      FX = .TRUE.
      XMIN = AMINI(SCALE(1), SCALE(2))
      XMAX = AMAXI(SCALE(1), SCALE(2))
      HSCALE = XMAX - XMIN
      TEST FOR VALIDITY
      IF (HSCALE .LE. 0.0) FX = .FALSE.
      RETURN
C
      ENTRY NOFIX
      FX = .FALSE.
      RETURN
C
      END

```

SUBROUTINE DISPL

SUBROUTINE DISPL PROVIDES A GEOGRAPHICAL DISPLAY OF THE
BLUE SURFACE UNITS. THE MAXIMUM RANGE SCALE IS 200 NM FROM
FORCE CENTER. A 100 NM CIRCLE IS DRAWN ON THE PLOT.

```

CCOMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SM
1AT(300,10),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NOND(190,40),ISEE
2D,CHANEL(40,4),NADAR(40,19),RXATA(5),LOVER,ITEMS,PLIST(40,6),REASO
3RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFRG,RELOAD(40,4),
4MARY(100),CHECK,IFIRST,NPGS,KWART(4),NSAM,TGTAV(190),TCF(6),IHI(4
560),AMF,HISX(100),JACK(40,7),HISA(100)
DIMENSION CX(1257),YSHIP(40),CSHIP(40),XXSHIP(40),XXSHIP(40)
DO 1 I = 1,NS
  XSHIP(I) = 4.0 + 0.0200*SHIP(I,2)
  YSHIP(I) = 4.0 + 0.0200*SHIP(I,3)
CONTINUE
1 CALL PLOTS
  CALL AXIS(4.0,0.0,1,1,8.0,90.0,-200.0,50.0)
  CALL AXIS(0.0,4.0,1,1,8.0,0.0,-200.0,50.0)
  CALL LINE(XSHIP, YSHIP, NS, 1, -4)
DO 2 I = 1,NS
  XXSHIP(I) = XSHIP(I) + 0.1
XXSHIP(I) = XSHIP(I)
CALL NUMBER(XXSHIP(I),YSHIP(I),0.14,CSHIP(I),0.0,-1)
CONTINUE
2 DO 3 N = 1,1257
  T = FLOAT(N)/100.
  CX(N) = 4.0 + 2.00*SIN(T)
  CY(N) = 4.0 + 2.00*COS(T)

```



```

33 CONTINUE
CALL LINE(CX,CY,1257,1,7),SHIP POSITIONS,0.0,0.14)
CALL SYMBOL(0.0,8.0,0.14),FLI AIR DEF SIM,0.0,0.15)
CALL SYMBOL(0.0,8.0,0.14),NORTH,0.0,0.5)
CALL PLOT(0.0,12.0,-3)
CALL PLOT
RETURN
END

```

SUBROUTINE RAIDIS

SUBROUTINE RAIDIS PROVIDES A GEOGRAPHICAL DISPLAY OF RAIDER TRACKS FROM THEIR INITIAL POSITION (IP) TO LAUNCH POSITION. IN THE CASE WHERE A RAIDER DOES NOT HAVE A LAUNCH POSITION, THE 30 MIN GAME TIME POSITION IS DISPLAYED. IF THE LAUNCH OR 30 MIN POSITION ARE MORE THAN 300 NM FROM THE CENTER, NO TRACK IS DISPLAYED AT THE LOCATION OF THE RAIDER'S IP. 800 NM IS THE MAXIMUM DISTANCE FOR THE PLOT

```

COMMON X(2744),ASMT(100,8),SAMASM(300,7),RAID(90,17),SHIP(40,6),SME
1AT(300,1),IVENTS(1000,2),STATS(40,2),IBAT(40,4),NONO(190,40),ISESO
2D,MAMBAL(40,19),RXATA(5),LDVER,ITEMS,PLIST(40,6),REASO
3N,CHANEL(40,3,6),NASM,JAM(4),TMAX,NRTGT(90),MISLFT(90,2),NR,NS,Q
4RT(50),IFLASK,IGAGE(190),ISAG(40),IFAG,ISBG(40),IFBG,RELOAD(40,4),
5MARY(100),CHECK,IFIRST,NPGS,KMART(4),NSAM,IGTAV(190),TCF(6),IHT(4
6),AMF,HISX(XRAID(2),YRAID(2)),HISA(100)
CALL PLOTS
CALL AXIS(0.0,4.0,1,1,8.0,0.0,-800.0,200.0)
CALL AXIS(4.0,0.0,1,1,8.0,90.0,-800.0,200.0)
DO 30 I=1,NR
LFLAG = 0
CRAID=I
XRAID(1) = 4.0 + 0.00500*RAID(I,3)
YRAID(1) = 4.0 + 0.00500*RAID(I,4)
IF (ABS(RAID(I,7)).GT.800.0.OR.ABS(RAID(I,8)).GT.800.0) GO TO 40
XRAID(2) = 4.0 + 0.00500*RAID(I,1)
YRAID(2) = 4.0 + 0.00500*RAID(I,8)
CONTINUE
CALL LINE(XKRAID,YRAID,2,1,3)
XKRAID = XRAID(1) + 0.05
CALL NUMBER(XXRAID,YRAID(1),0.07,CRAID,0.0,-1)
XXRAID = XXRAID + 0.15
CALL SYMBOL(XXRAID,YRAID(1),0.07,'IP',0.0,2)
XTRAID = XRAID(2) + 0.05
CALL NUMBER (XTRAID,YRAID(2),0.07,CRAID,0.0,-1)

```

20

CCCCCCCC


```

XTRAID = XTRAID + 0.15
IF (LFLAG.EQ.1) GO TO 70
CALL SYMBOL(XTRAID,YRAID(2),0.07,'LAUNCH',0.0,6)
25 CONTINUE
CALL WHERE(XNOW,YNOW)
CALL PLOT(XNOW,YNOW,3)
GO TO 30
40 LFLAG = 1
CALL LOCTIM (1,30.1,XRAID(2),YRAID(2))
IF (ABS(XRAID(2)).GT.800.0.OR.ABS(YRAID(2)).GT.800.0) GO TO 60
XRAID(2) = 4.0 + 0.00500*XRAID(2)
YRAID(2) = 4.0 + 0.00500*YRAID(2)
GO TO 20
CONTINUE
60 CALL SYMBOL (XTRAID,YRAID(1),0.07,CRAID,0.0,-1)
XTRAID = XRAID(1) + 0.05
CALL SYMBOL (XTRAID,YRAID(1),0.07,'ND TRACK',0.0,8)
GO TO 25
CONTINUE
70 CALL SYMBOL (XTRAID,YRAID(2),0.07,'30 MIN',0.0,6)
GO TO 25
CONTINUE
30 CALL SYMBOL(0.5,8.0,0.14,'RAIDER TRACKS',0.0,13)
CALL SYMBOL(0.5,8.5,0.14,'FLT AIR DEF SIM',0.0,15)
CALL SYMBOL(3.7,8.25,0.14,'NORTH',0.0,5)
CALL PLOT(0.0,12.0,-3)
CALL PLOTE
RETURN
END

```

```

SETIMX START (14,12)
SAVE (12,15)
LR USING SETIMX,12
ST 13,TEMP
LA 13,SAVE
STIMER TASK, FIXUP, TUINTVL=TIME
L RETURN (14,12),T
DROP 12
SAVE (14,12)
RETURN (14,12)
ENTRY GETIMX
SAVE (14,12)
LR 12,15
L USING GETIMX,12
L 2,0(1)

```

FIXUP

GETIMX


```

ST 13,TEMP
LA 13,SAVE
TTIMER
L 1,TIME
SR 1,0
ST 1,0(2)
L 13,TEMP
RETURN (14,12),T
DS 18F
DS F
DC X'7FFFFFFFF'
END

```

```

SAVE
TEMP
TIME

```

```

FUNCTION RADIAN (RD)

```

```

C CONVERTS FROM DEGREES TO RADIAN.
C

```

```

IMPLICIT REAL*8(R)
RADIAN = RD*0.017453293
RETURN
END

```

```

RAT 10
RAT 20
RAT 30
RAT 40
RAT 50
RAT 60
RAT 70
RAT 80

```

```

//LINK.SYSPRINT DD SYSOUT=0
//LINK.SYSIN DD *
//GO.FT06FOOT DD SPACE=(CYL,(4,2)),SYSOUT=0
//GO.SYSIN DD *
C JOB COMPLETE

```


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